

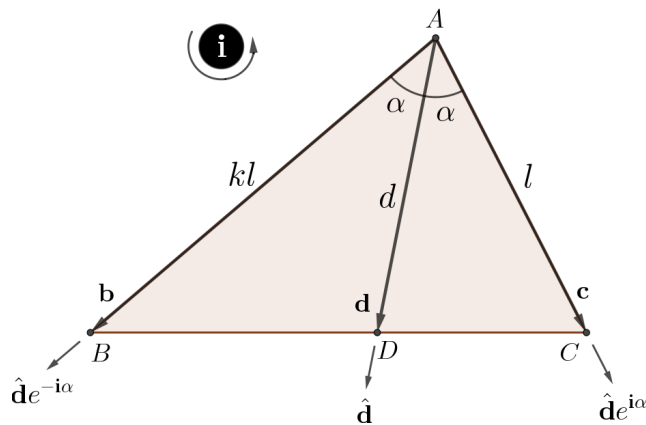
A Geometric Algebra Solution to a Hard Contest Problem

April 23, 2024

James Smith
 LinkedIn group ("Pre-University Geometric Algebra")

Abstract

We show how to use rotations of vectors in GA to solve the following problem: "The following are known about a triangle: The ratio of the lengths of two sides; the angle formed by those sides; and the length of that angle's bisector. Find the length of the side opposite that angle."



Given α , d , and k (but not l), find the length BC .

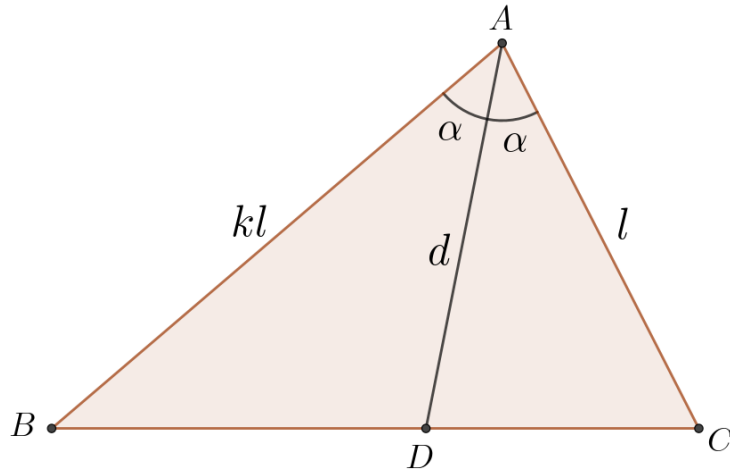


Figure 1: Given α , d , and k (but not l), find the length BC .

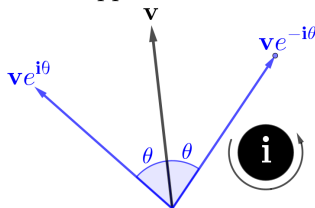
1 Statement of the Problem

The problem that we solve here is a generalization of a contest problem that the YouTube channel “Mind Your Decisions” solved by conventional means at <https://www.youtube.com/watch?v=BeuLmUjPFsk>. We state that generalization as: Given α , d , and k (but not l), find the length BC (Fig. 1).

2 Ideas that We Will Use

1. For any two parallel vectors \mathbf{u} and \mathbf{v} , $\mathbf{u} \wedge \mathbf{v} = 0$.
2. For any two vectors \mathbf{u} and \mathbf{v} , $\mathbf{u} \wedge \mathbf{v} = \langle \mathbf{u}\mathbf{v} \rangle_2$.
3. Ideas concern the rotation of a vector \mathbf{v} that is parallel to a given bivector \mathbf{i} :

- (a) The vectors $\mathbf{v}e^{i\theta}$ and $\mathbf{v}e^{-i\theta}$ are rotations of \mathbf{v} by the same angle θ , but in opposite directions.



- (b) For any angle θ , and any vector \mathbf{v} that is parallel to bivector \mathbf{i} , $\mathbf{v}e^{i\theta} = e^{-i\theta}\mathbf{v}$. Here is a proof:

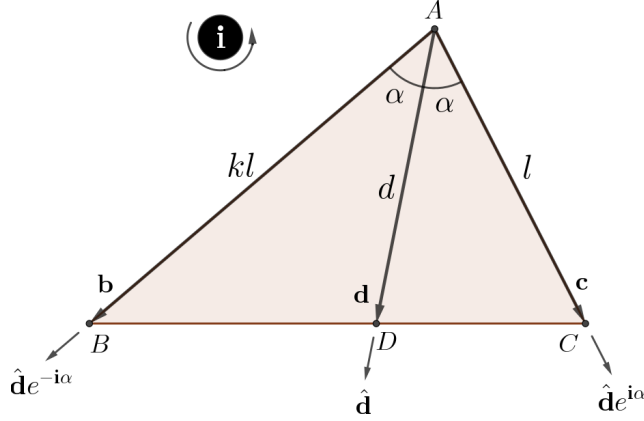


Figure 2: Formulation of the problem in terms of vectors. Note that $\mathbf{b} = kl\hat{\mathbf{d}}e^{-i\alpha}$; $\mathbf{d} = d\hat{\mathbf{d}}$; and $\mathbf{c} = l\hat{\mathbf{d}}e^{i\alpha}$.

$$\begin{aligned}
 \mathbf{v}e^{i\theta} &= \mathbf{v} [\cos \theta + \mathbf{i} \sin \theta] \\
 &= \mathbf{v} \cos \theta + \mathbf{v}\mathbf{i} \sin \theta \\
 &= \mathbf{v} \cos \theta - \mathbf{i}\mathbf{v} \sin \theta \\
 &= [\cos \theta - \mathbf{i} \sin \theta] \mathbf{v} \\
 &= e^{-i\theta} \mathbf{v}.
 \end{aligned}$$

(c) From $\mathbf{v}e^{i\theta} = e^{-i\theta} \mathbf{v}$, we can see that $\mathbf{v}e^{i\theta} \mathbf{v} = v^2 e^{-i\theta}$, and that $\hat{\mathbf{v}}e^{i\theta} \hat{\mathbf{v}} = e^{-i\theta}$.

3 Solution Strategy

We will use rotation of vectors to determine l , then (knowing l) we will use the Law of Cosines to calculate BC .

4 Formulation in Terms of Vectors

We formulate the problem as shown in Fig. 2.

5 Solution

We begin by recognizing that $[\mathbf{c} - \mathbf{d}] \parallel [\mathbf{d} - \mathbf{b}]$. Therefore, $[\mathbf{c} - \mathbf{d}] \wedge [\mathbf{d} - \mathbf{b}] = 0$, and

$$\hat{\mathbf{d}}e^{i\alpha}\hat{\mathbf{d}} = e^{-i\alpha}.$$

$$\langle d^2 \rangle_2 = 0.$$

$$\begin{aligned} \langle [\mathbf{c} - \mathbf{d}] [\mathbf{d} - \mathbf{b}] \rangle_2 &= 0 \\ \langle [l\hat{\mathbf{d}}e^{i\alpha} - d\hat{\mathbf{d}}] [d\hat{\mathbf{d}} - kl\hat{\mathbf{d}}e^{-i\alpha}] \rangle_2 &= 0 \\ \langle ld\hat{\mathbf{d}}e^{i\alpha}\hat{\mathbf{d}} - kl^2\hat{\mathbf{d}}e^{i\alpha}\hat{\mathbf{d}}e^{-i\alpha} - d^2 + kdle^{-i\alpha} \rangle_2 &= 0 \\ \langle lde^{-i\alpha} - kl^2e^{-i\alpha}e^{-i\alpha} + kdle^{-i\alpha} \rangle_2 &= 0 \\ \langle de^{-i\alpha} - kle^{-2i\alpha} + kde^{-i\alpha} \rangle_2 &= 0 \\ -d \sin \alpha + kl \sin 2\alpha - kd \sin \alpha &= 0 \\ \therefore l &= \frac{(k+1)d \sin \alpha}{k \sin 2\alpha}. \end{aligned}$$

Because $\sin 2\alpha = 2 \sin \alpha \cos \alpha$,

$$l = \frac{(k+1)d \sin \alpha}{2k \cos \alpha}.$$

Finally, from the Law of Cosines,

$$\begin{aligned} BC &= \sqrt{AB^2 + AC^2 - 2(AB)(AC) \cos 2\alpha} \\ &= \sqrt{(kl)^2 + l^2 - 2kl^2 \cos 2\alpha} \\ &= l\sqrt{k^2 + 1 - 2k \cos 2\alpha} \\ &= \left[\frac{(k+1)d \sin \alpha}{2k \cos \alpha} \right] \sqrt{(k+1)^2 - 2k(1 + \cos 2\alpha)} \\ &= \left[\frac{(k+1)d \sin \alpha}{2k \cos \alpha} \right] \sqrt{(k+1)^2 - 4k \cos^2 \alpha}. \end{aligned}$$

For any angle θ ,

$$\cos \frac{\theta}{2} = \sqrt{\frac{1 + \cos \theta}{2}}.$$

References

- [1] A. Macdonald, *Linear and Geometric Algebra* (First Edition), CreateSpace Independent Publishing Platform (Lexington, 2012).