

4/17/2020

①

The realist position holds that it is possible for a law to be found precisely. This supposes a hidden variable!

The Copenhagen position holds that it is the act of observation that produces a definite position.

It is possible that both views are true - logically that is that the act of producing a position is a

decision.

essentially that length can both vary and remain constant; simultaneous.

John Peed
[Signature]

The mathematical argument
is that curves are
self evident. (8)

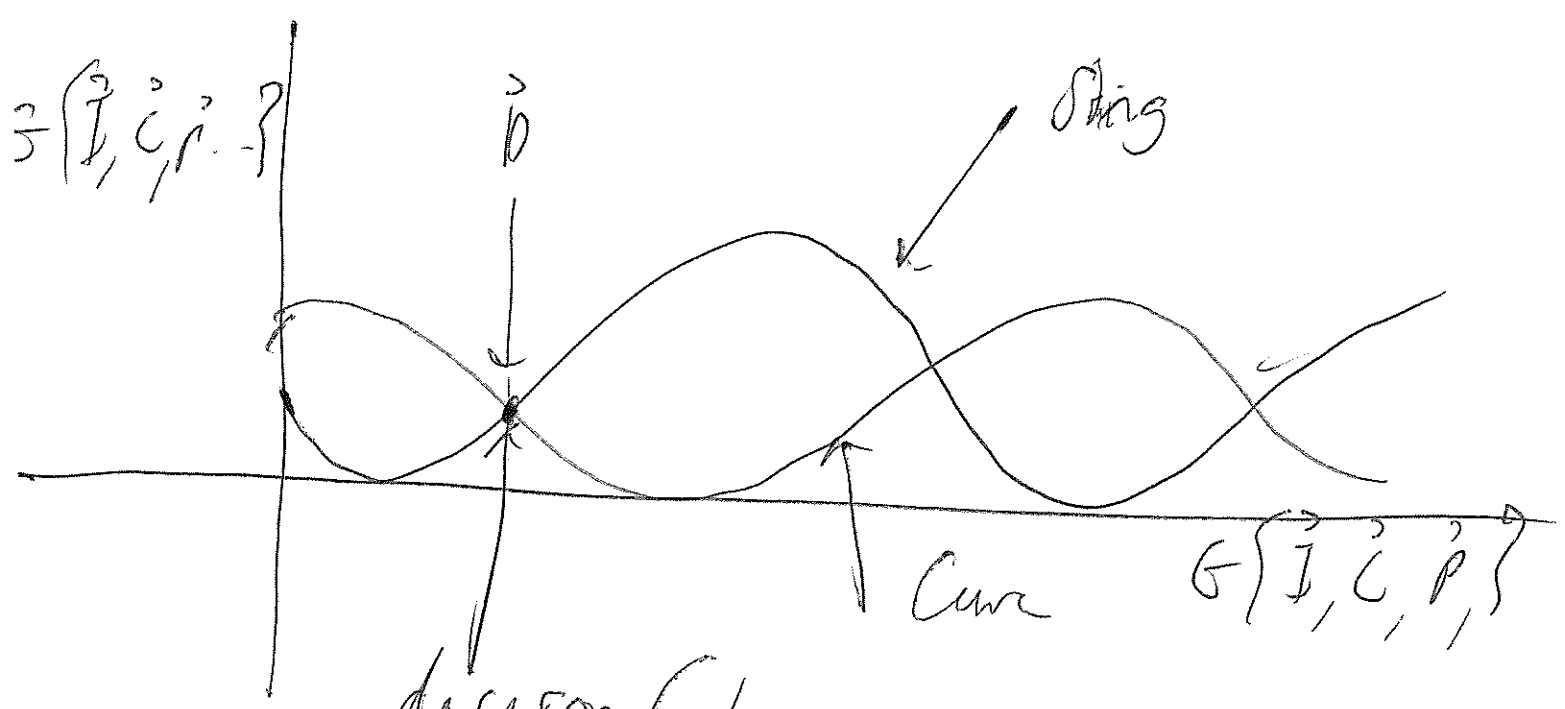
That is a thing (large
or quantum) is a type
of curve or a curve
is a logical construct.

The argument that measurement
is a decision rests on
the concept of the infinite.

In previous pages I
have expanded the following

Curve's rule & curve's rule

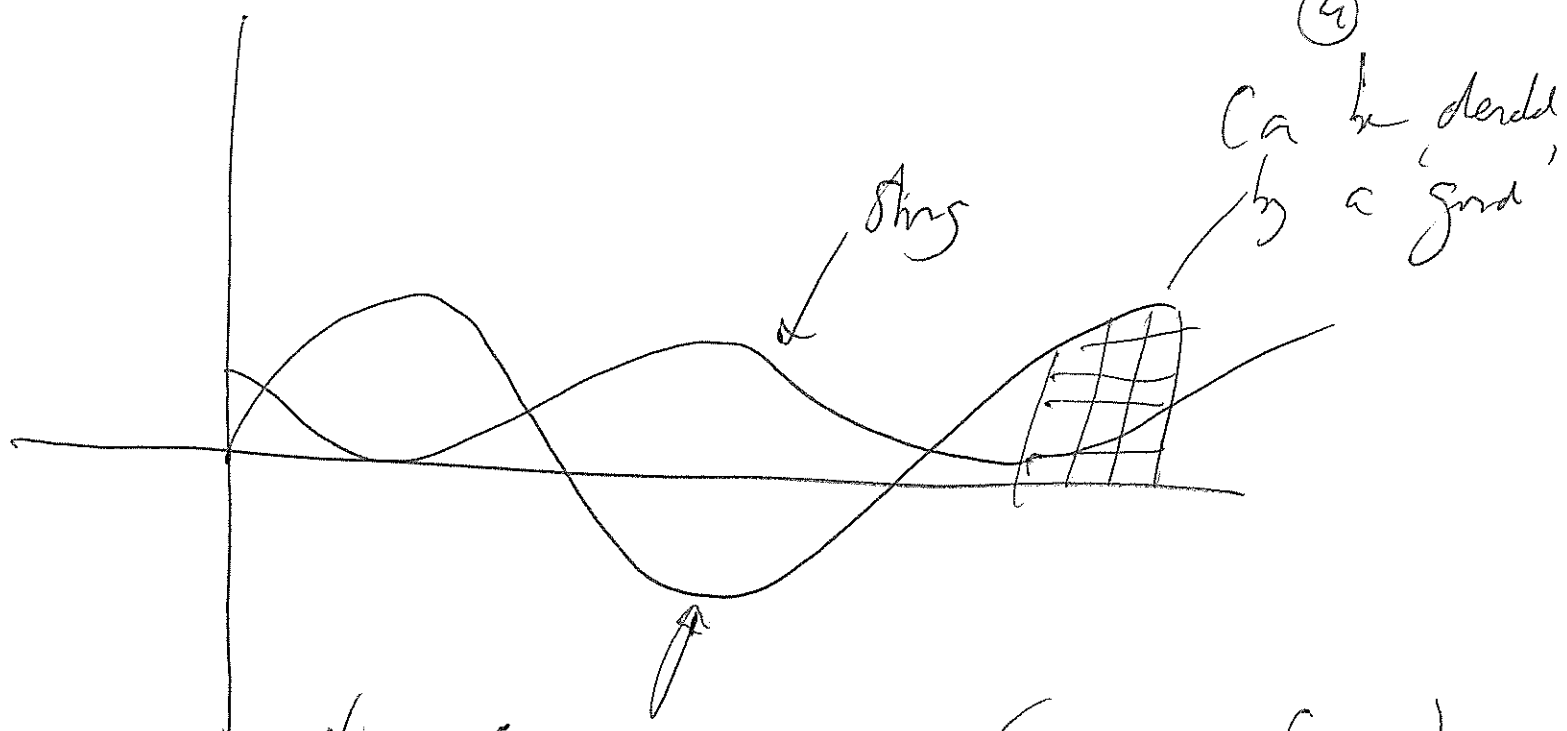
Thus this is the concept
of a string / buy a
Curve.



decision (logical
'deciding' on a parameter
'decision' is decided by

A
D

④



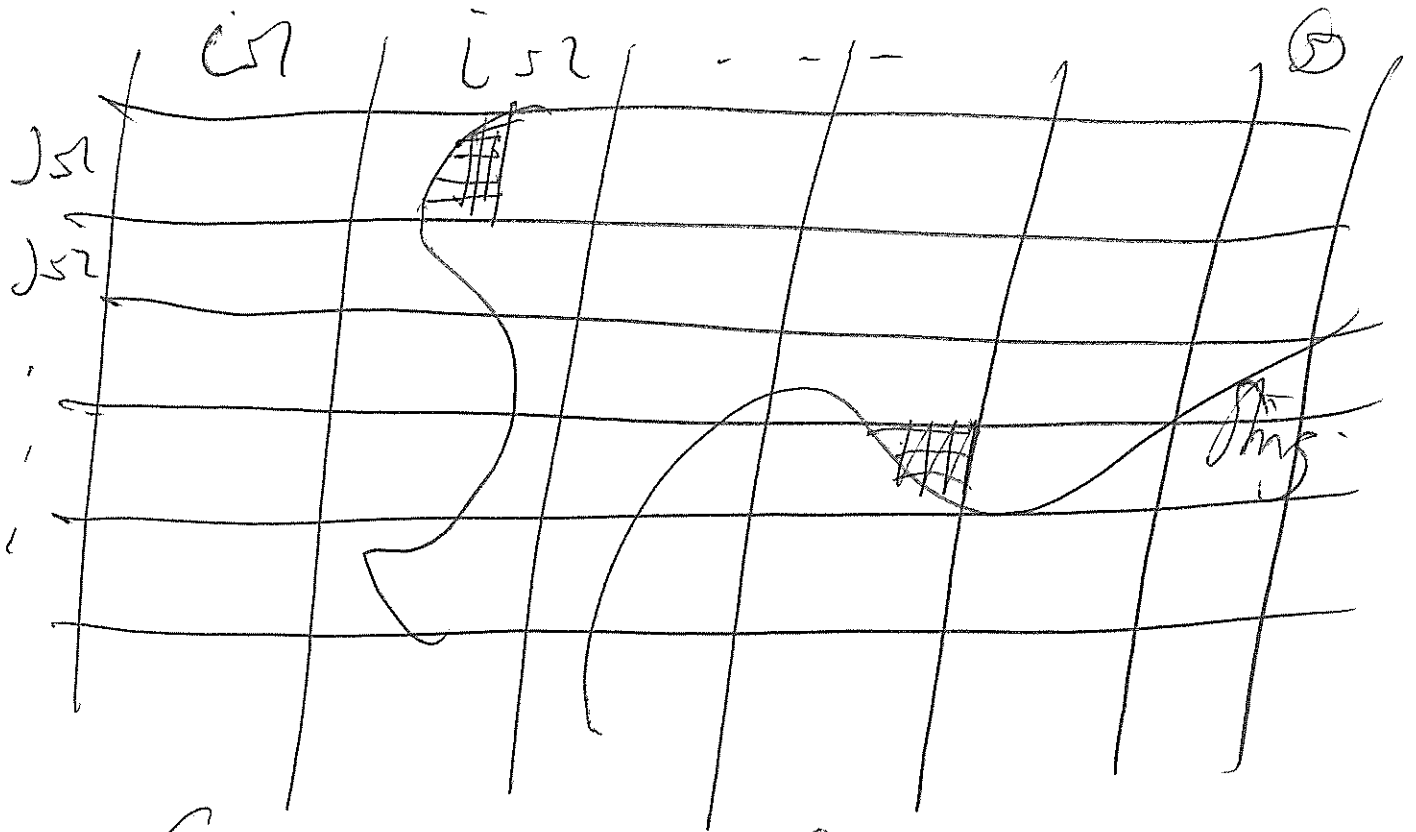
ψ is logical curve (wave function)

The probability is given

$$\text{by } P(\psi, \vec{D}), \quad P(\psi, R, \vec{I}, \vec{C} \dots)$$

when ψ and \vec{D} coincide a decision is made.

To illustrate how an equation can produce a curve and the wave we have

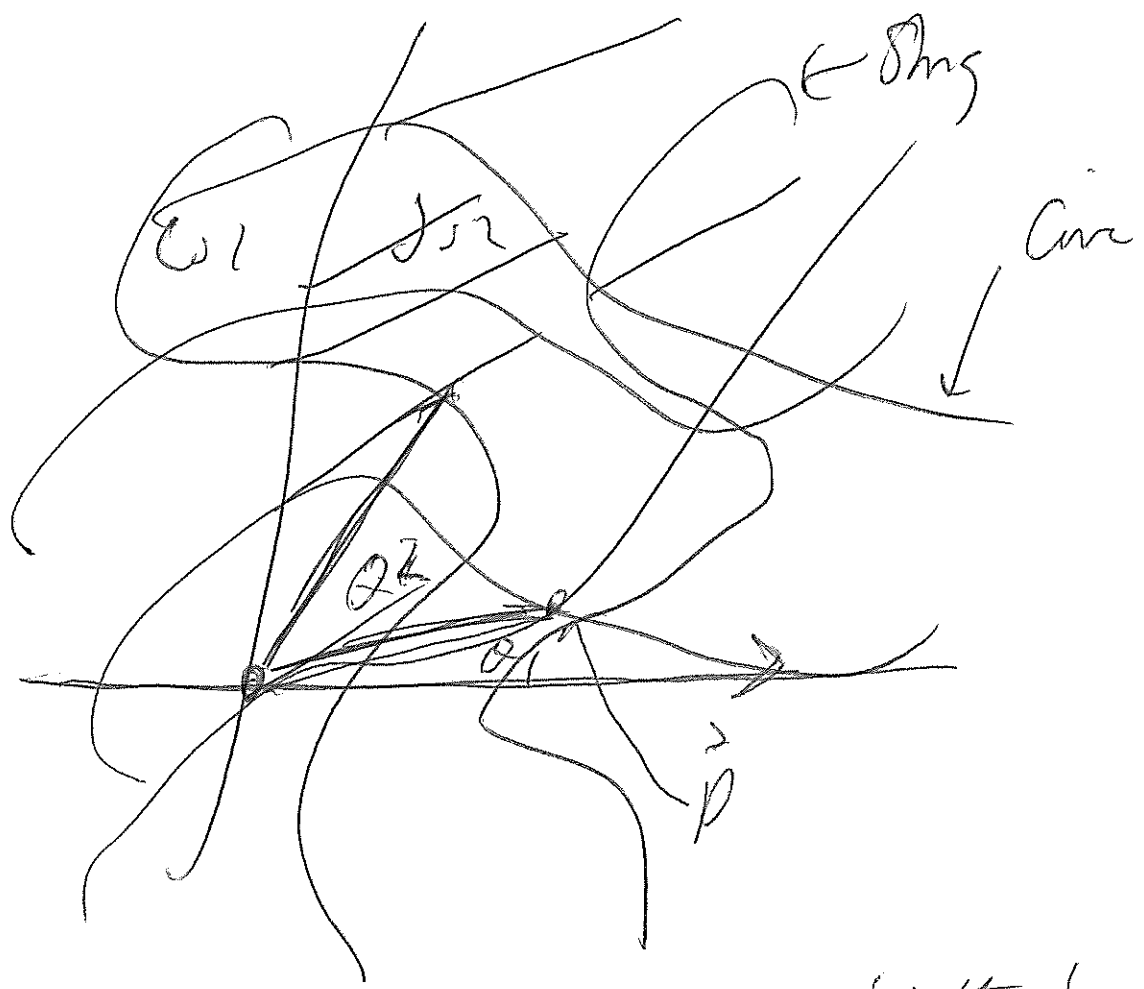


$\{c, j = 1, \dots, 10\}$ (each density).

density

$$c = \frac{N}{\text{Area}}$$

The grid (whole area) is explained later.

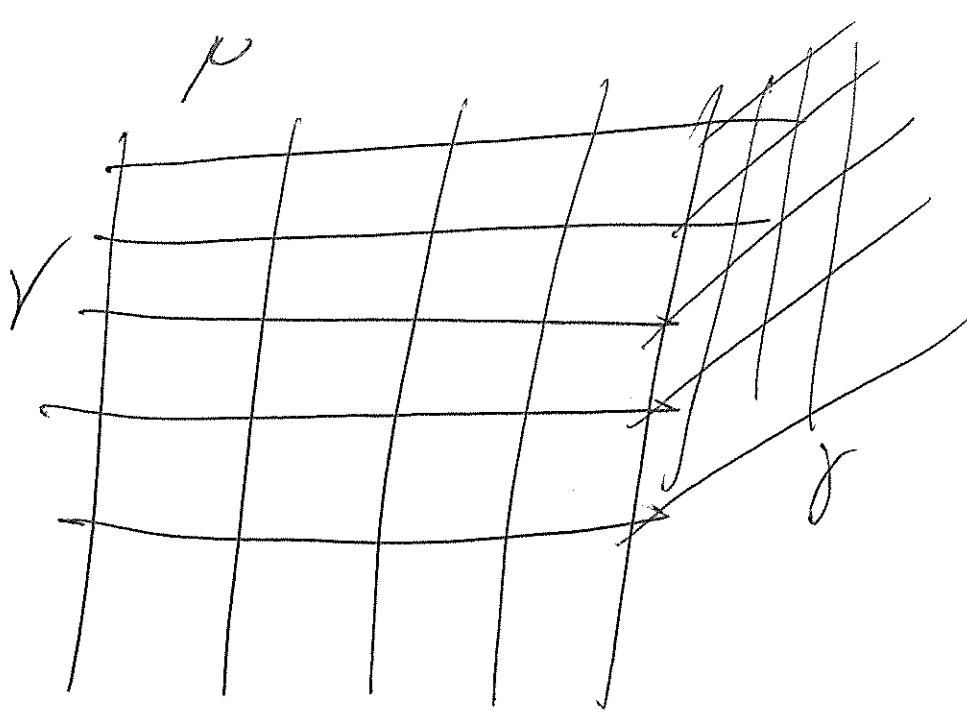


A diamond 'lattice'

May
 could
 curves can be
 as

$$\frac{\{ f(x)(x-d)^n \}}{n!}$$

for
 have
 elements we



(7)

a Jackson

$$\sum_{i=1}^n f_n(x^{\mu_i})$$

with also

f_n is dependent
 on Taylor series
 (NB differentiable)

And // as

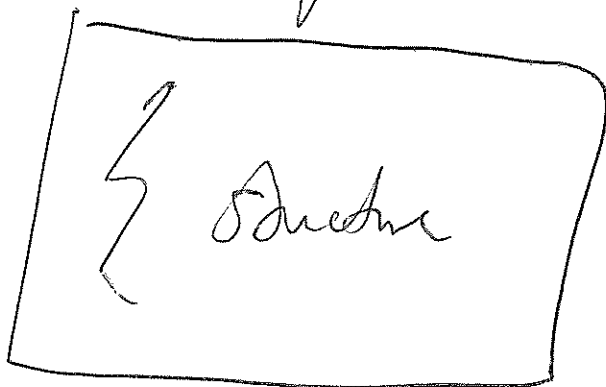
Can be written as
a sum

$$x^i = a_i$$

And a 'log' can

produce a log curve
(a eqn) (a sum)

So my problem is



Structure is a function
 $f_n(x^{a_i})$

Any any function ν ①

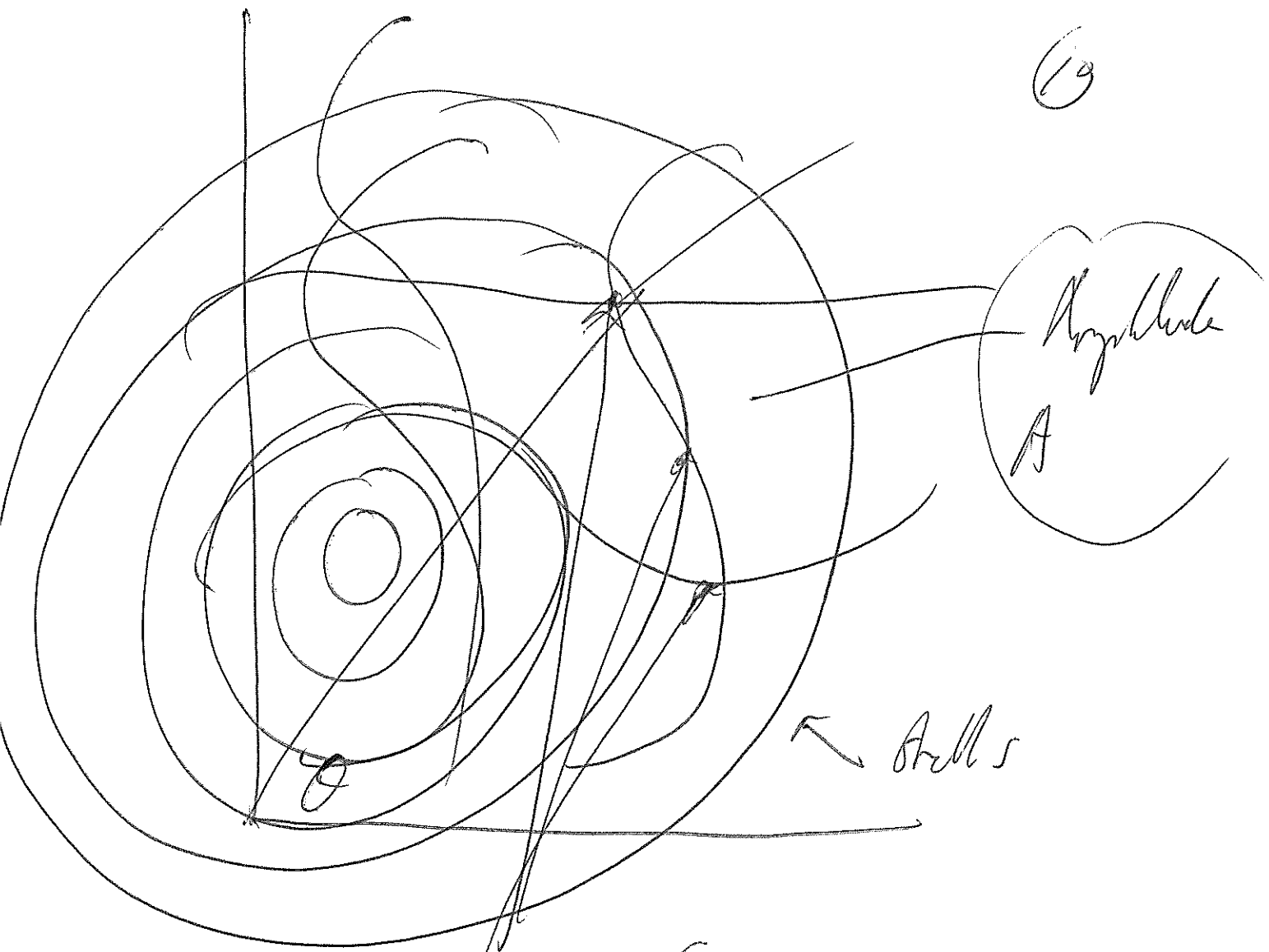
$$\{x^i, a\}$$

$$a \{i, i, i, i, \dots\}$$

Remember consumers \vec{c}
and the logical space \vec{I}
By and only

$$\{f(x^i)\} \rightarrow \{i, i, i\}$$

Thus a hidden variable
exists in \vec{I} or \vec{c}
or other space



decisions (and grounds)

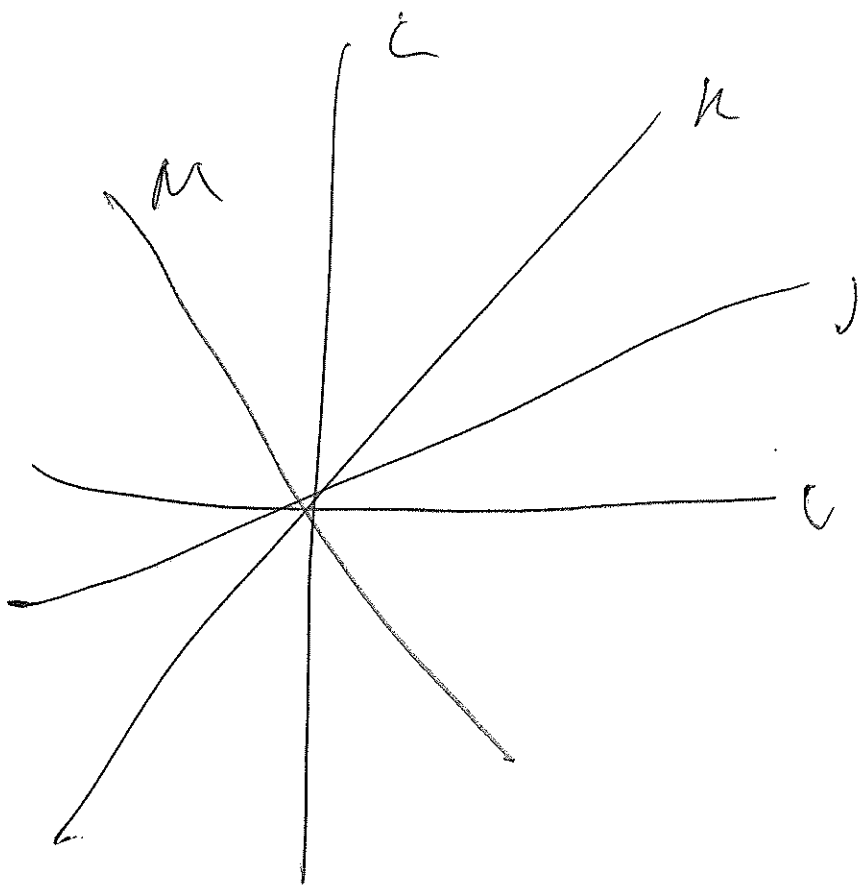
the model eqn "

$$D - n \{ \theta_i \text{ s.o.k.} \}$$

s constant μ_i

Now the variables that are involved in decisions →

the $\vec{D} \Rightarrow$ denser



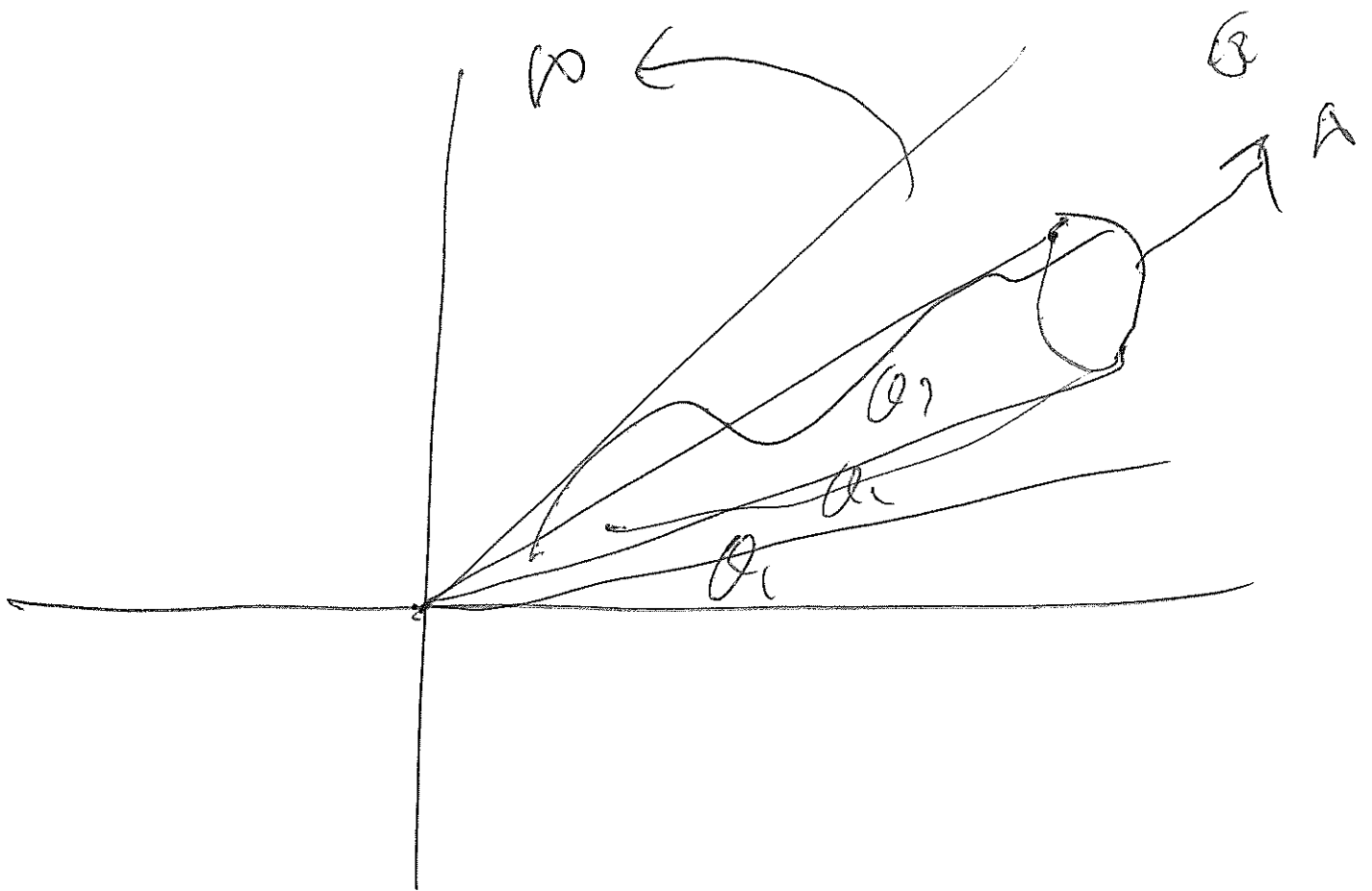
$\{C, J, K, \dots, M\}$

with \vec{D} downward.

NR

$$S_s \Delta r / \theta$$

$$\theta_s \frac{S}{\Delta r}$$



The assumption is that
 Q is both constant
and can vary.

for a downward axis

$$\{ n_i \leftrightarrow Q_i \}$$

a friction

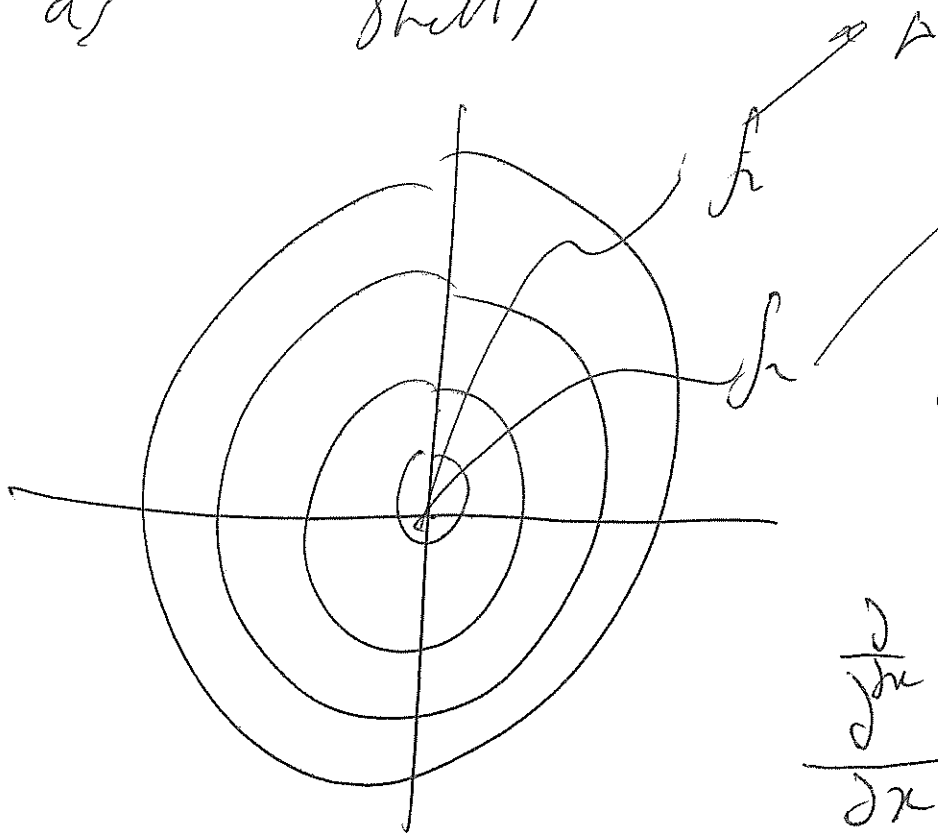
So for perfect factor,

where α

$$10 - n / \theta_i = P \alpha K$$

ρ constant

As can be written as 'shell'



$K_s / L_s = \alpha$
 $Y_s / S_{n\alpha}$

$$\frac{\partial}{\partial x} K_i = \frac{\partial}{\partial y} L_i \text{ s p. cost}$$

$$\frac{\partial}{\partial i} L_i = \frac{\partial}{\partial i} K_i \text{ s p. cost}$$

(15)

now

$$\frac{\partial}{\partial \theta} Q_c \leftrightarrow \frac{d^2}{d\omega^2} \infty.$$

This should be really
differentiable & physics

$$\left\{ \ln(x^{p^2}) \text{ can} \right.$$

be written as a

Taylor sum (logical equation)

$$\left\{ \rightarrow \text{Taylor} \left(\frac{d^i}{dx^i} \right) \right.$$

$$\frac{d}{dx} x - \frac{d}{dx} x_0 \theta \text{ s p}$$

$$\frac{d}{dx} x \text{ s } \sum \theta \text{ fraction}$$

Ans a bar 0
ans

$$\frac{d}{dx} x - \frac{d}{dx} x_0 \text{ s p}_1$$

$$x - \frac{d}{dx} x_0 \text{ s p}_2$$

$$x - \frac{d}{dx} x \text{ s p}_3$$

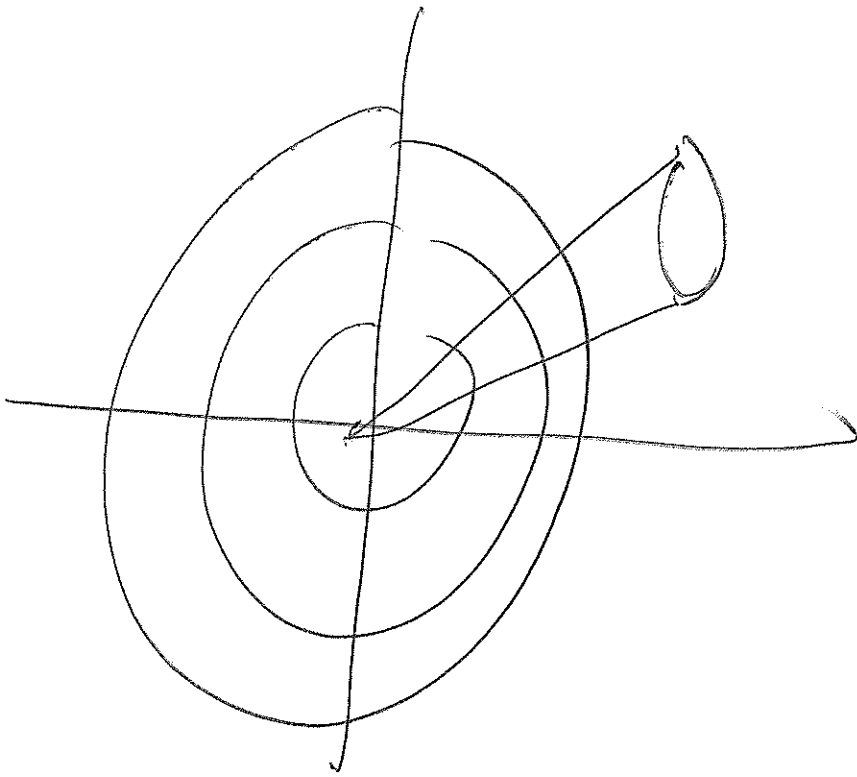
$$x_0 - x \text{ s p}_4$$

$$x_0 - \frac{d}{dx} x \text{ s p}_5$$

$$\frac{d}{dx} x - x \text{ s p}_6$$

Ans

69



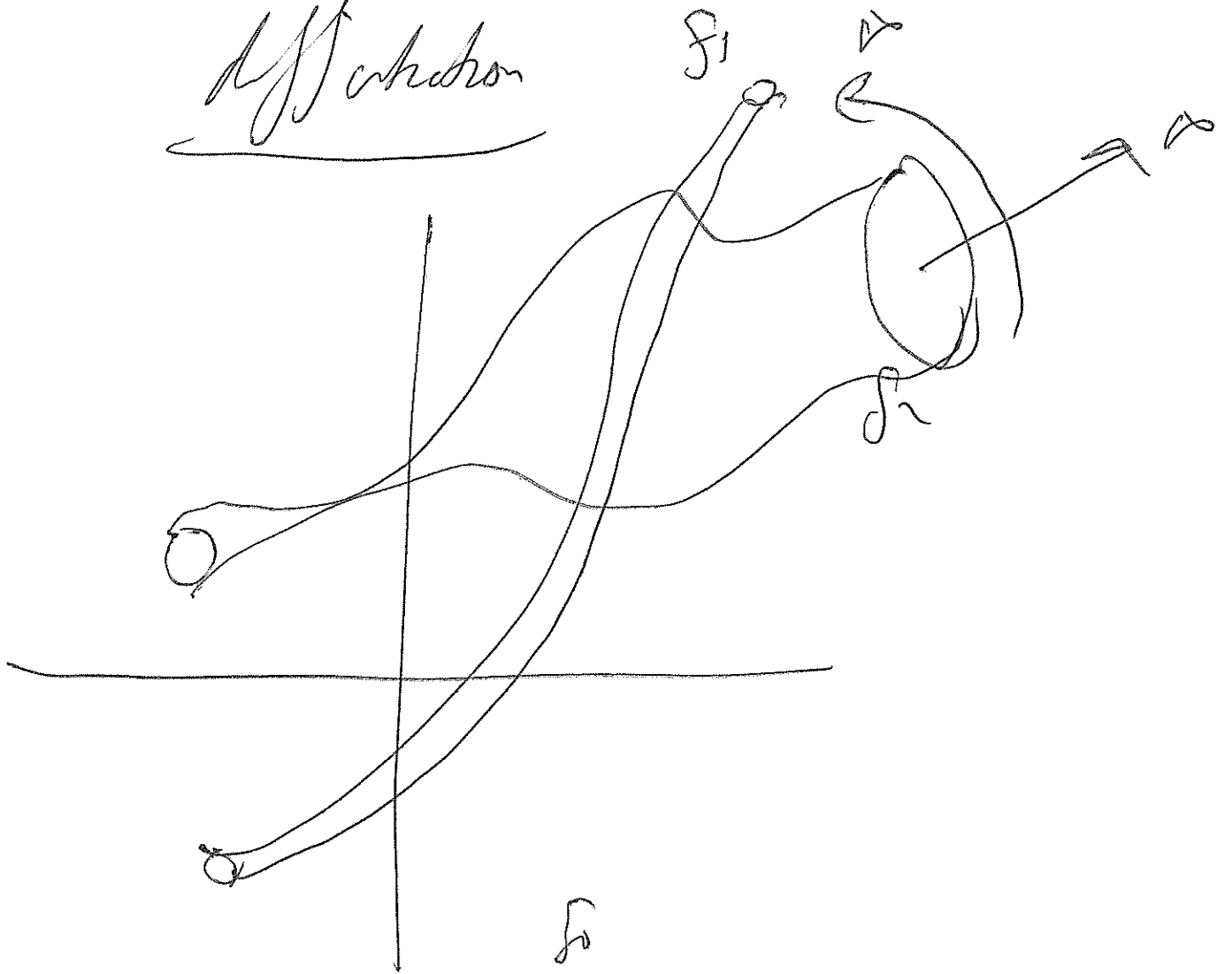
Ans varying angle and
keeping constant produces

n or r or θ etc

$$\frac{d\theta_c}{d\theta} = \frac{d\theta_s}{d\theta} = \frac{L}{r}$$

$$\frac{Q_0 - Q_i}{\Delta \theta} \approx K'(\theta)$$

Affektion



are $f_1 - f_2 \approx K$
 continuous

$$|K_{f_1} - K_{f_2}| < \delta$$

$$|f_1 - f_2| < \epsilon$$

$I_1 - I_2 = \Delta I$

(19)

$I_1 \text{ km} \rightarrow A$

Here ΔI is always

so unless length
but

$A - \text{km} \text{ s } \mu$

Sub that A is there

on $\text{km} \text{ s } \underline{a}$

A is many km

$\text{km} \text{ s } \text{there} \underline{\text{But}}$

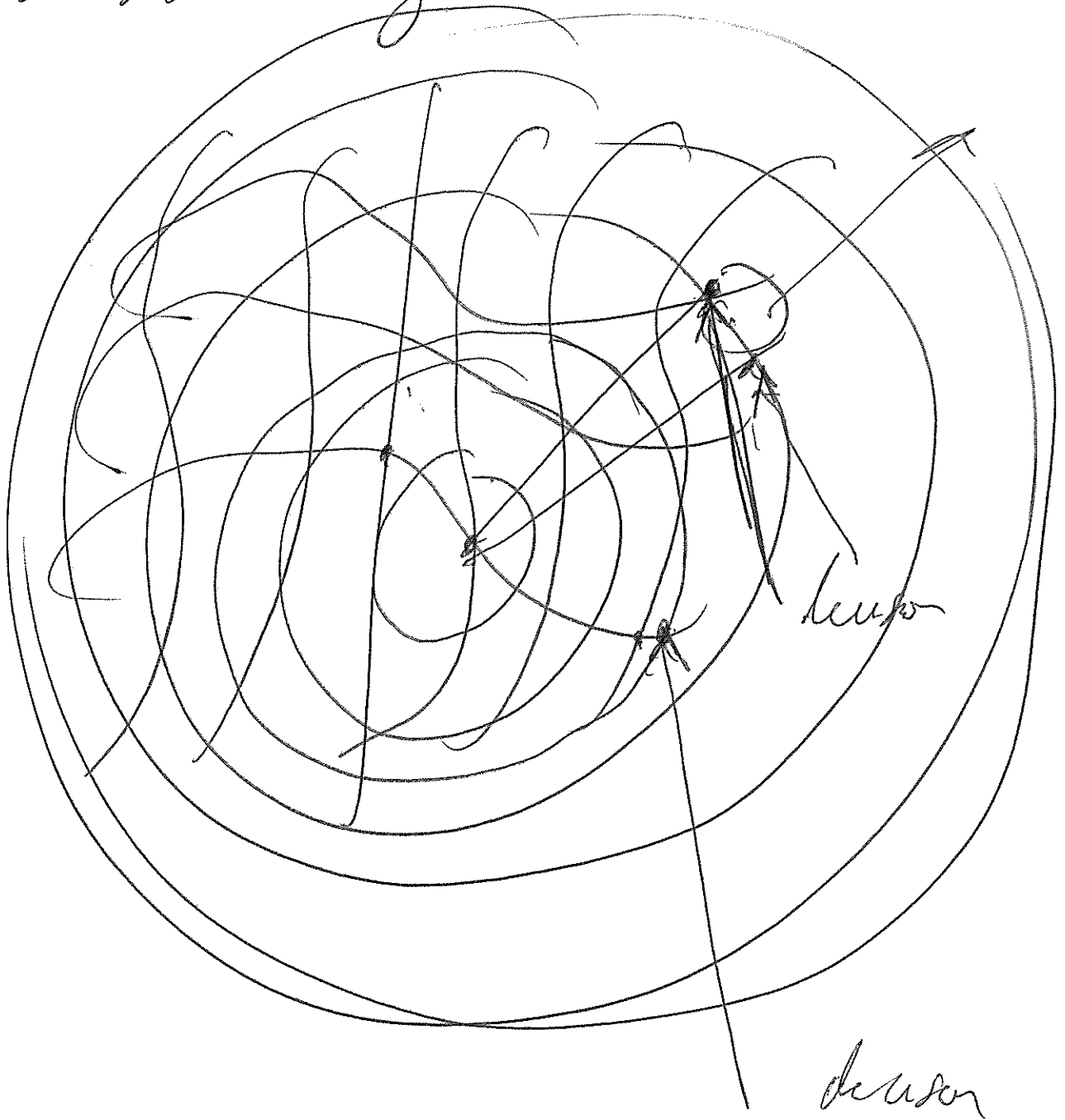
The description is both or done

Amo

$$10^5 - A_0 \cdot 5 \mu_i$$

Amo Amoy Am n

Amosad Am



Ans The notion that $h(\omega) - h(\omega_0)$ is both static and changing (varies) (20)

$$h(\omega) - h(\omega_0) = \mu$$

Thus the eqn is a decision

a core and the

strong (good) to a

logged only set

a decision is made in

the logic is that is

an infinite process

$$h(\omega) - h(\omega_0) = \mu$$

produces a constant which is an actual decision.

Chris

(23)

$$I_n(x^{p^i}) \mapsto h(x) - k(x^{p^i})_{sp}$$

where

$$\{ I_n(x^{p^i}) \} \text{ is a structure}$$

such that

$$\text{the structure is } \varphi$$

$$\text{or } \{ \text{Taylor} \}$$

Now with $x \in \mathbb{C}$
 $y \in \mathbb{C}$

So

was $\{x, y\}$ - the
 we have a position.

Plumber

One side is curved
exists in \vec{I} and

The position of corner
(corner) \vec{C} can alter
the shape of \vec{I} .

Thus there are better
variables, yielded in nature

$$\sin \theta, \cos \theta \in e^{i\theta}$$

which exist in the

set $\{ \vec{I}, \vec{P}, \vec{C}, \vec{D} \dots \}$

which itself is expressed in.
 \vec{P} = physical reality.