

Appendix SCPTS-RCLSEC-1-2021.

Re:- Derivation of Characteristic Formulae pertaining to an R-C-L Series Electrical Circuit.

For the purposes of deriving the aforesaid formulae, we shall accordingly enunciate the following theorem and concomitant definition:-

Theorem T-RCLSEC-1.

Let there exist an R-C-L series electrical circuit as indicated by Figs. 1 & 2 below. Hence, it may be proven that the resultant current, $I(t)$, generated by this particular circuit is accordingly expressed by the formula,

$$I(t) = (V_p/Z) \cos(\omega t + \phi),$$

insofar as the constants,

$$Z = \sqrt{(X_c - X_L)^2 + R^2}; \quad \cos(\phi) = (\frac{1}{C} - L\omega^2) / \sqrt{(\frac{1}{C} - L\omega^2)^2 + R^2\omega^2};$$

$$X_c = 1/C\omega = T_0/2\pi C; \quad \sin(\phi) = -R\omega / \sqrt{(\frac{1}{C} - L\omega^2)^2 + R^2\omega^2}.$$

$$X_L = L\omega = 2\pi L/T_0;$$

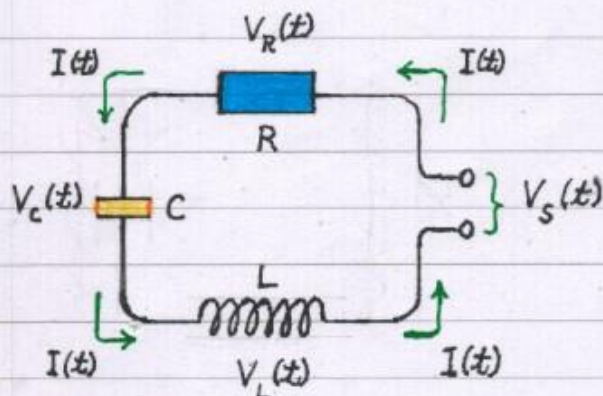


Fig. 1.

N.B.

(a) The symbols,

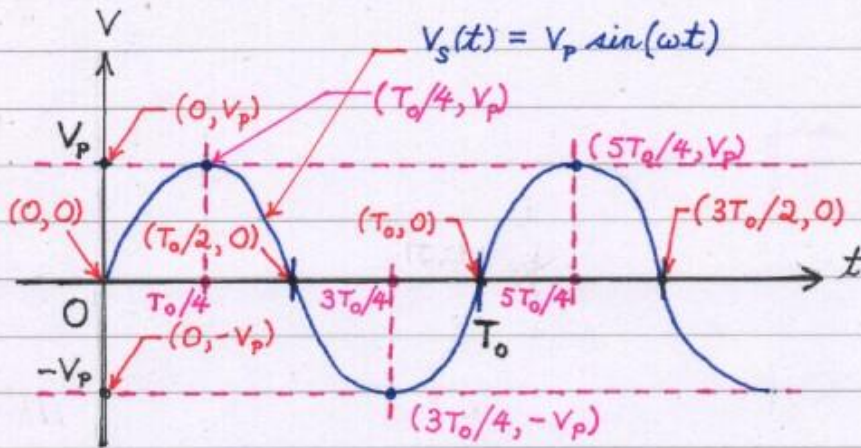
R = resistor (ohms); C = capacitor (farads); L = inductor (henrys).

(b) The voltages, [*]

$V_S(t) = V_p \sin(\omega t)$; $V_R(t) = RI(t)$;

$V_C(t) = Q(t)/C$; $V_L(t) = L \frac{dI(t)}{dt}$.

[*] By definition, 1 volt = 1 joule/coulomb.



Graph of Supply Voltage, $V_s(t)$, vs. Time, t (secs).

N.B.

- (a) The constant, V_p , denotes the peak voltage corresponding to the function, $V_s(t)$.
- (b) The constant, T_0 , denotes the periodicity of the function, $V_s(t)$.
- (c) The constant, $\omega = 2\pi/T_0$, denotes the frequency corresponding to the function, $V_s(t)$.

[*] Expressed in Hertz, Hz (= cycles/sec).

Fig. 2.



PROOF:-

With reference to Figs. 1 & 2 depicted in the preamble to this proof, we recall from Kirchoff's Laws (cf. web-page article [1] & Boyce & DiPrima [2]) the following definitive formula, namely -

The supply voltage of the circuit = the voltage drop over the resistor, R , +
the voltage drop over the capacitor, C , +
the voltage drop over the inductor, L ,

in other words -

$$V_S(t) = V_R(t) + V_C(t) + V_L(t)$$

$$\therefore V_p \sin(\omega t) = RI(t) + Q(t)/C + L \frac{d}{dt}(I(t))$$

$$\therefore L \frac{d}{dt}(I(t)) + RI(t) + Q(t)/C = V_p \sin(\omega t) \quad (1).$$

Since by definition the current function, $I(t)$, is the first derivative with respect to 't' of the charge function, $Q(t)$, i.e. -

$$I(t) = \frac{d}{dt}(Q(t)),$$

it automatically follows, after making the appropriate algebraic substitutions, that Eq.(1) can be rewritten as

$$L \frac{d}{dt} \left(\frac{d}{dt}(Q(t)) \right) + R \frac{d}{dt}(Q(t)) + Q(t)/C = V_p \sin(\omega t)$$

$$\therefore L \frac{d^2}{dt^2}(Q(t)) + R \frac{d}{dt}(Q(t)) + Q(t)/C = V_p \sin(\omega t) \quad (2a),$$

which by definition is a specific example of an inhomogeneous second order linear differential equation with respect to the function, $Q(t)$. (cf. Boyce & DiPrima [2]).

Now, in order to solve this particular differential equation, let us set the charge function,

$$Q(t) = A \sin(\omega t) + B \cos(\omega t) \quad (2b),$$

where A and B are arbitrary constants, whose values have yet to be determined. Subsequently, in view of Eq.(2b), we deduce that Eq.(2a) can likewise be rewritten as

$$L \frac{d^2}{dt^2} (A \sin(\omega t) + B \cos(\omega t)) + R \frac{d}{dt} (A \sin(\omega t) + B \cos(\omega t)) + (1/C)(A \sin(\omega t) + B \cos(\omega t)) = V_p \sin(\omega t) \quad (3a).$$

From the established definitions and theorems pertaining to the calculus of real variable functions (cf. Salas & Einar Hille [31]) we accordingly deduce that

(a) the first derivative with respect to 't' of the charge function, Q(t),

$$\begin{aligned} \frac{d}{dt}(Q(t)) &= \frac{d}{dt}(A \sin(\omega t) + B \cos(\omega t)) = \frac{d}{dt}(A \sin(\omega t)) + \frac{d}{dt}(B \cos(\omega t)) \\ &= A \frac{d}{dt}(\sin(\omega t)) + B \frac{d}{dt}(\cos(\omega t)) = A\omega \cos(\omega t) - B\omega \sin(\omega t) \quad (3b); \end{aligned}$$

(b) the second derivative with respect to 't' of the charge function, Q(t),

$$\begin{aligned} \frac{d^2}{dt^2}(Q(t)) &= \frac{d^2}{dt^2}(A \sin(\omega t) + B \cos(\omega t)) = \frac{d}{dt}\left(\frac{d}{dt}(Q(t))\right) \\ &= \frac{d}{dt}(A\omega \cos(\omega t) - B\omega \sin(\omega t)) = \frac{d}{dt}(A\omega \cos(\omega t)) - \frac{d}{dt}(B\omega \sin(\omega t)) \\ &= A\omega \frac{d}{dt}(\cos(\omega t)) - B\omega \frac{d}{dt}(\sin(\omega t)) = -A\omega^2 \sin(\omega t) - B\omega^2 \cos(\omega t) \\ &= -(A\omega^2 \sin(\omega t) + B\omega^2 \cos(\omega t)) \quad (3c), \end{aligned}$$

and hence Eq. (3a) can similarly be rewritten in view of Eqs. (3b) & (3c) as

$$\begin{aligned} &-L(A\omega^2 \sin(\omega t) + B\omega^2 \cos(\omega t)) + R(A\omega \cos(\omega t) - B\omega \sin(\omega t)) + \\ &(1/C)(A \sin(\omega t) + B \cos(\omega t)) \\ &= V_p \sin(\omega t) \end{aligned}$$

$$\therefore -LA\omega^2 \sin(\omega t) - LB\omega^2 \cos(\omega t) + RA\omega \cos(\omega t) - RB\omega \sin(\omega t) + (A/C) \sin(\omega t) + (B/C) \cos(\omega t)$$

$$= V_p \sin(\omega t)$$

$$\therefore -LA\omega^2 \sin(\omega t) - RB\omega \sin(\omega t) + (A/C) \sin(\omega t) - LB\omega^2 \cos(\omega t) + RA\omega \cos(\omega t) + (B/C) \cos(\omega t)$$

$$= V_p \sin(\omega t)$$

$$\therefore [-LA\omega^2 - RB\omega + A/C] \sin(\omega t) + [-LB\omega^2 + RA\omega + B/C] \cos(\omega t)$$

$$= V_p \sin(\omega t) = V_p \sin(\omega t) + 0 \cdot \cos(\omega t) \quad (4).$$

From the left and right hand sides of Eq.(4) we accordingly perceive that the constant coefficients of $\sin(\omega t)$ & $\cos(\omega t)$ generate the pair of simultaneous equations,

$$-LA\omega^2 - RB\omega + A/C = V_p$$

$$-LB\omega^2 + RA\omega + B/C = 0$$

$$\therefore -LA\omega^2 + A/C - RB\omega = V_p$$

$$RA\omega - LB\omega^2 + B/C = 0$$

$$\therefore (-L\omega^2 + 1/C)A - R\omega B = V_p$$

$$R\omega A + (-L\omega^2 + 1/C)B = 0$$

$$\therefore (1/C - L\omega^2)A - R\omega B = V_p \quad (5a);$$

$$R\omega A + (1/C - L\omega^2)B = 0 \quad (5b).$$

By invoking the well-established Cramer's Rule for determinants from linear algebra, we similarly perceive that the required solutions of Eqs.(5a) & (5b)

in terms of the arbitrary constants, A and B, are therefore given by (cf. Florey [4]) -

$$A = \begin{vmatrix} V_p & -R\omega \\ 0 & (1/C - L\omega^2) \end{vmatrix} \mathcal{D}^{-1} \quad \& \quad B = \begin{vmatrix} (1/C - L\omega^2) & V_p \\ R\omega & 0 \end{vmatrix} \mathcal{D}^{-1},$$

where the denominator, $\mathcal{D} = \begin{vmatrix} (1/C - L\omega^2) & -R\omega \\ R\omega & (1/C - L\omega^2) \end{vmatrix},$

$$\therefore A = (V_p(1/C - L\omega^2)) / ((1/C - L\omega^2)^2 + R^2\omega^2) \quad (6a) \quad \&$$

$$B = -(V_p R\omega) / ((1/C - L\omega^2)^2 + R^2\omega^2) \quad (6b).$$

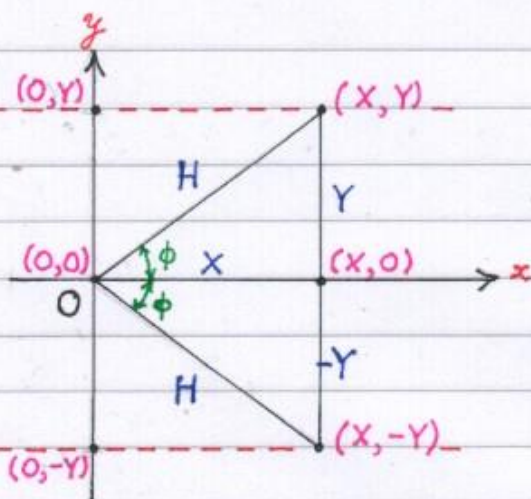


Fig. 3.

N.B.

(a) $X = 1/C - L\omega^2;$

(b) $Y = R\omega \implies -Y = -R\omega;$

(c) By virtue of Pythagoras's Theorem, the resultant hypotenuse,

$$H = \sqrt{X^2 + Y^2} = \sqrt{X^2 + (-Y)^2} \\ = \sqrt{(1/C - L\omega^2)^2 + R^2\omega^2};$$

(d) By definition, the trigonometric ratios,

$$\cos(\phi) = X/H \quad \& \quad \sin(\phi) = \pm Y/H.$$

With reference to Fig. 3 depicted above, it furthermore follows from Eqs. (6a) & (6b) that the constants,

$$A = V_p(1/C - L\omega^2) / (\sqrt{(1/C - L\omega^2)^2 + R^2\omega^2})^2$$

$$= (V_p / \sqrt{(1/C - L\omega^2)^2 + R^2\omega^2}) ((1/C - L\omega^2) / \sqrt{(1/C - L\omega^2)^2 + R^2\omega^2})$$

$$= (V_p / \sqrt{(1/C - L\omega^2)^2 + R^2\omega^2}) \cos(\phi)$$

$$= (V_p / \sqrt{\omega^2 [(1/\omega^2)(1/C - L\omega^2)^2 + R^2]}) \cos(\phi)$$

$$= (V_p / \omega \sqrt{(1/\omega^2)(1/C - L\omega^2)^2 + R^2}) \cos(\phi)$$

$$= (V_p / \omega \sqrt{[(1/\omega)(1/C - L\omega^2)]^2 + R^2}) \cos(\phi)$$

$$= (V_p / \omega \sqrt{(1/C\omega - L\omega)^2 + R^2}) \cos(\phi) \quad (7a) \quad \&$$

$$B = (V_p (-R\omega)) / (\sqrt{(1/C - L\omega^2)^2 + R^2\omega^2})^2$$

$$= (V_p / \sqrt{(1/C - L\omega^2)^2 + R^2\omega^2}) (-R\omega / \sqrt{(1/C - L\omega^2)^2 + R^2\omega^2})$$

$$= (V_p / \sqrt{(1/C - L\omega^2)^2 + R^2\omega^2}) \sin(\phi)$$

$$= (V_p / \sqrt{\omega^2 [(1/\omega^2)(1/C - L\omega^2)^2 + R^2]}) \sin(\phi)$$

$$= (V_p / \omega \sqrt{(1/\omega^2)(1/C - L\omega^2)^2 + R^2}) \sin(\phi)$$

$$= (V_p / \omega \sqrt{[(1/\omega)(1/C - L\omega^2)]^2 + R^2}) \sin(\phi)$$

$$= (V_p / \omega \sqrt{(1/C\omega - L\omega)^2 + R^2}) \sin(\phi) \quad (7b)$$

Let there exist a constant,

$$Z = \sqrt{(X_c - X_L)^2 + R^2}$$

such that the constants,

$$X_c = 1/C\omega = T_0/2\pi C \quad \& \quad X_L = L\omega = 2\pi L/T_0,$$

whereupon we subsequently deduce after making the appropriate algebraic

substitutions into Eqs. (7a) & (7b) that the constant coefficients,

$$A = (V_p/Z\omega) \cos(\phi) \quad \& \quad B = (V_p/Z\omega) \sin(\phi).$$

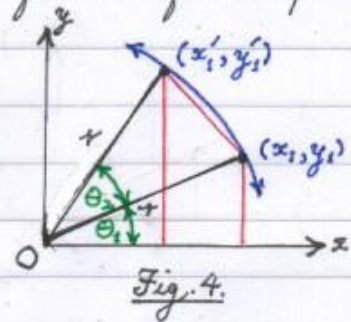
Finally, in view of the preceding statements, we conclude that the charge function,

$$\begin{aligned} Q(t) &= (V_p/Z\omega) \cos(\phi) \sin(\omega t) + (V_p/Z\omega) \sin(\phi) \cos(\omega t) \\ &= (V_p/Z\omega) (\cos(\phi) \sin(\omega t) + \sin(\phi) \cos(\omega t)) \\ &= (V_p/Z\omega) (\sin(\omega t) \cos(\phi) + \cos(\omega t) \sin(\phi)) \\ &= (V_p/Z\omega) \sin(\omega t + \phi), \end{aligned}$$

bearing in mind the well established trigonometric formula for compound angles, namely (cf. Fig. 4) -

$$\sin(\theta_1 + \theta_2) = \sin(\theta_1) \cos(\theta_2) + \cos(\theta_1) \sin(\theta_2),$$

and hence the resultant current function,



$$\begin{aligned} I(t) &= \frac{d}{dt}(Q(t)) = \frac{d}{dt} [(V_p/Z\omega) \sin(\omega t + \phi)] = (V_p/Z\omega) \frac{d}{dt} (\sin(\omega t + \phi)) \\ &= (V_p/Z\omega) \omega \cos(\omega t + \phi) = (V_p/Z) \cos(\omega t + \phi), \end{aligned}$$

insofar as the constants,

$$Z = \sqrt{(X_c - X_L)^2 + R^2}; \quad X_c = 1/C\omega = T_0/2\pi C; \quad X_L = L\omega = 2\pi L/T_0;$$

$$\cos(\phi) = (1/C - L\omega^2) / \sqrt{(1/C - L\omega^2)^2 + R^2\omega^2};$$

$$\sin(\phi) = -R\omega / \sqrt{(1/C - L\omega^2)^2 + R^2\omega^2},$$

as required. Q.E.D. [*]

[*] N.B.

The acronym 'Q.E.D.' denotes the Latin phrase, 'Quod erat demon-
strandum', which precisely translates as 'That (thing), which had to
be proven' and is commonly utilised by many mathematicians to
signify the completion of the proof of any given theorem.

Definition D-RCLSEC-1.

With regard to the contents of Theorem T-RCLSEC-1 we accordingly
observe that

(a) the constant,

$$X_c = 1/C\omega = T_0/2\pi C,$$

denotes the capacitive reactance of the circuit depicted in Fig. 1 [*];

(b) the constant,

$$X_L = L\omega = 2\pi L/T_0,$$

denotes the inductive reactance of the circuit depicted in Fig. 1 [*];

(c) the resultant difference between X_L and X_c ,

$$X_{(L,C)} = X_L - X_c,$$

denotes the total reactance of the circuit depicted in Fig. 1 [*];

(d) the constant,

$$Z = \sqrt{(X_c - X_L)^2 + R^2} = \sqrt{R^2 + (X_L - X_c)^2} = \sqrt{R^2 + X_{(L,C)}^2}$$

$$= |Z[C]| = |R + jX_{(L,C)}|, \quad (\text{N.B. The imaginary number, } j = \sqrt{-1} \in \mathbb{C}, \text{ the set of complex numbers.})$$

denotes the impedance of the circuit depicted in Fig. 1 [*].

[*] Measurements expressed in ohms as indicated in web-page article [5].

BIBLIOGRAPHY.

- [1] Wikipedia; Kirchoff's Circuit Laws (viz. https://en.wikipedia.org/wiki/Kirchoff%27s_circuit_laws).
- [2] W. E. Boyce & R. C. DiPrima; Elementary Differential Equations and Boundary Value Problems (3rd Edition); John Wiley & Sons Inc., New York, USA.
- [3] S. L. Salas & Einar Hille; Calculus - One and Several Variables (3rd Edition); John Wiley & Sons Inc., New York, USA.
- [4] F. G. Florey; Elementary Linear Algebra with Applications; Prentice-Hall Inc., New Jersey, USA.
- [5] Wikipedia; Electrical Reactance (viz. https://en.wikipedia.org/wiki/Electrical_reactance).

Stephen C. Pearson
STEPHEN. C. PEARSON.

1st December 2021.

[END OF PAPER – THIS PAGE HAS BEEN INTENTIONALLY LEFT BLANK.]