

# A further analysis of the possible phenomenon of energy changing dimension using the generalised Lagrangian operator

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## Abstract

The main assumption here is that a rotation through any angle(s) is a change in dimension. Also that operating on the structure of energy can alter the space of dimension. The matrix operator Q is related to the choice function E or B. Using ideas from previous papers the very structure of a particle is a logical entity and here is represented by matrices. A change in energy is a change in the number of variables of space(time). This may mean that the number of rows in the structure of a particle is a redundant energy, contributing to entropy.

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*Introduction:* Often the most interesting math is done on nxn matrices and this implies a symmetric structure of particles. A simple example of the rotation operator P will be given. Su(n) matrices are crucial in quantum mechanics. Here there may be further connections between angular momentum or energy and the very structure of logic – a possible path to the connection between operators and the structure of space – time.

The first result is simply applying a rotation operator to produce an entropy. The second is an operator which manipulates the number of columns (hence spatial – temporal dimensions) and rows in a matrix / tensor. Here mostly matrices are used.

Results: The basic principle of the first result is that of a rotation operator. For a simple rotation we have for matrices X and X':

$$X' = P X.$$

Writing this in terms of Anti – information: That is  $A = X - BX$  where B is a choice function such that this implies Information – logic ( where logic is BX) , we have:

$$X' - PX = A$$

Now to write as an entropy dS:

$$dS = A/x$$

Where 1/x is an inversion (duality). In matrix notation:

$$dS_B = \{ [X'] - B [X] \} Y^{-1}$$

$$dS_P = \frac{1}{x} \{ [X'] - P[X] \}$$

NB the two inverted terms are related. Also energy is an inverse length. Now equating the fraction A/x as entropy. That is

$$E_k = T dS$$

Here :

$E_k$  is used for energy and  $E$  for choice. (mistake in previous paper.)

If  $dS$  does not change, for a constant temperature then the energy does not change. Thus for total Entropy:

$$dS = dS_B \pm dS_P$$

Applying the inversion  $1/x$  we have a new matrix:

$$X'' - BX'$$

Such that this can be written as the characteristic equation

$$X - \lambda I$$

We may be able to construe  $P$  and  $B$  as frequency  $f$  and period  $T$  so that :

$$x = vt$$

And for a constant velocity:

$$P = B = f \text{ but } P P^{-1} = I$$

Now a zero change in energy is a zero change in the structure.

$$dS_B = dS_P = 0$$

But solutions exist for the matrices only if.

$$\det(X - \lambda I) = 0$$

So applying operators gives Lambda terms.

NB for no rotation we have:

$$P = B = I \text{ so that } X' = I X$$

And this implies no rotation means no change in energy. ( unless a dimension is changed – see later) Also  $B$  can be construed as the number of bits required ( see entropy as logarithm)

Also we may be able to write entropy as the number of paths through the matrix/ tensor:

$$dS = \frac{N - BN}{x^n x^{n'}}$$

Thus :

$$dS = \frac{N - BN}{x^n x^{n'}} = \frac{E}{T} = \frac{m x_i f_j^2}{T}$$

Using an iteration:

$$E_{i+1} = E_i(X' - PX)Y^{-1}$$

And again energy as an inverse length such as:

$$E_k = \frac{hc}{x}$$

Again for rotations:

$$E_k = \frac{1}{2} m r^2 \dot{\theta}^2$$

This sums up a possible mechanism - with further analysis - of energy changing dimension (rotation). We now look at an operator :

*Q and Q<sup>T</sup>*

Which adds or subtracts elements:

Here:

$$Q^T X_{ij} = X_{ij} \pm P_{KL} = A_{KL}$$

And:

$$Q A_{KL} = A_{KL} \pm P_{KL} = X_{ij}$$

Such that, for example - for a matrix:

$$Q \begin{matrix} & & & A_{KL} = \\ & a_{11} & a_{12} & a_{13} \\ & a_{21} & \dots & \dots \\ & a_{31} & a_{32} & a_{33} \end{matrix}$$

and for matrix:

$$P_{KL} = \begin{matrix} & & & \\ - & - & P_{13} & \\ - & - & P_{23} & \\ P_{31} & P_{32} & P_{33} & \end{matrix}$$

We have:

$$X_{ij} = \begin{matrix} & & & \\ = & a_{11} & a_{12} & \\ & a_{21} & a_{22} & \end{matrix}$$

Such that elements are removed or added to produce a matrix of different size. Now this relates to the Generalised Lagrangian operator as:

$$[E \pm B] \{X_{ij} \pm P_{KL}\} = A_{KL}$$

Where:

$$[E \pm B] \rightarrow Q^T$$

And

$$[E \pm B] \rightarrow Q$$

And:

$$[E \pm B]\{A_{KL} \pm P_{KL}\} = X_{ij}$$

Here we are primarily concerned with the number of columns  $n$  in an  $m \times n$  matrix – that is the dimension of space (time) . ie  $j$  and  $L$  but we treat the extra (or subtracted) rows as a change in entropy , hence energy.

Thus for a given volume:

$$x^n x^{n'}$$

There can be hidden information/energy – thus applying:

$$Q \text{ and } Q^T$$

We can change either energy/ dimensions or both.

$$Q \rightarrow Q^T \rightarrow [E \pm B]\{P, C, I, A \dots\}$$

(see previous papers)

Now, for example with a change in time:

$$\frac{\partial}{\partial t} [E \pm B]\{X_{ij} \pm P_{KL}\} = X_{ij}$$

And:

$$\frac{\partial}{\partial t} [E \pm B]\{A_{KL} \pm P_{KL}\} = A_{KL}$$

Where the logic can be extended - thus a time rate of change returns the original matrix. NB the implications.

Also for a further analysis:

$$\frac{\partial}{\partial t} E_k \Delta t \rightarrow \frac{\partial}{\partial t} [E \pm B]\{X_{ij} + P_{KL}\} \Delta t$$

References:

Anton, H., Rorres, c., Elementary linear algebra. Eighth Edition.

John Wiley and sons, 2000. (see pge 328 for an example

On rotations).