

# Properties of a possible unification algebra

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**Abstract.** An algebra providing a possible basis for the standard model is presented. The algebra is generated by combining the trigtaduonion Cayley-Dickson algebra with the complexified space-time Clifford algebra. Subalgebras are assigned to represent multivectors for transverse coordinates. When a requirement for isotropy with respect to spatial coordinates is applied to those subalgebras, the structure generated forms a pattern matching that of the fermions and bosons of the standard model.

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## 1. Introduction

For the Clifford algebra for the dimensionality used in string theories,  $Cl_{1,9}(R)$ , patterns matching the symmetries of the standard model can be found, but it is harder to find a pattern matching the asymmetries of the standard model. This leads to the conjecture that the observed universe is the result of a random choice by nature of one of many possible compactification topologies. A model which generates the features of the observed universe as an inevitable outcome from a relatively simple mathematical structure would be more useful. An algebra with the potential to provide a basis for such a model can be assembled by extending the Clifford algebra of space-time using a Cayley-Dickson algebra.

Cawagas et al[1] analysed the trigtaduonion loop  $T_L$ , finding four isomorphy classes of sedenion-type subloops having asymmetric octonion-type subloop composition. Combining a graded Clifford algebra of the same size, such as  $Cl_{1,4}(R) \cong Cl_4(C) \cong M_4(C)$  with the trigtaduonion algebra  $\mathbb{T}$  generates an algebra with a pattern of subalgebras having a complex combination of symmetry and asymmetry, suggesting that it could be provide a basis for a useful unification model.

In previous papers [2][3] the structure generated by subloops of the loop generated as the product of  $T_L$  with unit elements of  $M_4(C)$  was analysed. In [2]  $M_4(C) \otimes \mathbb{T}$  was labelled  $\mathbb{U}$ . The Cayley tables of unit elements of  $M_4(C)$  and of  $T_L$  can be aligned so that, if the signs of products are ignored, they match each other. A subalgebra of  $\mathbb{U}$ , labelled  $\mathbb{W}$ , having unit elements, each being the product of a unit element of  $M_4(C)$  with the element of  $T_L$  aligned with it, was investigated. In [3] the sedenion-type subloops of  $T_L$ , when required to be “spatially equivalent” were found display a possible correspondence with fundamental particles of the standard model.

In this paper a combination of these approaches is considered. The loop of unit elements of  $M_4(C)$  is labelled  $M_L$ . The loop of unit elements of  $\mathbb{U} \cong M_4(C) \otimes \mathbb{T}$  is designated  $U_L \cong M_L \otimes T_L$ . Elements of  $M_L$  are assigned to represent unit elements for the complexification of the space-time Clifford algebra for positive spatial signature,  $Cl_{3,1}(R) \otimes \mathbb{C} \cong Cl_4(C)$  (using negative spatial signature would generate similar results). For that assignment, subloops of  $U_L$  of the same order as  $M_L$  having elements which are products of “spatially equivalent” alignments of  $T_L$  with  $M_L$  are considered. It is postulated that these subloops correspond to the equivalent of a multivector for transverse complexified space-time coordinates. These subloops can be arranged in sets having the same scalar, transverse spatial bivectors and tranverse pseudovector.

The Loops package[4] for GAP4[5] has been used to investigate isomorphisms and isotopisms for  $T_L$  and its subloops.

## 2. Notation

### 2.1. Notation used for $T_L$

The notation for  $T_L$  for the Cayley table shown in Appendix A is setout in table 1. Cawagas et al[1] labelled the isomorphism types of sedenionic-type subloops of  $T_L$  as  $S_\gamma, S_\alpha, S_\beta, S_L$ . In this paper these have been labelled using uppercase greek letters with numbered subscripts:  $\Gamma_1, A_{1..7}, B_{1..7}, \Sigma_{1..15}$ , as shown in table 2.



## 2.2. Notation used for $M_L$ , the group of unit elements of $M_4(C) \cong Cl_{3,1}(C) \cong Cl(1, 3(C))$

The notation for unit elements of  $M_L$  is setout in table 3, for the unit matrix assignments and Cayley table shown in Appendix A.

TABLE 3. Notation used to label elements for  $M_L$  the group of unit elements of  $M_4(C)$

$e_0$	$e_1$	$e_2$	$e_3$	$e_4$	$e_5$	$e_6$	$e_7$	$e_8$	$e_9$	$e_{10}$	$e_{11}$	$e_{12}$	$e_{13}$	$e_{14}$	$e_{15}$
S	L	M	N	U	X	Y	Z	V	D	E	F	T	P	Q	R
$e_{16}$	$e_{17}$	$e_{18}$	$e_{19}$	$e_{20}$	$e_{21}$	$e_{22}$	$e_{23}$	$e_{24}$	$e_{25}$	$e_{26}$	$e_{27}$	$e_{28}$	$e_{29}$	$e_{30}$	$e_{31}$
iS	iL	iM	iN	iU	iX	iY	iZ	iV	iD	iE	iF	iT	iP	iQ	iR

## 2.3. Notation for elements of $U_L \cong T_L \otimes M_L$ , unit elements of $\mathbb{U}$

All unit elements of  $\mathbb{U}$  are the product of an element of  $T_L$  with an element of  $M_L$ , as listed in table 4.

TABLE 4. Notation used to label elements of  $U_L$ , the loop of unit elements of  $\mathbb{U}$

$\sigma_0 S \sigma_0 L \sigma_0 M \sigma_0 N \sigma_0 T \sigma_0 P \sigma_0 Q \sigma_0 R \sigma_0 U \sigma_0 X \sigma_0 Y \sigma_0 Z \sigma_0 V \sigma_0 D \sigma_0 E \sigma_0 F \sigma_0 iS \sigma_0 iL \sigma_0 iM \sigma_0 iN \sigma_0 iT \sigma_0 iP \sigma_0 iQ \sigma_0 iR \sigma_0 iU \sigma_0 iX \sigma_0 iY \sigma_0 iZ \sigma_0 iV \sigma_0 iD \sigma_0 iE \sigma_0 iF$   
 $\sigma_1 S \sigma_1 L \sigma_1 M \sigma_1 N \sigma_1 T \sigma_1 P \sigma_1 Q \sigma_1 R \sigma_1 U \sigma_1 X \sigma_1 Y \sigma_1 Z \sigma_1 V \sigma_1 D \sigma_1 E \sigma_1 F \sigma_1 iS \sigma_1 iL \sigma_1 iM \sigma_1 iN \sigma_1 iT \sigma_1 iP \sigma_1 iQ \sigma_1 iR \sigma_1 iU \sigma_1 iX \sigma_1 Y \sigma_1 iZ \sigma_1 iV \sigma_1 iD \sigma_1 iE \sigma_1 iF$   
 $\sigma_2 S \sigma_2 L \sigma_2 M \sigma_2 N \sigma_2 T \sigma_2 P \sigma_2 Q \sigma_2 R \sigma_2 U \sigma_2 X \sigma_2 Y \sigma_2 Z \sigma_2 V \sigma_2 D \sigma_2 E \sigma_2 F \sigma_2 iS \sigma_2 iL \sigma_2 iM \sigma_2 iN \sigma_2 iT \sigma_2 iP \sigma_2 iQ \sigma_2 iR \sigma_2 iU \sigma_2 iX \sigma_2 Y \sigma_2 iZ \sigma_2 iV \sigma_2 iD \sigma_2 iE \sigma_2 iF$   
 $\sigma_3 S \sigma_3 L \sigma_3 M \sigma_3 N \sigma_3 T \sigma_3 P \sigma_3 Q \sigma_3 R \sigma_3 U \sigma_3 X \sigma_3 Y \sigma_3 Z \sigma_3 V \sigma_3 D \sigma_3 E \sigma_3 F \sigma_3 iS \sigma_3 iL \sigma_3 iM \sigma_3 iN \sigma_3 iT \sigma_3 iP \sigma_3 iQ \sigma_3 iR \sigma_3 iU \sigma_3 iX \sigma_3 Y \sigma_3 iZ \sigma_3 iV \sigma_3 iD \sigma_3 iE \sigma_3 iF$   
 $\sigma_4 S \sigma_4 L \sigma_4 M \sigma_4 N \sigma_4 T \sigma_4 P \sigma_4 Q \sigma_4 R \sigma_4 U \sigma_4 X \sigma_4 Y \sigma_4 Z \sigma_4 V \sigma_4 D \sigma_4 E \sigma_4 F \sigma_4 iS \sigma_4 iL \sigma_4 iM \sigma_4 iN \sigma_4 iT \sigma_4 iP \sigma_4 iQ \sigma_4 iR \sigma_4 iU \sigma_4 iX \sigma_4 Y \sigma_4 iZ \sigma_4 iV \sigma_4 iD \sigma_4 iE \sigma_4 iF$   
 $\lambda_0 S \lambda_0 L \lambda_0 M \lambda_0 N \lambda_0 T \lambda_0 P \lambda_0 Q \lambda_0 R \lambda_0 U \lambda_0 X \lambda_0 Y \lambda_0 Z \lambda_0 V \lambda_0 D \lambda_0 E \lambda_0 F \lambda_0 iS \lambda_0 iL \lambda_0 iM \lambda_0 iN \lambda_0 iT \lambda_0 iP \lambda_0 iQ \lambda_0 iR \lambda_0 iU \lambda_0 iX \lambda_0 Y \lambda_0 iZ \lambda_0 iV \lambda_0 iD \lambda_0 iE \lambda_0 iF$   
 $\lambda_1 S \lambda_1 L \lambda_1 M \lambda_1 N \lambda_1 T \lambda_1 P \lambda_1 Q \lambda_1 R \lambda_1 U \lambda_1 X \lambda_1 Y \lambda_1 Z \lambda_1 V \lambda_1 D \lambda_1 E \lambda_1 F \lambda_1 iS \lambda_1 iL \lambda_1 iM \lambda_1 iN \lambda_1 iT \lambda_1 iP \lambda_1 iQ \lambda_1 iR \lambda_1 iU \lambda_1 iX \lambda_1 Y \lambda_1 iZ \lambda_1 iV \lambda_1 iD \lambda_1 iE \lambda_1 iF$   
 $\lambda_2 S \lambda_2 L \lambda_2 M \lambda_2 N \lambda_2 T \lambda_2 P \lambda_2 Q \lambda_2 R \lambda_2 U \lambda_2 X \lambda_2 Y \lambda_2 Z \lambda_2 V \lambda_2 D \lambda_2 E \lambda_2 F \lambda_2 iS \lambda_2 iL \lambda_2 iM \lambda_2 iN \lambda_2 iT \lambda_2 iP \lambda_2 iQ \lambda_2 iR \lambda_2 iU \lambda_2 iX \lambda_2 Y \lambda_2 iZ \lambda_2 iV \lambda_2 iD \lambda_2 iE \lambda_2 iF$   
 $\lambda_3 S \lambda_3 L \lambda_3 M \lambda_3 N \lambda_3 T \lambda_3 P \lambda_3 Q \lambda_3 R \lambda_3 U \lambda_3 X \lambda_3 Y \lambda_3 Z \lambda_3 V \lambda_3 D \lambda_3 E \lambda_3 F \lambda_3 iS \lambda_3 iL \lambda_3 iM \lambda_3 iN \lambda_3 iT \lambda_3 iP \lambda_3 iQ \lambda_3 iR \lambda_3 iU \lambda_3 iX \lambda_3 Y \lambda_3 iZ \lambda_3 iV \lambda_3 iD \lambda_3 iE \lambda_3 iF$   
 $\mu_0 S \mu_0 L \mu_0 M \mu_0 N \mu_0 T \mu_0 P \mu_0 Q \mu_0 R \mu_0 U \mu_0 X \mu_0 Y \mu_0 Z \mu_0 V \mu_0 D \mu_0 E \mu_0 F \mu_0 iS \mu_0 iL \mu_0 iM \mu_0 iN \mu_0 iT \mu_0 iP \mu_0 iQ \mu_0 iR \mu_0 iU \mu_0 iX \mu_0 Y \mu_0 iZ \mu_0 iV \mu_0 iD \mu_0 iE \mu_0 iF$   
 $\mu_1 S \mu_1 L \mu_1 M \mu_1 N \mu_1 T \mu_1 P \mu_1 Q \mu_1 R \mu_1 U \mu_1 X \mu_1 Y \mu_1 Z \mu_1 V \mu_1 D \mu_1 E \mu_1 F \mu_1 iS \mu_1 iL \mu_1 iM \mu_1 iN \mu_1 iT \mu_1 iP \mu_1 iQ \mu_1 iR \mu_1 iU \mu_1 iX \mu_1 Y \mu_1 iZ \mu_1 iV \mu_1 iD \mu_1 iE \mu_1 iF$   
 $\mu_2 S \mu_2 L \mu_2 M \mu_2 N \mu_2 T \mu_2 P \mu_2 Q \mu_2 R \mu_2 U \mu_2 X \mu_2 Y \mu_2 Z \mu_2 V \mu_2 D \mu_2 E \mu_2 F \mu_2 iS \mu_2 iL \mu_2 iM \mu_2 iN \mu_2 iT \mu_2 iP \mu_2 iQ \mu_2 iR \mu_2 iU \mu_2 iX \mu_2 Y \mu_2 iZ \mu_2 iV \mu_2 iD \mu_2 iE \mu_2 iF$   
 $\mu_3 S \mu_3 L \mu_3 M \mu_3 N \mu_3 T \mu_3 P \mu_3 Q \mu_3 R \mu_3 U \mu_3 X \mu_3 Y \mu_3 Z \mu_3 V \mu_3 D \mu_3 E \mu_3 F \mu_3 iS \mu_3 iL \mu_3 iM \mu_3 iN \mu_3 iT \mu_3 iP \mu_3 iQ \mu_3 iR \mu_3 iU \mu_3 iX \mu_3 Y \mu_3 iZ \mu_3 iV \mu_3 iD \mu_3 iE \mu_3 iF$   
 $\mu_4 S \mu_4 L \mu_4 M \mu_4 N \mu_4 T \mu_4 P \mu_4 Q \mu_4 R \mu_4 U \mu_4 X \mu_4 Y \mu_4 Z \mu_4 V \mu_4 D \mu_4 E \mu_4 F \mu_4 iS \mu_4 iL \mu_4 iM \mu_4 iN \mu_4 iT \mu_4 iP \mu_4 iQ \mu_4 iR \mu_4 iU \mu_4 iX \mu_4 Y \mu_4 iZ \mu_4 iV \mu_4 iD \mu_4 iE \mu_4 iF$   
 $\alpha_0 S \alpha_0 L \alpha_0 M \alpha_0 N \alpha_0 T \alpha_0 P \alpha_0 Q \alpha_0 R \alpha_0 U \alpha_0 X \alpha_0 Y \alpha_0 Z \alpha_0 V \alpha_0 D \alpha_0 E \alpha_0 F \alpha_0 iS \alpha_0 iL \alpha_0 iM \alpha_0 iN \alpha_0 iT \alpha_0 iP \alpha_0 iQ \alpha_0 iR \alpha_0 iU \alpha_0 iX \alpha_0 Y \alpha_0 iZ \alpha_0 iV \alpha_0 iD \alpha_0 iE \alpha_0 iF$   
 $\alpha_1 S \alpha_1 L \alpha_1 M \alpha_1 N \alpha_1 T \alpha_1 P \alpha_1 Q \alpha_1 R \alpha_1 U \alpha_1 X \alpha_1 Y \alpha_1 Z \alpha_1 V \alpha_1 D \alpha_1 E \alpha_1 F \alpha_1 iS \alpha_1 iL \alpha_1 iM \alpha_1 iN \alpha_1 iT \alpha_1 iP \alpha_1 iQ \alpha_1 iR \alpha_1 iU \alpha_1 iX \alpha_1 Y \alpha_1 iZ \alpha_1 iV \alpha_1 iD \alpha_1 iE \alpha_1 iF$   
 $\alpha_2 S \alpha_2 L \alpha_2 M \alpha_2 N \alpha_2 T \alpha_2 P \alpha_2 Q \alpha_2 R \alpha_2 U \alpha_2 X \alpha_2 Y \alpha_2 Z \alpha_2 V \alpha_2 D \alpha_2 E \alpha_2 F \alpha_2 iS \alpha_2 iL \alpha_2 iM \alpha_2 iN \alpha_2 iT \alpha_2 iP \alpha_2 iQ \alpha_2 iR \alpha_2 iU \alpha_2 iX \alpha_2 Y \alpha_2 iZ \alpha_2 iV \alpha_2 iD \alpha_2 iE \alpha_2 iF$   
 $\alpha_3 S \alpha_3 L \alpha_3 M \alpha_3 N \alpha_3 T \alpha_3 P \alpha_3 Q \alpha_3 R \alpha_3 U \alpha_3 X \alpha_3 Y \alpha_3 Z \alpha_3 V \alpha_3 D \alpha_3 E \alpha_3 F \alpha_3 iS \alpha_3 iL \alpha_3 iM \alpha_3 iN \alpha_3 iT \alpha_3 iP \alpha_3 iQ \alpha_3 iR \alpha_3 iU \alpha_3 iX \alpha_3 Y \alpha_3 iZ \alpha_3 iV \alpha_3 iD \alpha_3 iE \alpha_3 iF$   
 $\alpha_4 S \alpha_4 L \alpha_4 M \alpha_4 N \alpha_4 T \alpha_4 P \alpha_4 Q \alpha_4 R \alpha_4 U \alpha_4 X \alpha_4 Y \alpha_4 Z \alpha_4 V \alpha_4 D \alpha_4 E \alpha_4 F \alpha_4 iS \alpha_4 iL \alpha_4 iM \alpha_4 iN \alpha_4 iT \alpha_4 iP \alpha_4 iQ \alpha_4 iR \alpha_4 iU \alpha_4 iX \alpha_4 Y \alpha_4 iZ \alpha_4 iV \alpha_4 iD \alpha_4 iE \alpha_4 iF$   
 $\beta_0 S \beta_0 L \beta_0 M \beta_0 N \beta_0 T \beta_0 P \beta_0 Q \beta_0 R \beta_0 U \beta_0 X \beta_0 Y \beta_0 Z \beta_0 V \beta_0 D \beta_0 E \beta_0 F \beta_0 iS \beta_0 iL \beta_0 iM \beta_0 iN \beta_0 iT \beta_0 iP \beta_0 iQ \beta_0 iR \beta_0 iU \beta_0 iX \beta_0 Y \beta_0 iZ \beta_0 iV \beta_0 iD \beta_0 iE \beta_0 iF$   
 $\beta_1 S \beta_1 L \beta_1 M \beta_1 N \beta_1 T \beta_1 P \beta_1 Q \beta_1 R \beta_1 U \beta_1 X \beta_1 Y \beta_1 Z \beta_1 V \beta_1 D \beta_1 E \beta_1 F \beta_1 iS \beta_1 iL \beta_1 iM \beta_1 iN \beta_1 iT \beta_1 iP \beta_1 iQ \beta_1 iR \beta_1 iU \beta_1 iX \beta_1 Y \beta_1 iZ \beta_1 iV \beta_1 iD \beta_1 iE \beta_1 iF$   
 $\beta_2 S \beta_2 L \beta_2 M \beta_2 N \beta_2 T \beta_2 P \beta_2 Q \beta_2 R \beta_2 U \beta_2 X \beta_2 Y \beta_2 Z \beta_2 V \beta_2 D \beta_2 E \beta_2 F \beta_2 iS \beta_2 iL \beta_2 iM \beta_2 iN \beta_2 iT \beta_2 iP \beta_2 iQ \beta_2 iR \beta_2 iU \beta_2 iX \beta_2 Y \beta_2 iZ \beta_2 iV \beta_2 iD \beta_2 iE \beta_2 iF$   
 $\beta_3 S \beta_3 L \beta_3 M \beta_3 N \beta_3 T \beta_3 P \beta_3 Q \beta_3 R \beta_3 U \beta_3 X \beta_3 Y \beta_3 Z \beta_3 V \beta_3 D \beta_3 E \beta_3 F \beta_3 iS \beta_3 iL \beta_3 iM \beta_3 iN \beta_3 iT \beta_3 iP \beta_3 iQ \beta_3 iR \beta_3 iU \beta_3 iX \beta_3 Y \beta_3 iZ \beta_3 iV \beta_3 iD \beta_3 iE \beta_3 iF$   
 $\beta_4 S \beta_4 L \beta_4 M \beta_4 N \beta_4 T \beta_4 P \beta_4 Q \beta_4 R \beta_4 U \beta_4 X \beta_4 Y \beta_4 Z \beta_4 V \beta_4 D \beta_4 E \beta_4 F \beta_4 iS \beta_4 iL \beta_4 iM \beta_4 iN \beta_4 iT \beta_4 iP \beta_4 iQ \beta_4 iR \beta_4 iU \beta_4 iX \beta_4 Y \beta_4 iZ \beta_4 iV \beta_4 iD \beta_4 iE \beta_4 iF$   
 $\gamma_0 S \gamma_0 L \gamma_0 M \gamma_0 N \gamma_0 T \gamma_0 P \gamma_0 Q \gamma_0 R \gamma_0 U \gamma_0 X \gamma_0 Y \gamma_0 Z \gamma_0 V \gamma_0 D \gamma_0 E \gamma_0 F \gamma_0 iS \gamma_0 iL \gamma_0 iM \gamma_0 iN \gamma_0 iT \gamma_0 iP \gamma_0 iQ \gamma_0 iR \gamma_0 iU \gamma_0 iX \gamma_0 Y \gamma_0 iZ \gamma_0 iV \gamma_0 iD \gamma_0 iE \gamma_0 iF$   
 $\gamma_1 S \gamma_1 L \gamma_1 M \gamma_1 N \gamma_1 T \gamma_1 P \gamma_1 Q \gamma_1 R \gamma_1 U \gamma_1 X \gamma_1 Y \gamma_1 Z \gamma_1 V \gamma_1 D \gamma_1 E \gamma_1 F \gamma_1 iS \gamma_1 iL \gamma_1 iM \gamma_1 iN \gamma_1 iT \gamma_1 iP \gamma_1 iQ \gamma_1 iR \gamma_1 iU \gamma_1 iX \gamma_1 Y \gamma_1 iZ \gamma_1 iV \gamma_1 iD \gamma_1 iE \gamma_1 iF$   
 $\gamma_2 S \gamma_2 L \gamma_2 M \gamma_2 N \gamma_2 T \gamma_2 P \gamma_2 Q \gamma_2 R \gamma_2 U \gamma_2 X \gamma_2 Y \gamma_2 Z \gamma_2 V \gamma_2 D \gamma_2 E \gamma_2 F \gamma_2 iS \gamma_2 iL \gamma_2 iM \gamma_2 iN \gamma_2 iT \gamma_2 iP \gamma_2 iQ \gamma_2 iR \gamma_2 iU \gamma_2 iX \gamma_2 Y \gamma_2 iZ \gamma_2 iV \gamma_2 iD \gamma_2 iE \gamma_2 iF$   
 $\gamma_3 S \gamma_3 L \gamma_3 M \gamma_3 N \gamma_3 T \gamma_3 P \gamma_3 Q \gamma_3 R \gamma_3 U \gamma_3 X \gamma_3 Y \gamma_3 Z \gamma_3 V \gamma_3 D \gamma_3 E \gamma_3 F \gamma_3 iS \gamma_3 iL \gamma_3 iM \gamma_3 iN \gamma_3 iT \gamma_3 iP \gamma_3 iQ \gamma_3 iR \gamma_3 iU \gamma_3 iX \gamma_3 Y \gamma_3 iZ \gamma_3 iV \gamma_3 iD \gamma_3 iE \gamma_3 iF$   
 $\gamma_4 S \gamma_4 L \gamma_4 M \gamma_4 N \gamma_4 T \gamma_4 P \gamma_4 Q \gamma_4 R \gamma_4 U \gamma_4 X \gamma_4 Y \gamma_4 Z \gamma_4 V \gamma_4 D \gamma_4 E \gamma_4 F \gamma_4 iS \gamma_4 iL \gamma_4 iM \gamma_4 iN \gamma_4 iT \gamma_4 iP \gamma_4 iQ \gamma_4 iR \gamma_4 iU \gamma_4 iX \gamma_4 Y \gamma_4 iZ \gamma_4 iV \gamma_4 iD \gamma_4 iE \gamma_4 iF$   
 $\delta_0 S \delta_0 L \delta_0 M \delta_0 N \delta_0 T \delta_0 P \delta_0 Q \delta_0 R \delta_0 U \delta_0 X \delta_0 Y \delta_0 Z \delta_0 V \delta_0 D \delta_0 E \delta_0 F \delta_0 iS \delta_0 iL \delta_0 iM \delta_0 iN \delta_0 iT \delta_0 iP \delta_0 iQ \delta_0 iR \delta_0 iU \delta_0 iX \delta_0 Y \delta_0 iZ \delta_0 iV \delta_0 iD \delta_0 iE \delta_0 iF$   
 $\delta_1 S \delta_1 L \delta_1 M \delta_1 N \delta_1 T \delta_1 P \delta_1 Q \delta_1 R \delta_1 U \delta_1 X \delta_1 Y \delta_1 Z \delta_1 V \delta_1 D \delta_1 E \delta_1 F \delta_1 iS \delta_1 iL \delta_1 iM \delta_1 iN \delta_1 iT \delta_1 iP \delta_1 iQ \delta_1 iR \delta_1 iU \delta_1 iX \delta_1 Y \delta_1 iZ \delta_1 iV \delta_1 iD \delta_1 iE \delta_1 iF$   
 $\delta_2 S \delta_2 L \delta_2 M \delta_2 N \delta_2 T \delta_2 P \delta_2 Q \delta_2 R \delta_2 U \delta_2 X \delta_2 Y \delta_2 Z \delta_2 V \delta_2 D \delta_2 E \delta_2 F \delta_2 iS \delta_2 iL \delta_2 iM \delta_2 iN \delta_2 iT \delta_2 iP \delta_2 iQ \delta_2 iR \delta_2 iU \delta_2 iX \delta_2 Y \delta_2 iZ \delta_2 iV \delta_2 iD \delta_2 iE \delta_2 iF$   
 $\delta_3 S \delta_3 L \delta_3 M \delta_3 N \delta_3 T \delta_3 P \delta_3 Q \delta_3 R \delta_3 U \delta_3 X \delta_3 Y \delta_3 Z \delta_3 V \delta_3 D \delta_3 E \delta_3 F \delta_3 iS \delta_3 iL \delta_3 iM \delta_3 iN \delta_3 iT \delta_3 iP \delta_3 iQ \delta_3 iR \delta_3 iU \delta_3 iX \delta_3 Y \delta_3 iZ \delta_3 iV \delta_3 iD \delta_3 iE \delta_3 iF$   
 $\delta_4 S \delta_4 L \delta_4 M \delta_4 N \delta_4 T \delta_4 P \delta_4 Q \delta_4 R \delta_4 U \delta_4 X \delta_4 Y \delta_4 Z \delta_4 V \delta_4 D \delta_4 E \delta_4 F \delta_4 iS \delta_4 iL \delta_4 iM \delta_4 iN \delta_4 iT \delta_4 iP \delta_4 iQ \delta_4 iR \delta_4 iU \delta_4 iX \delta_4 Y \delta_4 iZ \delta_4 iV \delta_4 iD \delta_4 iE \delta_4 iF$

**2.4. Grading of elements of  $M_L$  when used to represent unit multivector elements of  $Cl_{3,1}(R)$**

Elements of  $M_L$  can be assigned to represent unit multivector elements for  $Cl_{3,1}(R)$  as follows:

- Unit Scalar: S
- Unit spatial vectors: X, Y, Z
- Unit temporal vector: T
- Spatial bivectors: L,M,N
- Space/time bivectors: D,E,F
- Spatial trivector: U
- Space/time trivectors: P,Q,R
- Pseudoscalar: V

**3. Electroweak sector**

$T_L$  subloops with have identical participation for elements subscripted  $\iota, j$  and  $\kappa$  are shown in table 5.

TABLE 5. Unit elements for spatially equivalent sedenion-type subloops

	$\sigma_o$	$\sigma_\iota$	$\sigma_j$	$\sigma_\kappa$	$\lambda_o$	$\lambda_\iota$	$\lambda_j$	$\lambda_\kappa$	$\mu_o$	$\mu_\iota$	$\mu_j$	$\mu_\kappa$	$\nu_o$	$\nu_\iota$	$\nu_j$	$\nu_\kappa$	$\alpha_o$	$\alpha_\iota$	$\alpha_j$	$\alpha_\kappa$	$\beta_o$	$\beta_\iota$	$\beta_j$	$\beta_\kappa$	$\gamma_o$	$\gamma_\iota$	$\gamma_j$	$\gamma_\kappa$	$\delta_o$	$\delta_\iota$	$\delta_j$	$\delta_\kappa$				
$\Gamma_0$	■	■	■	■	■	■	■	■																					■	■	■	■	■	■	■	■
$A_0$	■	■	■	■					■	■	■	■									■	■	■	■									■	■	■	■
$B_0$	■	■	■	■									■	■	■	■					■	■	■	■	■	■	■	■								
$\Sigma_0$	■	■	■	■	■	■	■	■	■	■	■	■	■	■	■	■																				
$\Sigma_1$	■	■	■	■	■	■	■	■									■	■	■	■	■	■	■	■												
$\Sigma_2$	■	■	■	■					■	■	■	■					■	■	■	■					■	■	■	■								
$\Sigma_3$	■	■	■	■									■	■	■	■	■	■	■	■									■	■	■	■				

If elements subscripted  $\iota, j$  and  $\kappa$  are excluded, the automorphism group for the unit imaginary octonions that remain,  $[\lambda_o, \mu_o, \nu_o, \alpha_o, \beta_o, \gamma_o, \delta_o]$ , is G2. Including the  $\iota, j$  and  $\kappa$  elements breaks that symmetry, but some symmetry remains.  $\Sigma_1, \Sigma_2$  and  $\Sigma_3$  are related by a quaternionic symmetry, so the automorphism group for their complexification can be  $SU(2) \otimes U(1)$ .

Most unification models using the octonions[6] [7] [8] [9] [10] [11] [12] [13] [14] [15] [16] [17] [18] [19] [20] [21] [22] [23] [24] [25] [26] include quarks and gluons. However, G2 has been used in modelling the electroweak/lepton sector alone by Carone and Rastogi[27] [28], extending the SU(3) model for electroweak unification proposed by Dimopoulos and Kaplan[29].

As noted in [3], the  $\alpha_o$  element of  $T_L$  and the unit imaginary of  $M_L$  have unique status. This suggests identifying them with unit imaginary elements of a complex doublet for the Brout-Englert-Higgs mechanism[30][31][32].  $\Sigma_1, \Sigma_2$  and  $\Sigma_3$  include  $\alpha_o, \alpha_\iota, \alpha_j, \alpha_\kappa$ , whereas  $\Sigma_0$  does not. This suggests assignment of  $\Sigma_1, \Sigma_2$  and  $\Sigma_3$  to electroweak vector bosons that gain mass by the Brout-Englert-Higgs mechanism, and  $\Sigma_0$  to a vector boson that remains massless.

Having  $\Sigma_0, \Sigma_1, \Sigma_2$  and  $\Sigma_3$  assigned to electroweak vector bosons leaves  $A_0, B_0$  and  $\Gamma_0$  available to be assigned to electroweak fermions. This suggests assignment of one of these subloops to generate three generations of one chirality of the neutrino family, and the other two subloops to generate three generations of two chiralities of electron/muon/tau family.

## 4. Fermions

### 4.1. Basis for the Dirac equation

In [3] spatially equivalent assignment of elements of  $T_L$  were identified as ones for which the subloop  $[\sigma_o\sigma_\iota\sigma_j\sigma_\kappa]$  of  $T_L$  is aligned with the subloop  $[SLMN]$  of  $M_L$ . In this paper this concept is extended by postulating that spatially equivalent application of elements of  $T_L$  to unit multivector elements of the space-time Clifford algebra generates an algebra,  $\mathbb{U}$  with subalgebras which can be used to represent graded multivector-type subalgebras for “unphysical” transverse coordinates for excitations of quantum fields.

For the complexified sedenionic-type subloop labelled  $\Gamma_0$ , a possible spatially equivalent alignment generates the loop of unit transverse multivector elements shown in table 6.

TABLE 6. Transverse multivector elements for a spatially equivalent  $\Gamma_0$  alignment

$e_0$	$e_1$	$e_2$	$e_3$	$e_4$	$e_5$	$e_6$	$e_7$	$e_8$	$e_9$	$e_{10}$	$e_{11}$	$e_{12}$	$e_{13}$	$e_{14}$	$e_{15}$	$e_{16}$ to $e_{31}$
$\sigma_o S$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\lambda_o U$	$\lambda_\iota X$	$\lambda_j Y$	$\lambda_\kappa Z$	$\gamma_o V$	$\gamma_\iota D$	$\gamma_j E$	$\gamma_\kappa F$	$\delta_o T$	$\delta_\iota P$	$\delta_j Q$	$\delta_\kappa R$	$i \times [e_1 \text{ to } e_{15}]$

If elements  $[e_1..e_{15}]$  are graded according to the grading of their  $M_L$  components when  $M_4(C)$  is assigned to represent the complexified space-time Clifford algebra, the result shown in Table 7.

TABLE 7. Grading for transverse multivector unit elements for a  $\Gamma_0$  alignment

scalar	vector				bivector						trivector			pseudo scalar	
	spatial			t	spatial			spatio-t			spatio-t		xyz		
$\sigma_o S$	$\lambda_\iota X$	$\lambda_j Y$	$\lambda_\kappa Z$	$\delta_o T$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\gamma_\iota D$	$\gamma_j E$	$\gamma_\kappa F$	$\delta_\iota P$	$\delta_j Q$	$\delta_\kappa R$	$\lambda_o U$	$\gamma_o V$

The even multivector components in table 7 could also be generated by imaginary counterparts of the vector elements as shown in Table 8.

TABLE 8. Grading for alternative spatially equivalent transverse multivector unit elements

scalar	vector				bivector						trivector			pseudo scalar	
	spatial			t	spatial			spatio-t			spatio-t		xyz		
$\sigma_o S$	$\lambda_\iota i X$	$\lambda_j i Y$	$\lambda_\kappa i Z$	$\delta_o i T$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\gamma_\iota D$	$\gamma_j E$	$\gamma_\kappa F$	$\delta_\iota i P$	$\delta_j i Q$	$\delta_\kappa i R$	$\lambda_o i U$	$\gamma_o V$

This suggests assembly of a version of the Dirac equation for this alignment using  $\lambda_\iota, \lambda_j, \lambda_\kappa, \delta_o$  instead of the gamma matrices. This assembly can be labelled  $\Gamma_{0\gamma}^{\lambda\delta}$ , with the subscript indicating the  $T_L$  element applied to the pseudoscalar, the first superscript indicating the  $T_L$  elements applied to the spatial vectors and the second superscript indicating the  $T_L$  element applied to the time-like vector.

For the space-time Clifford algebra multivector, Hestenes [?] uses the unit pseudoscalar as a substitute for the unit imaginary, generating a version of the Dirac equation for one handed of a fermion. Comparing this with  $[\sigma_o S, \sigma_\iota L, \sigma_j M, \sigma_\kappa N, \gamma_\iota D, \gamma_j E, \gamma_\kappa F, \gamma_o V]$ , for all elements except the scalar there is a reversal of signature and commutation/anticommutation properties, and Lie brackets are interchanged with Jordan brackets. This means that the equivalent of the pseudoscalar,  $[\gamma_o V]$ , anticommutes with the bivector elements and squares to the positive scalar. an alternative way to assemble spinors could be to use odd multivector components, as  $[\lambda_\iota X, \lambda_j Y, \lambda_\kappa Z, \delta_o T] \times \gamma_o V = [\delta_\iota P, \delta_j Q, \delta_\kappa R, \lambda_o U]$ . This suggests that similar equations to those obtained by Hestenes can be generated from each of  $\Gamma_{0\gamma}, \Gamma_{0\delta}, \Gamma_{0\lambda}$ , corresponding different flavors for one chirality for type of fermion.

#### 4.2. Three generations for families of fermions

For combined  $T_L \otimes M_L$  subloops, rotations and reflections with respect to unit vectors of  $Cl_{3,1}(R)$  correspond to permutations of  $\iota \rightarrow j \rightarrow \kappa$  subscripts. Permuting  $\lambda_{o\iota j\kappa} \rightarrow \gamma_{o\iota j\kappa} \rightarrow \delta_{o\iota j\kappa}$  reorientates subloops with respect to grading, but not with respect to spatial orientation.

For the spatially equivalent transverse multivector subloops based on each of the  $\Gamma_0$ ,  $A_0$  and  $B_0$  subloops of  $T_L$ , ignoring rotations and reflections, there are 6 possible spatially equivalent orientations. They can be grouped in sets which share the same even multivector components, as shown in tables 9 and 10.

The families of fermions are:

1 chirality for the neutrino family

2 chiralities for the electron/muon/tau family

2 chiralities x 3 colors for the up/charm/top quark family

2 chiralities x 3 colors for the down/strange/bottom quark family

As noted in [3], this, together with the observation that sets of three subloops can, as a combination, display spatial equivalence, suggests assignment of subloops to families of fermions as follows:

$\Gamma_0$  to 1 chirality for the neutrino family

$A_0$  to one chirality and  $B_0$  to a second chirality for the electron/muon/tau family

$A_{1-6}$  to one chirality with 3 colors two families of quarks

$B_{1-6}$  to a second chirality with 3 colors for two families of quarks

Distinct representations for different generations within these families can be found when these  $T_L$  subloops are combined with  $M_L$  subloops in different spatially equivalent alignments and are to represent a type of multivector for transverse coordinates for an unphysical space. The notation for elements of  $U_L$ , unit elements of  $\mathbb{U}$  is set out in table 5.

TABLE 9. Graded spatially equivalent  $\Gamma_0$  orientations

Ref	scalar	vector				bivector				trivector			pseudo scalar	$[e_{16} \text{ to } e_{31}]$			
		spatial		t	spatial		spatio-t	spatio-t		xyz							
$\Gamma_{0\gamma}^{\lambda\delta}$	$\sigma_o S$	$\lambda_\iota X$	$\lambda_j Y$	$\lambda_\kappa Z$	$\delta_o T$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\gamma_\iota D$	$\gamma_j E$	$\gamma_\kappa F$	$\delta_\iota P$	$\delta_j Q$	$\delta_\kappa R$	$\lambda_o U$	$\gamma_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$\lambda_\iota iX$	$\lambda_j iY$	$\lambda_\kappa iZ$	$\delta_o iT$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\gamma_\iota D$	$\gamma_j E$	$\gamma_\kappa F$	$\delta_\iota iP$	$\delta_j iQ$	$\delta_\kappa iR$	$\lambda_o iU$	$\gamma_o V$	$i \times [e_1 \text{ to } e_{15}]$
$\Gamma_{0\gamma}^{\delta\lambda}$	$\sigma_o S$	$\delta_\iota X$	$\delta_j Y$	$\delta_\kappa Z$	$\lambda_o T$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\gamma_\iota D$	$\gamma_j E$	$\gamma_\kappa F$	$\lambda_\iota P$	$\lambda_j Q$	$\lambda_\kappa R$	$\delta_o U$	$\gamma_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$\delta_\iota iX$	$\delta_j iY$	$\delta_\kappa iZ$	$\lambda_o iT$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\gamma_\iota D$	$\gamma_j E$	$\gamma_\kappa F$	$\lambda_\iota iP$	$\lambda_j iQ$	$\lambda_\kappa iR$	$\delta_o iU$	$\gamma_o V$	$i \times [e_1 \text{ to } e_{15}]$
$\Gamma_{0\delta}^{\lambda\gamma}$	$\sigma_o S$	$\lambda_\iota X$	$\lambda_j Y$	$\lambda_\kappa Z$	$\gamma_o T$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\delta_\iota D$	$\delta_j E$	$\delta_\kappa F$	$\gamma_\iota P$	$\gamma_j Q$	$\gamma_\kappa R$	$\lambda_o U$	$\delta_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$\lambda_\iota iX$	$\lambda_j iY$	$\lambda_\kappa iZ$	$\gamma_o iT$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\delta_\iota D$	$\delta_j E$	$\delta_\kappa F$	$\gamma_\iota iP$	$\gamma_j iQ$	$\gamma_\kappa iR$	$\lambda_o iU$	$\delta_o V$	$i \times [e_1 \text{ to } e_{15}]$
$\Gamma_{0\delta}^{\gamma\lambda}$	$\sigma_o S$	$\gamma_\iota X$	$\gamma_j Y$	$\gamma_\kappa Z$	$\lambda_o T$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\delta_\iota D$	$\delta_j E$	$\delta_\kappa F$	$\lambda_\iota P$	$\lambda_j Q$	$\lambda_\kappa R$	$\gamma_o U$	$\delta_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$\gamma_\iota iX$	$\gamma_j iY$	$\gamma_\kappa iZ$	$\lambda_o iT$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\delta_\iota D$	$\delta_j E$	$\delta_\kappa F$	$\lambda_\iota iP$	$\lambda_j iQ$	$\lambda_\kappa iR$	$\gamma_o iU$	$\delta_o V$	$i \times [e_1 \text{ to } e_{15}]$
$\Gamma_{0\lambda}^{\gamma\delta}$	$\sigma_o S$	$\gamma_\iota X$	$\gamma_j Y$	$\gamma_\kappa Z$	$\delta_o T$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\lambda_\iota D$	$\lambda_j E$	$\lambda_\kappa F$	$\delta_\iota P$	$\delta_j Q$	$\delta_\kappa R$	$\gamma_o U$	$\lambda_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$\gamma_\iota iX$	$\gamma_j iY$	$\gamma_\kappa iZ$	$\delta_o iT$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\lambda_\iota D$	$\lambda_j E$	$\lambda_\kappa F$	$\delta_\iota iP$	$\delta_j iQ$	$\delta_\kappa iR$	$\gamma_o iU$	$\lambda_o V$	$i \times [e_1 \text{ to } e_{15}]$
$\Gamma_{0\lambda}^{\delta\gamma}$	$\sigma_o S$	$\delta_\iota X$	$\delta_j Y$	$\delta_\kappa Z$	$\gamma_o T$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\lambda_\iota D$	$\lambda_j E$	$\lambda_\kappa F$	$\gamma_\iota P$	$\gamma_j Q$	$\gamma_\kappa R$	$\delta_o U$	$\lambda_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$\delta_\iota iX$	$\delta_j iY$	$\delta_\kappa iZ$	$\gamma_o iT$	$\sigma_\iota L$	$\sigma_j M$	$\sigma_\kappa N$	$\lambda_\iota D$	$\lambda_j E$	$\lambda_\kappa F$	$\gamma_\iota iP$	$\gamma_j iQ$	$\gamma_\kappa iR$	$\delta_o iU$	$\lambda_o V$	$i \times [e_1 \text{ to } e_{15}]$

TABLE 10. Graded spatially equivalent  $A_0$  and  $B_0$  orientations

Ref	scalar	vector				bivector						trivector			pseudo scalar	[ $e_{16}$ to $e_{31}$ ]	
		spatial		t	spatial		spatio-t		spatio-t		xyz						
$A_{0\beta}^{\mu\delta}$	$\sigma_o S$	$\mu_l X$	$\mu_j Y$	$\mu_\kappa Z$	$\delta_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\beta_l D$	$\beta_j E$	$\beta_\kappa F$	$\delta_l P$	$\delta_j Q$	$\delta_\kappa R$	$\mu_o U$	$\beta_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$i\mu_l X$	$i\mu_j Y$	$i\mu_\kappa Z$	$i\delta_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\beta_l D$	$\beta_j E$	$\beta_\kappa F$	$i\delta_l P$	$i\delta_j Q$	$i\delta_\kappa R$	$i\mu_o U$	$\beta_o V$	$i \times [e_1 \text{ to } e_{15}]$
$A_{0\beta}^{\delta\mu}$	$\sigma_o S$	$\delta_l X$	$\delta_j Y$	$\delta_\kappa Z$	$\mu_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\beta_l D$	$\beta_j E$	$\beta_\kappa F$	$\mu_l P$	$\mu_j Q$	$\mu_\kappa R$	$\delta_o U$	$\beta_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$i\delta_l X$	$i\delta_j Y$	$i\delta_\kappa Z$	$i\mu_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\beta_l D$	$\beta_j E$	$\beta_\kappa F$	$i\mu_l P$	$i\mu_j Q$	$i\mu_\kappa R$	$i\delta_o U$	$\beta_o V$	$i \times [e_1 \text{ to } e_{15}]$
$A_{0\delta}^{\beta\mu}$	$\sigma_o S$	$\beta_l X$	$\beta_j Y$	$\beta_\kappa Z$	$\mu_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\delta_l D$	$\delta_j E$	$\delta_\kappa F$	$\mu_l P$	$\mu_j Q$	$\mu_\kappa R$	$\beta_o U$	$\delta_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$i\beta_l X$	$i\beta_j Y$	$i\beta_\kappa Z$	$i\mu_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\delta_l D$	$\delta_j E$	$\delta_\kappa F$	$i\mu_l P$	$i\mu_j Q$	$i\mu_\kappa R$	$i\beta_o U$	$\delta_o V$	$i \times [e_1 \text{ to } e_{15}]$
$A_{0\delta}^{\mu\beta}$	$\sigma_o S$	$\mu_l X$	$\mu_j Y$	$\mu_\kappa Z$	$\beta_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\delta_l D$	$\delta_j E$	$\delta_\kappa F$	$\beta_l P$	$\beta_j Q$	$\beta_\kappa R$	$\mu_o U$	$\delta_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$i\mu_l X$	$i\mu_j Y$	$i\mu_\kappa Z$	$i\beta_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\delta_l D$	$\delta_j E$	$\delta_\kappa F$	$i\beta_l P$	$i\beta_j Q$	$i\beta_\kappa R$	$i\mu_o U$	$\delta_o V$	$i \times [e_1 \text{ to } e_{15}]$
$A_{0\mu}^{\delta\beta}$	$\sigma_o S$	$\delta_l X$	$\delta_j Y$	$\delta_\kappa Z$	$\beta_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\mu_l D$	$\mu_j E$	$\mu_\kappa F$	$\beta_l P$	$\beta_j Q$	$\beta_\kappa R$	$\delta_o U$	$\mu_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$i\delta_l X$	$i\delta_j Y$	$i\delta_\kappa Z$	$i\beta_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\mu_l D$	$\mu_j E$	$\mu_\kappa F$	$i\beta_l P$	$i\beta_j Q$	$i\beta_\kappa R$	$i\delta_o U$	$\mu_o V$	$i \times [e_1 \text{ to } e_{15}]$
$A_{0\mu}^{\beta\delta}$	$\sigma_o S$	$\beta_l X$	$\beta_j Y$	$\beta_\kappa Z$	$\delta_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\mu_l D$	$\mu_j E$	$\mu_\kappa F$	$\delta_l P$	$\delta_j Q$	$\delta_\kappa R$	$\beta_o U$	$\mu_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$i\beta_l X$	$i\beta_j Y$	$i\beta_\kappa Z$	$i\delta_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\mu_l D$	$\mu_j E$	$\mu_\kappa F$	$i\delta_l P$	$i\delta_j Q$	$i\delta_\kappa R$	$i\beta_o U$	$\mu_o V$	$i \times [e_1 \text{ to } e_{15}]$
$B_{0\beta}^{\nu\gamma}$	$\sigma_o S$	$\nu_l X$	$\nu_j Y$	$\nu_\kappa Z$	$\gamma_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\beta_l D$	$\beta_j E$	$\beta_\kappa F$	$\gamma_l P$	$\gamma_j Q$	$\gamma_\kappa R$	$\nu_o U$	$\beta_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$i\nu_l X$	$i\nu_j Y$	$i\nu_\kappa Z$	$i\gamma_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\beta_l D$	$\beta_j E$	$\beta_\kappa F$	$i\gamma_l P$	$i\gamma_j Q$	$i\gamma_\kappa R$	$i\nu_o U$	$\beta_o V$	$i \times [e_1 \text{ to } e_{15}]$
$B_{0\beta}^{\gamma\nu}$	$\sigma_o S$	$\gamma_l X$	$\gamma_j Y$	$\gamma_\kappa Z$	$\nu_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\beta_l D$	$\beta_j E$	$\beta_\kappa F$	$\nu_l P$	$\nu_j Q$	$\nu_\kappa R$	$\gamma_o U$	$\beta_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$i\gamma_l X$	$i\gamma_j Y$	$i\gamma_\kappa Z$	$i\nu_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\beta_l D$	$\beta_j E$	$\beta_\kappa F$	$i\nu_l P$	$i\nu_j Q$	$i\nu_\kappa R$	$i\gamma_o U$	$\beta_o V$	$i \times [e_1 \text{ to } e_{15}]$
$B_{0\gamma}^{\beta\nu}$	$\sigma_o S$	$\beta_l X$	$\beta_j Y$	$\beta_\kappa Z$	$\nu_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\gamma_l D$	$\gamma_j E$	$\gamma_\kappa F$	$\nu_l P$	$\nu_j Q$	$\nu_\kappa R$	$\beta_o U$	$\gamma_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$i\beta_l X$	$i\beta_j Y$	$i\beta_\kappa Z$	$i\nu_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\gamma_l D$	$\gamma_j E$	$\gamma_\kappa F$	$i\nu_l P$	$i\nu_j Q$	$i\nu_\kappa R$	$i\beta_o U$	$\gamma_o V$	$i \times [e_1 \text{ to } e_{15}]$
$B_{0\gamma}^{\nu\beta}$	$\sigma_o S$	$\nu_l X$	$\nu_j Y$	$\nu_\kappa Z$	$\beta_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\gamma_l D$	$\gamma_j E$	$\gamma_\kappa F$	$\beta_l P$	$\beta_j Q$	$\beta_\kappa R$	$\nu_o U$	$\gamma_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$i\nu_l X$	$i\nu_j Y$	$i\nu_\kappa Z$	$i\beta_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\gamma_l D$	$\gamma_j E$	$\gamma_\kappa F$	$i\beta_l P$	$i\beta_j Q$	$i\beta_\kappa R$	$i\nu_o U$	$\gamma_o V$	$i \times [e_1 \text{ to } e_{15}]$
$B_{0\nu}^{\gamma\beta}$	$\sigma_o S$	$\gamma_l X$	$\gamma_j Y$	$\gamma_\kappa Z$	$\beta_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\nu_l D$	$\nu_j E$	$\nu_\kappa F$	$\beta_l P$	$\beta_j Q$	$\beta_\kappa R$	$\gamma_o U$	$\nu_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$i\gamma_l X$	$i\gamma_j Y$	$i\gamma_\kappa Z$	$i\beta_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\nu_l D$	$\nu_j E$	$\nu_\kappa F$	$i\beta_l P$	$i\beta_j Q$	$i\beta_\kappa R$	$i\gamma_o U$	$\nu_o V$	$i \times [e_1 \text{ to } e_{15}]$
$B_{0\nu}^{\beta\gamma}$	$\sigma_o S$	$\beta_l X$	$\beta_j Y$	$\beta_\kappa Z$	$\gamma_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\nu_l D$	$\nu_j E$	$\nu_\kappa F$	$\gamma_l P$	$\gamma_j Q$	$\gamma_\kappa R$	$\beta_o U$	$\nu_o V$	$i \times [e_1 \text{ to } e_{15}]$
	$\sigma_o S$	$i\beta_l X$	$i\beta_j Y$	$i\beta_\kappa Z$	$i\gamma_o T$	$\sigma_l L$	$\sigma_j M$	$\sigma_\kappa N$	$\nu_l D$	$\nu_j E$	$\nu_\kappa F$	$i\gamma_l P$	$i\gamma_j Q$	$i\gamma_\kappa R$	$i\beta_o U$	$\nu_o V$	$i \times [e_1 \text{ to } e_{15}]$

For each of  $\Gamma_0$ ,  $A_0$  and  $B_0$  three sets of four of alignments share common even multivector components, suggesting that the even transverse multivectors for each set correspond to a spinor for a fundamental fermion. The Jordan bracket for their subalgebra matches the Lie bracket for the even  $Cl_{3,1}^+$  subalgebra, so this may be consistent with Hestenes version of the Dirac equation[33].

For the assignment of  $A_0$  to one chirality and  $B_0$  to the opposite chirality, inspection of table 10 reveals that, for the change to the opposite chiralities,  $[x, y, z, t]$  transverse vectors are factored by unit octonions from a quaternionic subloop, e.g. for:

$$A_{0\beta}^{\mu\delta} \leftrightarrow B_{0\beta}^{\nu\gamma} \text{ and } A_{0\beta}^{\delta\mu} \leftrightarrow B_{0\beta}^{\gamma\nu} : [xyzt] \text{ are factored by } \lambda_o$$

$$A_{0\beta}^{\mu\delta} \leftrightarrow B_{0\beta}^{\gamma\nu} \text{ and } A_{0\beta}^{\delta\mu} \leftrightarrow B_{0\beta}^{\nu\gamma} : [xyzt] \text{ are factored by } \alpha_o$$

For these subloops vectors are factored by either  $\alpha_o$  or  $\lambda_o$  from the  $[\sigma_o, \lambda_o, \alpha_o, \beta_o]$  subloop, and for:

$$A_{0\delta}^{\beta\mu} \leftrightarrow B_{0\gamma}^{\beta\nu} : [xyz] \text{ are factored by } \sigma_o, [t] \times \lambda_o$$

$$A_{0\delta}^{\beta\mu} \leftrightarrow B_{0\gamma}^{\nu\beta} : [xyz] \text{ are factored by } \gamma_o, [t] \times \delta_o$$

$$A_{0\delta}^{\mu\beta} \leftrightarrow B_{0\gamma}^{\nu\beta} : [xyz] \text{ are factored by } \lambda_o, [t] \times \sigma_o$$

$$A_{0\delta}^{\mu\beta} \leftrightarrow B_{0\gamma}^{\beta\nu} : [xyz] \text{ For these subloops vectors are factored by } \delta_o, [t] \times \gamma_o$$

vectors are factored by elements from the  $[\sigma_o, \lambda_o, \gamma_o, \delta_o]$  subloop.

Subloops for all such chirality changes include  $\lambda_o$ , so it is associated with a chirality operator



## 5. Strong nuclear sector

Elements subscripted  $\iota, j$  and  $\kappa$ , when complexified, can be associated with rotations in three complex dimensions, for which  $SU(3)$  is applicable symmetry group. When  $[\sigma_o, \iota_o, j_o, \kappa_o]$  are multiplied by  $\alpha_o$ , the result is a loop of unit octonions. So, if  $\alpha_o$  is fixed the associated automorphism group becomes the  $SU(3)$  subgroup of  $G_2$ .

### 5.1. Colored fermions - quarks

In section 4.2 subloops  $A_{1..6}$  and  $B_{1..6}$  were assigned to quarks. Inspection of table 2 suggests that they can be combined in sets of three so that spatial equivalence is achieved for the combination, as elements subscripted  $\iota, j$  and  $\kappa$  would be included in a balanced way. Also, whilst a single subloop representing a single color quark would be unbalanced with respect to these subscripted elements, in a combination with a subloop representing its antiquark the imbalance can be eliminated.

### 5.2. Colored Bosons - Gluons

Subloops  $\Sigma_4, \Sigma_5$  and  $\Sigma_6$  do not feature internal spatial equivalence, so are associated with a single color, and are subject to the strong nuclear force. For a given subloop/color, their  $\sigma_{o\iota j\kappa}, \lambda_{o\iota j\kappa}, \mu_{o\iota j\kappa}, \nu_{o\iota j\kappa}, \alpha_{o\iota j\kappa}, \beta_{o\iota j\kappa}, \gamma_{o\iota j\kappa}$ , and  $\delta_{o\iota j\kappa}$  contents all match each other, so gluons are not subject to the electroweak force.

### 5.3. Flavor/Colored bosons - U bosons

With respect to subloops  $\Sigma_4, \Sigma_5$  and  $\Sigma_6$ , subloops  $\Sigma_7$  to  $\Sigma_{15}$  have a similar relationship to that for subloops  $\Sigma_1, \Sigma_2$  and  $\Sigma_3$  with respect to  $\Sigma_o$ . This suggests that they will acquire mass by a Brout-Englert-Higgs type mechanism generating bosons similar to the lepto-quark bosons featuring in Pati-Salam models[34].

### 5.4. Higgs Boson

An algebra assembled as  $[S, T, U, V] \otimes [\sigma_o, \lambda_o, \mu_o, \nu_o] \otimes [\sigma_o, i\sigma_o, \alpha_o, i\alpha_o]$  has only scalar components with respect to the spatial dimensions for  $CL_{3,1}(R)$  so could accommodate a subalgebra representing the Higgs boson.

## 6. Charge

In [3], charge was postulated as being associated with the proportion of  $[\beta_\iota, \beta_j, \beta_\kappa]$  present. This was dictated by the assignment of  $A_0$  and  $B_0$  to the electron/muon/tau family and  $\Gamma_0$  to the neutrino family. However, this rule only confers charge for one electroweak boson subloop. A rule that generates charge assignments that are consistent with the fermion families' charges, and which confers charges for two electroweak boson subloops, is: to associate neutrality with the proportion of  $[\lambda_\iota, \lambda_j, \lambda_\kappa]$  present.

For this rule, the  $\Gamma_0, \Sigma_0$  and  $\Sigma_2$  families are neutral, the  $A_0$  and  $B_0$  families have unit charge, the  $A_{1..3}$  families and  $B_{1..3}$  families have 1/3 charge and the  $A_{4..6}$  families and  $B_{4..6}$  families have 2/3 charge. The  $\Sigma_{1..3}$  subloops would also have 1/3 charge, but this need not prevent these subloops from being used for gluons, as gluons are combinations of colors with anticolors, so combinations can have zero electric charge.

## 7. Supersymmetry

For each fermionic subalgebra, there is a bosonic subalgebra with the same  $[\sigma_{o\iota j\kappa}, \lambda_{o\iota j\kappa}, \mu_{o\iota j\kappa}, \nu_{o\iota j\kappa}]$  content, but inverted  $[\alpha_{o\iota j\kappa}, \beta_{o\iota j\kappa}, \gamma_{o\iota j\kappa}, \delta_{o\iota j\kappa}]$  content. This suggests a form of supersymmetry. The bosonic subalgebra  $\Sigma_0$  is left without a supersymmetric partner.

## 8. Dark matter

$\mathbb{U}$  does not offer subalgebras that could represent fermionic dark matter. This suggests that the bosonic subalgebras postulated as representing  $\mathbb{U}$  bosons may be responsible for the existence of dark matter, possibly combining to create bosonic dark matter particles in a similar way to that in which gluons can combine to create glueballs.

## 9. Measurement/collapse

For a model based on a non-associative algebra, it may be possible to ascribe the phenomenon of quantum measurement/collapse to its non-associativity. For a model based on  $\mathbb{T} \otimes Cl_{3,1}(C)$ , this suggests a universe propagating as a Huygens wave for a conformal space embedded in five dimensions with a  $Cl_{0,5}(R) \cong Cl_{3,1}(C)$  multivector combined with absolute time. Between measurements particle trajectories would be deterministic, but, because handings and order of algebraic operations could differ for different points of observation, calculations of trajectories between events would be ambiguous. As a result, any attempt to predict events could only be probabilistic. Events would be loci for which calculations for all points of observation generate a consistent but not necessarily identical result, some latitude being possible subject to limits imposed by the Heisenberg uncertainty principle. Loci with inconsistent results would be occupied by “quantum foam”. A theory based on this approach may require application of the principles of chaos theory.

## 10. Conclusion

It seems reasonable to suppose that, in the tradition of the periodic table and Bohr’s model of the atom, there might be a simplistic mathematical pattern with a structure similar to that of the standard model. Just such a pattern can be found for  $\mathbb{U}$ . This may be a coincidence, but the similarities are striking, so the speculative analysis presented in this paper may assist in finding a path to a deeper understanding of the basis of reality.

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## Appendix A. Cayley tables for $M_L$ and $T_L$

### A.1. Cayley tables

The Cayley tables of both  $M_4(C)$  and  $\mathbb{T}$  can be assembled as normalised latin squares with elements ordered so that bit-wise ‘exclusive or’ (XOR) of binary representations of two elements’ numbering generates the numbering of their product. As a result, if the sign of products is ignored, their Cayley tables are the same and, for subalgebras that include the negative of the identity, their subalgebra inventory is the same. To detail a scheme of ultra-complexification of  $M_4(C)$ , notation such as  $e_0, e_1, \dots, e_{31}$  could be used for its elements. However, as one requirement for a unification algebra is consistency with respect to the principle of equivalence of spatial dimensions, an alternative approach to labelling unit elements has been adopted.

### A.2. Notation for $M_4(C)$ unit elements

TABLE 11. Notation used to label  $4 \times 4$  unit matrices

$$\begin{array}{ccc}
 & S = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} & \\
 R = \begin{bmatrix} 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{bmatrix} & P = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} & M = \begin{bmatrix} 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \\
 Y = \begin{bmatrix} 0 & -1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & -1 & 0 \end{bmatrix} & E = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix} & T = \begin{bmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \\
 D = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} & X = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{bmatrix} & N = \begin{bmatrix} 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \\
 F = \begin{bmatrix} 0 & -1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} & Z = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix} & L = \begin{bmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{bmatrix} \\
 U = \begin{bmatrix} 0 & 0 & 0 & -1 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} & V = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} & Q = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \\ 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}
 \end{array}$$

Note: the forms of these matrices differ from those used in previous papers by this author[35][2]. Positive forms have been chosen to allow  $[S, L, M, N]$  to represent unit elements for a right isoclinic quaternion algebra  $\mathbb{H}_{\mathbb{R}}$ , and  $[S, T, U, V]$  to represent unit elements for a left isoclinic quaternion algebra  $\mathbb{H}_{\mathbb{L}}$ , as used by Van Elfrinkhof[36].

The multiplication table for  $M_4(C)$  using these labels is shown in Table 12.

TABLE 12. Labels and Cayley table for  $M \cong M_4(C)$

	$e_0$	$e_1$	$e_2$	$e_3$	$e_4$	$e_5$	$e_6$	$e_7$	$e_8$	$e_9$	$e_{10}$	$e_{11}$	$e_{12}$	$e_{13}$	$e_{14}$	$e_{15}$	$e_{16}$	$e_{17}$	$e_{18}$	$e_{19}$	$e_{20}$	$e_{21}$	$e_{22}$	$e_{23}$	$e_{24}$	$e_{25}$	$e_{26}$	$e_{27}$	$e_{28}$	$e_{29}$	$e_{30}$	$e_{31}$
	$S$	$L$	$M$	$N$	$T$	$P$	$Q$	$R$	$U$	$X$	$Y$	$Z$	$V$	$D$	$E$	$F$	$iS$	$iL$	$iM$	$iN$	$iT$	$iP$	$iQ$	$iR$	$iU$	$iX$	$iY$	$iZ$	$iV$	$iD$	$iE$	$iF$
$S$	$+S$	$+L$	$+M$	$+N$	$+T$	$+P$	$+Q$	$+R$	$+U$	$+X$	$+Y$	$+Z$	$+V$	$+D$	$+E$	$+F$	$+iS$	$+iL$	$+iM$	$+iN$	$+iT$	$+iP$	$+iQ$	$+iR$	$+iU$	$+iX$	$+iY$	$+iZ$	$+iV$	$+iD$	$+iE$	$+iF$
$L$	$+L$	$-S$	$-N$	$+M$	$+P$	$-T$	$-R$	$+Q$	$+X$	$-U$	$-Z$	$+Y$	$+D$	$-V$	$-F$	$+E$	$+iL$	$-iS$	$-iN$	$+iM$	$+iP$	$-iT$	$-iR$	$+iQ$	$+iX$	$-iU$	$-iZ$	$+iY$	$+iD$	$-iV$	$-iF$	$+iE$
$M$	$+M$	$+N$	$-S$	$-L$	$+Q$	$+R$	$-T$	$-P$	$+Y$	$+Z$	$-U$	$-X$	$+E$	$+F$	$-V$	$-D$	$+iM$	$+iN$	$-iS$	$-iL$	$+iQ$	$+iR$	$-iT$	$-iP$	$+iY$	$+iZ$	$-iU$	$-iX$	$+iE$	$+iF$	$-iV$	$-iD$
$N$	$+N$	$-M$	$+L$	$-S$	$+R$	$-Q$	$+P$	$-T$	$+Z$	$-Y$	$+X$	$-U$	$+F$	$-E$	$+D$	$-V$	$+iN$	$-iM$	$+iL$	$-iS$	$+iR$	$-iQ$	$+iP$	$-iT$	$+iZ$	$-iY$	$+iX$	$-iU$	$+iF$	$-iE$	$+iD$	$-iV$
$T$	$+T$	$+P$	$+Q$	$+R$	$-S$	$-L$	$-M$	$-N$	$+V$	$+D$	$+E$	$+F$	$-U$	$-X$	$-Y$	$-Z$	$+iT$	$+iP$	$+iQ$	$+iR$	$-iS$	$-iL$	$-iM$	$-iN$	$+iV$	$+iD$	$+iE$	$+iF$	$-iU$	$-iX$	$-iY$	$-iZ$
$P$	$+P$	$-T$	$-R$	$+Q$	$-L$	$+S$	$+N$	$-M$	$+D$	$-V$	$-F$	$+E$	$-X$	$+U$	$+Z$	$-Y$	$+iP$	$-iT$	$-iR$	$+iQ$	$-iL$	$+iS$	$+iN$	$-iM$	$+iD$	$-iV$	$-iF$	$+iE$	$-iX$	$+iU$	$+iZ$	$-iY$
$Q$	$+Q$	$+R$	$-T$	$-P$	$-M$	$-N$	$+S$	$+L$	$+E$	$+F$	$-V$	$-D$	$-Y$	$-Z$	$+U$	$+X$	$+iQ$	$+iR$	$-iT$	$-iP$	$-iM$	$-iN$	$+iS$	$+iL$	$+iE$	$+iF$	$-iV$	$-iD$	$-iY$	$-iZ$	$+iU$	$+iX$
$R$	$+R$	$-Q$	$+P$	$-T$	$-N$	$+M$	$-L$	$+S$	$+F$	$-E$	$+D$	$-V$	$-Z$	$+Y$	$-X$	$+U$	$+iR$	$-iQ$	$+iP$	$-iT$	$-iN$	$+iM$	$-iL$	$+iS$	$+iF$	$-iE$	$+iD$	$-iV$	$-iZ$	$+iY$	$-iX$	$+iU$
$U$	$+U$	$+X$	$+Y$	$+Z$	$-V$	$-D$	$-E$	$-F$	$-S$	$-L$	$-M$	$-N$	$+T$	$+P$	$+Q$	$+R$	$+iU$	$+iX$	$+iY$	$+iZ$	$-iV$	$-iD$	$-iE$	$-iF$	$-iS$	$-iL$	$-iM$	$-iN$	$+iT$	$+iP$	$+iQ$	$+iR$
$X$	$+X$	$-U$	$-Z$	$+Y$	$-D$	$+V$	$-E$	$-L$	$+S$	$+N$	$-M$	$+P$	$-T$	$-R$	$+Q$	$+iX$	$-iU$	$-iZ$	$+iY$	$-iD$	$+iV$	$+iF$	$-iE$	$-iS$	$-iL$	$+iM$	$+iN$	$-iM$	$+iP$	$-iT$	$-iR$	$+iQ$
$Y$	$+Y$	$+Z$	$-U$	$-X$	$-E$	$-F$	$+V$	$+D$	$-M$	$-N$	$+S$	$+L$	$+Q$	$+R$	$-T$	$-P$	$+iY$	$+iZ$	$-iU$	$-iX$	$-iE$	$-iF$	$+iV$	$+iD$	$-iM$	$-iN$	$+iS$	$+iL$	$+iQ$	$+iR$	$-iT$	$-iP$
$Z$	$+Z$	$-Y$	$+X$	$-U$	$-F$	$+E$	$-D$	$+V$	$-N$	$+M$	$-L$	$+S$	$+R$	$-Q$	$+P$	$-T$	$+iZ$	$-iY$	$+iX$	$-iU$	$-iF$	$+iE$	$-iD$	$+iV$	$-iN$	$+iM$	$-iL$	$+iS$	$+iR$	$-iQ$	$+iP$	$-iT$
$V$	$+V$	$+D$	$+E$	$+F$	$+U$	$+X$	$+Y$	$+Z$	$-T$	$-P$	$-Q$	$-R$	$-S$	$-L$	$-M$	$-N$	$+iV$	$+iD$	$+iE$	$+iF$	$+iU$	$+iX$	$+iY$	$+iZ$	$-iT$	$-iP$	$-iQ$	$-iR$	$-iS$	$-iL$	$-iM$	$-iN$
$D$	$+D$	$-V$	$-F$	$+E$	$+X$	$-U$	$-Z$	$+Y$	$-P$	$+T$	$+R$	$-Q$	$-L$	$+S$	$+N$	$-M$	$+iD$	$-iV$	$-iF$	$+iE$	$+iX$	$-iU$	$-iZ$	$+iY$	$-iP$	$+iT$	$+iR$	$-iQ$	$-iL$	$+iS$	$+iN$	$-iM$
$E$	$+E$	$+F$	$-V$	$-D$	$+Y$	$+Z$	$-U$	$-X$	$-Q$	$-R$	$+T$	$+P$	$-M$	$-N$	$+S$	$+L$	$+iE$	$+iF$	$-iV$	$-iD$	$+iY$	$+iZ$	$-iU$	$-iX$	$-iQ$	$-iR$	$+iT$	$+iP$	$-iM$	$-iN$	$+iS$	$+iL$
$F$	$+F$	$-E$	$+D$	$-V$	$+Z$	$-Y$	$+X$	$-U$	$-R$	$+Q$	$-P$	$+T$	$-N$	$+M$	$-L$	$+S$	$+iF$	$-iE$	$+iD$	$-iV$	$+iZ$	$-iY$	$+iX$	$-iU$	$-iR$	$+iQ$	$-iP$	$+iT$	$+iM$	$+iN$	$+iS$	$+iL$
$S$	$+iS$	$+iL$	$+iM$	$+iN$	$+iT$	$+iP$	$+iQ$	$+iR$	$+iU$	$+iX$	$+iY$	$+iZ$	$+iV$	$+iD$	$+iE$	$+iF$	$-S$	$-L$	$-M$	$-N$	$-T$	$-P$	$-Q$	$-R$	$-U$	$-X$	$-Y$	$-Z$	$-V$	$-D$	$-E$	$-F$
$L$	$+iL$	$-iS$	$-iN$	$+iM$	$+iP$	$-iT$	$-iR$	$+iQ$	$+iX$	$-iU$	$-iZ$	$+iY$	$+iD$	$-iV$	$-iF$	$+iE$	$-L$	$+S$	$+N$	$-M$	$-P$	$+T$	$+R$	$-Q$	$-X$	$+U$	$+Z$	$-Y$	$-D$	$+V$	$+F$	$-E$
$M$	$+iM$	$+iN$	$-iS$	$-iL$	$+iQ$	$+iR$	$-iT$	$-iP$	$+iY$	$+iZ$	$-iU$	$-iX$	$+iE$	$+iF$	$-iV$	$-iD$	$-M$	$-N$	$+S$	$+L$	$-Q$	$-R$	$+T$	$+P$	$-Y$	$-Z$	$+U$	$+X$	$-E$	$-F$	$+V$	$+D$
$N$	$+iN$	$-iM$	$+iL$	$-iS$	$+iR$	$-iQ$	$+iP$	$-iT$	$+iZ$	$-iY$	$+iX$	$-iU$	$+iF$	$-iE$	$+iD$	$-iV$	$-N$	$+M$	$-L$	$+S$	$-R$	$+Q$	$-P$	$+T$	$-Z$	$+Y$	$-X$	$+U$	$-F$	$+E$	$-D$	$+V$
$T$	$+iT$	$+iP$	$+iQ$	$+iR$	$-iS$	$-iL$	$-iM$	$-iN$	$+iV$	$+iD$	$+iE$	$+iF$	$-iU$	$-iX$	$-iY$	$-iZ$	$-T$	$-P$	$-Q$	$-R$	$+S$	$+L$	$+M$	$+N$	$-V$	$-D$	$-E$	$-F$	$+U$	$+X$	$+Y$	$+Z$
$P$	$+iP$	$-iT$	$-iR$	$+iQ$	$-iL$	$+iS$	$+iN$	$-iM$	$+iD$	$-iV$	$-iF$	$+iE$	$-iX$	$+iU$	$+iZ$	$-iY$	$-P$	$+T$	$+R$	$-Q$	$+L$	$-S$	$-N$	$+M$	$-D$	$+V$	$+F$	$-E$	$+X$	$-U$	$-Z$	$+Y$
$Q$	$+iQ$	$+iR$	$-iT$	$-iP$	$-iM$	$-iN$	$+iS$	$+iL$	$+iE$	$+iF$	$-iV$	$-iD$	$-iY$	$-iZ$	$+iU$	$+iX$	$-Q$	$-R$	$+T$	$+P$	$+M$	$+N$	$-S$	$-L$	$-E$	$-F$	$+V$	$+D$	$+Y$	$+Z$	$-U$	$-X$
$R$	$+iR$	$-iQ$	$+iP$	$-iT$	$-iN$	$+iM$	$-iL$	$+iS$	$+iF$	$-iE$	$+iD$	$-iV$	$-iZ$	$+iY$	$-iX$	$+iU$	$-R$	$+Q$	$-P$	$+T$	$+N$	$-M$	$+L$	$-S$	$-F$	$+E$	$-D$	$+V$	$+Z$	$-Y$	$+X$	$-U$
$U$	$+iU$	$+iX$	$+iY$	$+iZ$	$-iV$	$-iD$	$-iE$	$-iF$	$-iS$	$-iL$	$-iM$	$-iN$	$+iT$	$+iP$	$+iQ$	$+iR$	$-U$	$-X$	$-Y$	$-Z$	$+V$	$+D$	$+E$	$+F$	$+S$	$+L$	$+M$	$+N$	$-T$	$-P$	$-Q$	$-R$
$X$	$+iX$	$-iU$	$-iZ$	$+iY$	$-iD$	$+iV$	$+iF$	$-iE$	$-iL$	$+iS$	$+iN$	$-iM$	$+iP$	$-iT$	$-iR$	$+iQ$	$-X$	$+U$	$+Z$	$-Y$	$+D$	$-V$	$-F$	$+E$	$+L$	$-S$	$-N$	$+M$	$-P$	$+T$	$+R$	$-Q$
$Y$	$+iY$	$+iZ$	$-iU$	$-iX$	$-iE$	$-iF$	$+iV$	$+iD$	$-iM$	$-iN$	$+iS$	$+iL$	$+iQ$	$+iR$	$-iT$	$-iP$	$-Y$	$-Z$	$+U$	$+X$	$+E$	$+F$	$-V$	$-D$	$+M$	$+N$	$-S$	$-L$	$-Q$	$-R$	$+T$	$+P$
$Z$	$+iZ$	$-iY$	$+iX$	$-iU$	$-iF$	$+iE$	$-iD$	$+iV$	$-iN$	$+iM$	$-iL$	$+iS$	$+iR$	$-iQ$	$+iP$	$-iT$	$-Z$	$+Y$	$-X$	$+U$	$+F$	$-E$	$+D$	$-V$	$+N$	$-M$	$+L$	$-S$	$-R$	$+Q$	$-P$	$+T$
$V$	$+iV$	$+iD$	$+iE$	$+iF$	$+iU$	$+iX$	$+iY$	$+iZ$	$-iT$	$-iP$	$-iQ$	$-iR$	$-iS$	$-iL$	$-iM$	$-iN$	$-V$	$-D$	$-E$	$-F$	$-U$	$-X$	$-Y$	$-Z$	$+T$	$+P$	$+Q$	$+R$	$+S$	$+L$	$+M$	$+N$
$D$	$+iD$	$-iV$	$-iF$	$+iE$	$+iX$	$-iU$	$-iZ$	$+iY$	$-iP$	$+iT$	$+iR$	$-iQ$	$-iL$	$+iS$	$+iN$	$-iM$	$-D$	$+V$	$+F$	$-E$	$-X$	$+U$	$+Z$	$-Y$	$+P$	$-T$	$-R$	$+Q$	$+L$	$-S$	$-N$	$+M$
$E$	$+iE$	$+iF$	$-iV$	$-iD$	$+iY$	$+iZ$	$-iU$	$-iX$	$-iQ$	$-iR$	$+iT$	$+iP$	$-iM$	$-iN$	$+iS$	$+iL$	$-E$	$-F$	$+V$	$+D$	$-Y$	$-Z$	$+U$	$+X$	$+Q$	$+R$	$-T$	$-P$	$+M$	$+N$	$-S$	$-L$
$F$	$+iF$	$-iE$	$+iD$	$-iV$	$+iZ$	$-iY$	$+iX$	$-iU$	$-iR$	$+iQ$	$-iP$	$+iT$	$-iN$	$+iM$	$-iL$	$+iS$	$-F$	$+E$	$-D$	$+V$	$-Z$	$+Y$	$-X$	$+U$	$+R$	$-Q$	$+P$	$-T$	$+N$	$-M$	$+L$	$-S$

### A.3. Notation for $\mathbb{T}$ unit elements

As for  $M_4(C)$ , for  $\mathbb{T}$  an alternative approach to labelling unit elements has been adopted. Greek letters with greek subscripts have been chosen. The subscripts relate unit elements in sets in a scheme similar to that relating sets of unit elements for  $M_4(C)$  to the set chosen to represent a right isoclinic quaternion algebra as used by Van Elfr

The multiplication table for  $\mathbb{T}$  using these labels is shown in Table 14.

TABLE 14. Labels and Cayley table for  $\mathbb{T}$  basis elements

	$e_0$	$e_1$	$e_2$	$e_3$	$e_4$	$e_5$	$e_6$	$e_7$	$e_8$	$e_9$	$e_{10}$	$e_{11}$	$e_{12}$	$e_{13}$	$e_{14}$	$e_{15}$	$e_{16}$	$e_{17}$	$e_{18}$	$e_{19}$	$e_{20}$	$e_{21}$	$e_{22}$	$e_{23}$	$e_{24}$	$e_{25}$	$e_{26}$	$e_{27}$	$e_{28}$	$e_{29}$	$e_{30}$	$e_{31}$
	$\sigma_o$	$\sigma_i$	$\sigma_j$	$\sigma_k$	$\lambda_o$	$\lambda_i$	$\lambda_j$	$\lambda_k$	$\mu_o$	$\mu_i$	$\mu_j$	$\mu_k$	$\nu_o$	$\nu_i$	$\nu_j$	$\nu_k$	$\alpha_o$	$\alpha_i$	$\alpha_j$	$\alpha_k$	$\beta_o$	$\beta_i$	$\beta_j$	$\beta_k$	$\gamma_o$	$\gamma_i$	$\gamma_j$	$\gamma_k$	$\delta_o$	$\delta_i$	$\delta_j$	$\delta_k$
$\sigma_o$	$+\sigma_o$	$+\sigma_i$	$+\sigma_j$	$+\sigma_k$	$+\lambda_o$	$+\lambda_i$	$+\lambda_j$	$+\lambda_k$	$+\mu_o$	$+\mu_i$	$+\mu_j$	$+\mu_k$	$+\nu_o$	$+\nu_i$	$+\nu_j$	$+\nu_k$	$+\alpha_o$	$+\alpha_i$	$+\alpha_j$	$+\alpha_k$	$+\beta_o$	$+\beta_i$	$+\beta_j$	$+\beta_k$	$+\gamma_o$	$+\gamma_i$	$+\gamma_j$	$+\gamma_k$	$+\delta_o$	$+\delta_i$	$+\delta_j$	$+\delta_k$
$\sigma_i$	$+\sigma_i$	$-\sigma_o$	$+\sigma_k$	$-\sigma_j$	$+\lambda_i$	$-\lambda_o$	$-\lambda_k$	$+\lambda_j$	$+\mu_i$	$-\mu_o$	$-\mu_k$	$+\mu_j$	$-\nu_i$	$+\nu_o$	$+\nu_k$	$-\nu_j$	$+\alpha_i$	$-\alpha_o$	$-\alpha_k$	$+\alpha_j$	$-\beta_i$	$+\beta_o$	$+\beta_k$	$-\beta_j$	$-\gamma_i$	$+\gamma_o$	$+\gamma_k$	$-\gamma_j$	$+\delta_i$	$-\delta_o$	$-\delta_k$	$+\delta_j$
$\sigma_j$	$+\sigma_j$	$-\sigma_k$	$-\sigma_o$	$+\sigma_i$	$+\lambda_j$	$+\lambda_k$	$-\lambda_o$	$-\lambda_i$	$+\mu_j$	$+\mu_k$	$-\mu_o$	$-\mu_i$	$-\nu_j$	$-\nu_k$	$+\nu_o$	$+\nu_i$	$+\alpha_j$	$+\alpha_k$	$-\alpha_o$	$-\alpha_i$	$-\beta_j$	$-\beta_k$	$+\beta_o$	$+\beta_i$	$-\gamma_j$	$-\gamma_k$	$+\gamma_o$	$+\gamma_i$	$+\delta_j$	$+\delta_k$	$-\delta_o$	$-\delta_i$
$\sigma_k$	$+\sigma_k$	$+\sigma_j$	$-\sigma_i$	$-\sigma_o$	$+\lambda_k$	$-\lambda_j$	$+\lambda_i$	$-\lambda_o$	$+\mu_k$	$-\mu_j$	$+\mu_i$	$-\mu_o$	$-\nu_k$	$+\nu_j$	$-\nu_i$	$+\nu_o$	$+\alpha_k$	$-\alpha_j$	$+\alpha_i$	$-\alpha_o$	$-\beta_k$	$+\beta_j$	$-\beta_i$	$+\beta_o$	$-\gamma_k$	$+\gamma_j$	$-\gamma_i$	$+\gamma_o$	$+\delta_k$	$-\delta_j$	$+\delta_i$	$-\delta_o$
$\lambda_o$	$+\lambda_o$	$-\lambda_i$	$-\lambda_j$	$-\lambda_k$	$-\sigma_o$	$+\sigma_i$	$+\sigma_j$	$+\sigma_k$	$+\nu_o$	$+\nu_i$	$+\nu_j$	$+\nu_k$	$-\mu_o$	$-\mu_i$	$-\mu_j$	$-\mu_k$	$+\beta_o$	$+\beta_i$	$+\beta_j$	$+\beta_k$	$-\alpha_o$	$-\alpha_i$	$-\alpha_j$	$-\alpha_k$	$-\delta_o$	$-\delta_i$	$-\delta_j$	$-\delta_k$	$+\gamma_o$	$+\gamma_i$	$+\gamma_j$	$+\gamma_k$
$\lambda_i$	$+\lambda_i$	$+\lambda_o$	$-\lambda_k$	$+\lambda_j$	$-\sigma_i$	$-\sigma_o$	$-\sigma_k$	$+\sigma_j$	$+\nu_i$	$+\nu_o$	$+\nu_k$	$-\nu_j$	$+\mu_i$	$-\mu_o$	$+\mu_k$	$-\mu_j$	$+\beta_i$	$-\beta_o$	$+\beta_k$	$-\beta_j$	$+\alpha_i$	$-\alpha_o$	$+\alpha_k$	$-\alpha_j$	$-\delta_i$	$+\delta_o$	$-\delta_k$	$+\delta_j$	$-\gamma_i$	$+\gamma_o$	$-\gamma_k$	$+\gamma_j$
$\lambda_j$	$+\lambda_j$	$+\lambda_k$	$+\lambda_o$	$-\lambda_i$	$-\sigma_j$	$+\sigma_k$	$-\sigma_o$	$-\sigma_i$	$+\nu_j$	$-\nu_k$	$-\nu_o$	$+\nu_i$	$+\mu_j$	$-\mu_k$	$-\mu_o$	$+\mu_i$	$+\beta_j$	$-\beta_k$	$-\beta_o$	$+\beta_i$	$-\alpha_j$	$-\alpha_k$	$-\alpha_o$	$+\alpha_i$	$-\delta_j$	$+\delta_k$	$+\delta_o$	$-\delta_i$	$-\gamma_j$	$+\gamma_k$	$+\gamma_o$	$-\gamma_i$
$\lambda_k$	$+\lambda_k$	$-\lambda_j$	$+\lambda_i$	$+\lambda_o$	$-\sigma_k$	$-\sigma_j$	$+\sigma_i$	$-\sigma_o$	$+\nu_k$	$+\nu_j$	$-\nu_i$	$-\nu_o$	$+\mu_k$	$+\mu_j$	$-\mu_i$	$-\mu_o$	$+\beta_k$	$+\beta_j$	$-\beta_i$	$-\beta_o$	$+\alpha_k$	$+\alpha_j$	$-\alpha_i$	$-\alpha_o$	$-\delta_k$	$-\delta_j$	$+\delta_i$	$+\delta_o$	$-\gamma_k$	$-\gamma_j$	$+\gamma_i$	$+\gamma_o$
$\mu_o$	$+\mu_o$	$-\mu_i$	$-\mu_j$	$-\mu_k$	$-\nu_o$	$-\nu_i$	$-\nu_j$	$-\nu_k$	$-\sigma_o$	$+\sigma_i$	$+\sigma_j$	$+\sigma_k$	$+\lambda_o$	$+\lambda_i$	$+\lambda_j$	$+\lambda_k$	$+\gamma_o$	$+\gamma_i$	$+\gamma_j$	$+\gamma_k$	$+\delta_o$	$+\delta_i$	$+\delta_j$	$+\delta_k$	$-\alpha_o$	$-\alpha_i$	$-\alpha_j$	$-\alpha_k$	$-\beta_o$	$-\beta_i$	$-\beta_j$	$-\beta_k$
$\mu_i$	$+\mu_i$	$+\mu_o$	$-\mu_k$	$-\mu_j$	$-\nu_i$	$+\nu_o$	$+\nu_k$	$-\nu_j$	$-\sigma_i$	$-\sigma_o$	$-\sigma_k$	$+\sigma_j$	$-\lambda_i$	$+\lambda_o$	$+\lambda_k$	$-\lambda_j$	$+\gamma_i$	$+\gamma_k$	$-\gamma_j$	$+\gamma_o$	$+\delta_i$	$-\delta_o$	$-\delta_k$	$+\delta_j$	$+\alpha_i$	$-\alpha_o$	$-\alpha_k$	$-\alpha_j$	$+\beta_i$	$-\beta_o$	$-\beta_k$	$+\beta_j$
$\mu_j$	$+\mu_j$	$+\mu_k$	$+\mu_o$	$-\mu_i$	$-\nu_j$	$+\nu_o$	$+\nu_i$	$-\nu_k$	$-\sigma_j$	$-\sigma_k$	$-\sigma_o$	$-\sigma_i$	$-\lambda_j$	$-\lambda_k$	$+\lambda_o$	$+\lambda_i$	$+\gamma_j$	$-\gamma_k$	$-\gamma_o$	$+\gamma_i$	$+\delta_j$	$+\delta_k$	$-\delta_o$	$-\delta_i$	$+\alpha_j$	$-\alpha_k$	$-\alpha_o$	$+\alpha_i$	$+\beta_j$	$+\beta_k$	$-\beta_o$	$-\beta_i$
$\mu_k$	$+\mu_k$	$-\mu_j$	$+\mu_i$	$+\mu_o$	$-\nu_k$	$+\nu_j$	$-\nu_i$	$+\nu_o$	$-\sigma_k$	$-\sigma_j$	$+\sigma_i$	$-\sigma_o$	$-\lambda_k$	$+\lambda_j$	$-\lambda_i$	$+\lambda_o$	$+\gamma_k$	$+\gamma_j$	$-\gamma_i$	$-\gamma_o$	$+\delta_k$	$-\delta_j$	$+\delta_i$	$-\delta_o$	$+\alpha_k$	$+\alpha_j$	$-\alpha_i$	$-\alpha_o$	$+\beta_k$	$-\beta_j$	$+\beta_i$	$-\beta_o$
$\nu_o$	$+\nu_o$	$+\nu_i$	$+\nu_j$	$+\nu_k$	$+\mu_o$	$-\mu_i$	$-\mu_j$	$-\mu_k$	$-\lambda_o$	$+\lambda_i$	$+\lambda_j$	$+\lambda_k$	$-\sigma_o$	$-\sigma_i$	$-\sigma_j$	$-\sigma_k$	$+\delta_o$	$-\delta_i$	$-\delta_j$	$-\delta_k$	$-\gamma_o$	$+\gamma_i$	$+\gamma_j$	$+\gamma_k$	$+\beta_o$	$-\beta_i$	$-\beta_j$	$-\beta_k$	$-\alpha_o$	$+\alpha_i$	$+\alpha_j$	$+\alpha_k$
$\nu_i$	$+\nu_i$	$-\nu_o$	$+\nu_k$	$-\nu_j$	$+\mu_i$	$+\mu_o$	$+\mu_k$	$-\mu_j$	$-\lambda_i$	$-\lambda_o$	$+\lambda_k$	$-\lambda_j$	$+\sigma_i$	$-\sigma_o$	$+\sigma_k$	$-\sigma_j$	$+\delta_i$	$+\delta_o$	$-\delta_k$	$+\delta_j$	$-\gamma_i$	$-\gamma_o$	$-\gamma_k$	$+\gamma_j$	$+\beta_i$	$+\beta_o$	$-\beta_k$	$-\beta_j$	$-\alpha_i$	$+\alpha_o$	$-\alpha_k$	$+\alpha_j$
$\nu_j$	$+\nu_j$	$-\nu_k$	$-\nu_o$	$+\nu_i$	$+\mu_j$	$-\mu_i$	$+\mu_o$	$+\mu_k$	$-\lambda_j$	$-\lambda_k$	$-\lambda_o$	$+\lambda_i$	$+\sigma_j$	$-\sigma_k$	$-\sigma_o$	$+\sigma_i$	$+\delta_j$	$+\delta_k$	$+\delta_o$	$-\delta_i$	$-\gamma_j$	$+\gamma_k$	$-\gamma_o$	$-\gamma_i$	$+\beta_j$	$+\beta_k$	$+\beta_o$	$-\beta_i$	$-\alpha_j$	$+\alpha_k$	$-\alpha_o$	$-\alpha_i$
$\nu_k$	$+\nu_k$	$+\nu_j$	$-\nu_i$	$-\nu_o$	$+\mu_k$	$+\mu_j$	$-\mu_i$	$+\mu_o$	$-\lambda_k$	$+\lambda_j$	$-\lambda_i$	$-\lambda_o$	$+\sigma_k$	$+\sigma_j$	$-\sigma_i$	$-\sigma_o$	$+\delta_k$	$-\delta_j$	$+\delta_i$	$+\delta_o$	$-\gamma_k$	$-\gamma_j$	$+\gamma_i$	$-\gamma_o$	$+\beta_k$	$-\beta_j$	$+\beta_i$	$+\beta_o$	$-\alpha_k$	$-\alpha_j$	$+\alpha_i$	$-\alpha_o$
$\alpha_o$	$+\alpha_o$	$-\alpha_i$	$-\alpha_j$	$-\alpha_k$	$-\beta_o$	$-\beta_i$	$-\beta_j$	$-\beta_k$	$-\gamma_o$	$-\gamma_i$	$-\gamma_j$	$-\gamma_k$	$-\delta_o$	$-\delta_i$	$-\delta_j$	$-\delta_k$	$-\sigma_o$	$+\sigma_i$	$+\sigma_j$	$+\sigma_k$	$+\lambda_o$	$+\lambda_i$	$+\lambda_j$	$+\lambda_k$	$+\mu_o$	$+\mu_i$	$+\mu_j$	$+\mu_k$	$+\nu_o$	$+\nu_i$	$+\nu_j$	$+\nu_k$
$\alpha_i$	$+\alpha_i$	$+\alpha_o$	$-\alpha_k$	$+\alpha_j$	$-\beta_i$	$+\beta_o$	$+\beta_k$	$-\beta_j$	$-\gamma_i$	$+\gamma_o$	$+\gamma_k$	$-\gamma_j$	$+\delta_i$	$-\delta_o$	$-\delta_k$	$+\delta_j$	$-\sigma_i$	$-\sigma_o$	$-\sigma_k$	$+\sigma_j$	$-\lambda_i$	$+\lambda_o$	$+\lambda_k$	$-\lambda_j$	$-\mu_i$	$+\mu_o$	$+\mu_k$	$-\mu_j$	$+\nu_i$	$-\nu_o$	$-\nu_k$	$+\nu_j$
$\alpha_j$	$+\alpha_j$	$+\alpha_k$	$+\alpha_o$	$-\alpha_i$	$-\beta_j$	$-\beta_k$	$+\beta_o$	$+\beta_i$	$-\gamma_j$	$-\gamma_k$	$+\gamma_o$	$+\gamma_i$	$+\delta_j$	$+\delta_k$	$-\delta_o$	$-\delta_i$	$-\sigma_j$	$+\sigma_k$	$-\sigma_o$	$-\sigma_i$	$-\lambda_j$	$-\lambda_k$	$+\lambda_o$	$+\lambda_i$	$-\mu_j$	$-\mu_k$	$+\mu_o$	$+\mu_i$	$+\nu_j$	$+\nu_k$	$-\nu_o$	$-\nu_i$
$\alpha_k$	$+\alpha_k$	$-\alpha_j$	$+\alpha_i$	$+\alpha_o$	$-\beta_k$	$+\beta_j$	$-\beta_i$	$+\beta_o$	$-\gamma_k$	$+\gamma_j$	$-\gamma_i$	$+\gamma_o$	$+\delta_k$	$-\delta_j$	$+\delta_i$	$-\delta_o$	$-\sigma_k$	$-\sigma_j$	$+\sigma_i$	$-\sigma_o$	$-\lambda_k$	$+\lambda_j$	$-\lambda_i$	$+\lambda_o$	$-\mu_k$	$+\mu_j$	$-\mu_i$	$+\mu_o$	$+\nu_k$	$-\nu_j$	$+\nu_i$	$-\nu_o$
$\beta_o$	$+\beta_o$	$+\beta_i$	$+\beta_j$	$+\beta_k$	$+\alpha_o$	$-\alpha_i$	$-\alpha_j$	$-\alpha_k$	$-\delta_o$	$-\delta_i$	$-\delta_j$	$-\delta_k$	$+\gamma_o$	$+\gamma_i$	$+\gamma_j$	$+\gamma_k$	$-\lambda_o$	$+\lambda_i$	$+\lambda_j$	$+\lambda_k$	$-\sigma_o$	$-\sigma_i$	$-\sigma_j$	$-\sigma_k$	$-\nu_o$	$-\nu_i$	$-\nu_j$	$-\nu_k$	$+\mu_o$	$+\mu_i$	$+\mu_j$	$+\mu_k$
$\beta_i$	$+\beta_i$	$-\beta_o$	$+\beta_k$	$-\beta_j$	$+\alpha_i$	$+\alpha_o$	$+\alpha_k$	$-\alpha_j$	$-\delta_i$	$+\delta_o$	$-\delta_k$	$+\delta_j$	$-\gamma_i$	$+\gamma_o$	$-\gamma_k$	$+\gamma_j$	$-\lambda_i$	$-\lambda_o$	$+\lambda_k$	$-\lambda_j$	$+\sigma_i$	$-\sigma_o$	$+\sigma_k$	$-\sigma_j$	$-\nu_i$	$+\nu_o$	$-\nu_k$	$+\nu_j$	$-\mu_i$	$+\mu_o$	$-\mu_k$	$+\mu_j$
$\beta_j$	$+\beta_j$	$-\beta_k$	$-\beta_o$	$+\beta_i$	$+\alpha_j$	$-\alpha_k$	$+\alpha_o$	$+\alpha_i$	$-\delta_j$	$+\delta_k$	$+\delta_o$	$-\delta_i$	$-\gamma_j$	$+\gamma_k$	$+\gamma_o$	$-\gamma_i$	$-\lambda_j$	$-\lambda_k$	$-\lambda_o$	$+\lambda_i$	$+\sigma_j$	$-\sigma_k$	$-\sigma_o$	$+\sigma_i$	$-\nu_j$	$+\nu_k$	$+\nu_o$	$-\nu_i$	$-\mu_j$	$+\mu_k$	$+\mu_o$	$-\mu_i$
$\beta_k$	$+\beta_k$	$+\beta_j$	$-\beta_i$	$-\beta_o$	$+\alpha_k$	$+\alpha_j$	$-\alpha_i$	$+\alpha_o$	$-\delta_k$	$-\delta_j$	$+\delta_i$	$+\delta_o$	$-\gamma_k$	$-\gamma_j$	$+\gamma_i$	$+\gamma_o$	$-\lambda_k$	$+\lambda_j$	$-\lambda_i$	$-\lambda_o$	$+\sigma_k$	$+\sigma_j$	$-\sigma_i$	$-\sigma_o$	$-\nu_k$	$+\nu_j$	$+\nu_o$	$-\nu_i$	$-\mu_k$	$+\mu_j$	$+\mu_o$	$-\mu_i$
$\gamma_o$	$+\gamma_o$	$+\gamma_i$	$+\gamma_j$	$+\gamma_k$	$+\delta_o$	$+\delta_i$	$+\delta_j$	$+\delta_k$	$+\alpha_o$	$-\alpha_i$	$-\alpha_j$	$-\alpha_k$	$-\beta_o$	$-\beta_i$	$-\beta_j$	$-\beta_k$	$-\mu_o$	$+\mu_i$	$+\mu_j$	$+\mu_k$	$+\nu_o$	$+\nu_i$	$+\nu_j$	$+\nu_k$	$-\sigma_o$	$-\sigma_i$	$-\sigma_j$	$-\sigma_k$	$-\lambda_o$	$-\lambda_i$	$-\lambda_j$	$-\lambda_k$
$\gamma_i$	$+\gamma_i$	$-\gamma_o$	$+\gamma_k$	$-\gamma_j$	$+\delta_i$	$-\delta_o$	$-\delta_k$	$+\delta_j$	$+\alpha_i$	$+\alpha_o$	$+\alpha_k$	$-\alpha_j$	$+\beta_i$	$-\beta_o$	$-\beta_k$	$+\beta_j$	$-\mu_i$	$-\mu_o$	$+\mu_k$	$-\mu_j$	$+\nu_i$	$-\nu_o$	$-\nu_k$	$+\nu_j$	$+\sigma_i$	$-\sigma_o$	$+\sigma_k$	$-\sigma_j$	$+\lambda_i$	$-\lambda_o$	$-\lambda_k$	$+\lambda_j$
$\gamma_j$																																