

Einstein-Whitehead model of GW 150914

by Lluís Bel (retired from CNRS, France)

A fully relativistic description of the encounter of 35 solar masses point-like objects, somehow mimicking the binary merger GW1508144 described by LIGO Scientific and VIRGO collaboration (Ann. Phys. (Berlin) 529, No 1-2)

!! Formulas for odevx, odevy, odevxp and odevyp have been corrected)
The Lagrangian and Hamiltonian used have been included.

```
> restart:
```

```
> with(tensor) :
```

```
# Whitehead Lagrangian 05/07/2019
```

```
> g[4,4]:=(-1+2*mp/r)*c^2;
```

$$g_{4,4} := \left(-1 + \frac{2 \, mp}{r} \right) c^2 \quad (1)$$

```
> g[4,1]:=(2*mp*x/r^2)*c;
```

$$g_{4,1} := \frac{2 \, mp \, x \, c}{r^2} \quad (2)$$

```
> g[4,2]:=(2*mp*y/r^2)*c;
```

$$g_{4,2} := \frac{2 \, mp \, y \, c}{r^2} \quad (3)$$

```
> g[4,3]:=(2*mp*z/r^2)*c;
```

$$g_{4,3} := \frac{2 \, mp \, z \, c}{r^2} \quad (4)$$

```
> g[1,1]:=1+2*mp*x^2/r^3;
```

$$g_{1,1} := 1 + \frac{2 \, mp \, x^2}{r^3} \quad (5)$$

```
> g[2,2]:=1+2*mp*y^2/r^3;
```

$$g_{2,2} := 1 + \frac{2 \, mp \, y^2}{r^3} \quad (6)$$

```
> g[3,3]:=1+2*mp*z^2/r^3;
```

$$g_{3,3} := 1 + \frac{2 \, mp \, z^2}{r^3} \quad (7)$$

```
> g[1,2]:=2*mp*x*y/r^3;
```

$$g_{1,2} := \frac{2 \, mp \, x \, y}{r^3} \quad (8)$$

```
> g[2,3]:=2*mp*y*z/r^3;
```

$$g_{2,3} := \frac{2 \, mp \, y \, z}{r^3} \quad (9)$$

```
> g[3,1]:=2*mp*x*z/r^3;
```

$$g_{3,1} := \frac{2 \, mp \, x \, z}{r^3} \quad (10)$$

Kontuz-----

```
> L2:=+M^2*c^2*(g[4,4]+g[1,1]*vx^2+g[2,2]*vy^2+g[3,3]*vz^2  
+2*(g[4,1]*vx+g[4,2]*vy+g[4,3]*vz
```

$$\begin{aligned}
& +2*(g[1,2]*vx*vy+g[2,3]*vy*vz+g[3,1]*vz*vx))) ; \text{ epsilon}^2=1 \\
L2 := & M^2 c^2 \left(vx^2 \left(1 + \frac{2 mp x^2}{r^3} \right) + \frac{8 vx vy mp x y}{r^3} + \frac{8 vx vz mp x z}{r^3} + vy^2 \left(1 + \frac{2 mp y^2}{r^3} \right) \right. \\
& \left. + \frac{8 vy vz mp y z}{r^3} + vz^2 \left(1 + \frac{2 mp z^2}{r^3} \right) + \frac{4 vx mp x c}{r^2} + \frac{4 vy mp y c}{r^2} + \frac{4 vz mp z c}{r^2} \right. \\
& \left. + \left(-1 + \frac{2 mp}{r} \right) c^2 \right) \quad (11)
\end{aligned}$$

> L2x:=diff(L2,x)+diff(L2,r)*x/r;

$$\begin{aligned}
L2x := & M^2 c^2 \left(\frac{4 vx^2 mp x}{r^3} + \frac{8 vx vy mp y}{r^3} + \frac{8 vx vz mp z}{r^3} + \frac{4 vx mp c}{r^2} \right) + \frac{1}{r} \left(M^2 c^2 \left(\right. \right. \\
& \left. \left. - \frac{6 vx^2 mp x^2}{r^4} - \frac{24 vx vy mp x y}{r^4} - \frac{24 vx vz mp x z}{r^4} - \frac{6 vy^2 mp y^2}{r^4} - \frac{24 vy vz mp y z}{r^4} \right. \right. \\
& \left. \left. - \frac{6 vz^2 mp z^2}{r^4} - \frac{8 vx mp x c}{r^3} - \frac{8 vy mp y c}{r^3} - \frac{8 vz mp z c}{r^3} - \frac{2 mp c^2}{r^2} \right) x \right) \quad (12)
\end{aligned}$$

> L2y:=diff(L2,y)+diff(L2,r)*y/r;

$$\begin{aligned}
L2y := & M^2 c^2 \left(\frac{8 vx vy mp x}{r^3} + \frac{4 vy^2 mp y}{r^3} + \frac{8 vy vz mp z}{r^3} + \frac{4 vy mp c}{r^2} \right) + \frac{1}{r} \left(M^2 c^2 \left(\right. \right. \\
& \left. \left. - \frac{6 vx^2 mp x^2}{r^4} - \frac{24 vx vy mp x y}{r^4} - \frac{24 vx vz mp x z}{r^4} - \frac{6 vy^2 mp y^2}{r^4} - \frac{24 vy vz mp y z}{r^4} \right. \right. \\
& \left. \left. - \frac{6 vz^2 mp z^2}{r^4} - \frac{8 vx mp x c}{r^3} - \frac{8 vy mp y c}{r^3} - \frac{8 vz mp z c}{r^3} - \frac{2 mp c^2}{r^2} \right) y \right) \quad (13)
\end{aligned}$$

> L2z:=diff(L2,z)+diff(L2,r)*z/r;

$$\begin{aligned}
L2z := & M^2 c^2 \left(\frac{8 vx vz mp x}{r^3} + \frac{8 vy vz mp y}{r^3} + \frac{4 vz^2 mp z}{r^3} + \frac{4 vz mp c}{r^2} \right) + \frac{1}{r} \left(M^2 c^2 \left(\right. \right. \\
& \left. \left. - \frac{6 vx^2 mp x^2}{r^4} - \frac{24 vx vy mp x y}{r^4} - \frac{24 vx vz mp x z}{r^4} - \frac{6 vy^2 mp y^2}{r^4} - \frac{24 vy vz mp y z}{r^4} \right. \right. \\
& \left. \left. - \frac{6 vz^2 mp z^2}{r^4} - \frac{8 vx mp x c}{r^3} - \frac{8 vy mp y c}{r^3} - \frac{8 vz mp z c}{r^3} - \frac{2 mp c^2}{r^2} \right) z \right) \quad (14)
\end{aligned}$$

> px:=1/(2*L)*diff(L2,vx); # px;=diff(sqrt(L2)),x):

$$px := \frac{1}{2} \frac{M^2 c^2 \left(2 vx \left(1 + \frac{2 mp x^2}{r^3} \right) + \frac{8 vy mp x y}{r^3} + \frac{8 vz mp x z}{r^3} + \frac{4 mp x c}{r^2} \right)}{L} \quad (15)$$

> py:=1/(2*L)*diff(L2,vy);

$$py := \frac{1}{2} \frac{M^2 c^2 \left(\frac{8 vx mp x y}{r^3} + 2 vy \left(1 + \frac{2 mp y^2}{r^3} \right) + \frac{8 vz mp y z}{r^3} + \frac{4 mp y c}{r^2} \right)}{L} \quad (16)$$

> pz:=1/(2*L)*diff(L2,vz);

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$$pz := \frac{1}{2} \frac{M^2 c^2 \left(\frac{8 vx mp x z}{r^3} + \frac{8 vy mp y z}{r^3} + 2 vz \left(1 + \frac{2 mp z^2}{r^3} \right) + \frac{4 mp z c}{r^2} \right)}{L} \quad (17)$$

> **H:=(px*vx+py*vy+pz*vz)-L;**

$$H := \frac{1}{2} \frac{M^2 c^2 \left(2 vx \left(1 + \frac{2 mp x^2}{r^3} \right) + \frac{8 vy mp x y}{r^3} + \frac{8 vz mp x z}{r^3} + \frac{4 mp x c}{r^2} \right) vx}{L} \quad (18)$$

$$+ \frac{1}{2} \frac{M^2 c^2 \left(\frac{8 vx mp x y}{r^3} + 2 vy \left(1 + \frac{2 mp y^2}{r^3} \right) + \frac{8 vz mp y z}{r^3} + \frac{4 mp y c}{r^2} \right) vy}{L}$$

$$+ \frac{1}{2} \frac{M^2 c^2 \left(\frac{8 vx mp x z}{r^3} + \frac{8 vy mp y z}{r^3} + 2 vz \left(1 + \frac{2 mp z^2}{r^3} \right) + \frac{4 mp z c}{r^2} \right) vz}{L} - L$$

> **L:=sqrt(L2);**

$$L := \quad (19)$$

$$\left(M^2 c^2 \left(vx^2 \left(1 + \frac{2 mp x^2}{r^3} \right) + \frac{8 vx vy mp x y}{r^3} + \frac{8 vx vz mp x z}{r^3} + vy^2 \left(1 + \frac{2 mp y^2}{r^3} \right) + \frac{8 vy vz mp y z}{r^3} + vz^2 \left(1 + \frac{2 mp z^2}{r^3} \right) + \frac{4 vx mp x c}{r^2} + \frac{4 vy mp y c}{r^2} + \frac{4 vz mp z c}{r^2} + \left(-1 + \frac{2 mp}{r} \right) c^2 \right) \right)^{1/2}$$

> **H:=simplify(H);**

$$H := - \left(M^2 c^3 (2 c mp r - c r^2 + 2 mp vx x + 2 mp vy y + 2 mp vz z) \right) \quad (20)$$

$$\left(r^2 \left(\frac{1}{r^3} (M^2 c^2 (2 c^2 mp r^2 - c^2 r^3 + 4 c mp r vx x + 4 c mp r vy y + 4 c mp r vz z + 2 mp vx^2 x^2 + 8 mp vx vy x y + 8 mp vx vz x z + 2 mp vy^2 y^2 + 8 mp vy vz y z + 2 mp vz^2 z^2 + r^3 vx^2 + r^3 vy^2 + r^3 vz^2)) \right)^{1/2} \right)$$

> **#limit(H,r=infinity);**

> **H2:=subs(z=0,vz=0,H);**

$$H2 := - \left(M^2 c^3 (2 c mp r - c r^2 + 2 mp vx x + 2 mp vy y) \right) \quad (21)$$

$$\left(r^2 \left(\frac{1}{r^3} (M^2 c^2 (2 c^2 mp r^2 - c^2 r^3 + 4 c mp r vx x + 4 c mp r vy y + 4 c mp r vz z + 2 mp vx^2 x^2 + 8 mp vx vy x y + 8 mp vx vz x z + 2 mp vy^2 y^2 + 8 mp vy vz y z + 2 mp vz^2 z^2 + r^3 vx^2 + r^3 vy^2 + r^3 vz^2)) \right)^{1/2} \right)$$

$$\left(\frac{1}{r^3} (M^2 c^2 (2 c^2 mp r^2 - c^2 r^3 + 4 c mp r vx x + 4 c mp r vy y + 2 mp vx^2 x^2 + 8 mp vx vy x y + 2 mp vy^2 y^2 + r^3 vx^2 + r^3 vy^2)))^{1/2} \right)$$

> H2:=convert(series(H2,mp,2),polynom);

$$H2 := \frac{M^2 c^4}{\sqrt{-M^2 c^2 (c^2 - vx^2 - vy^2)}} + \left(\frac{M^2 c^4 (c^2 r^2 + 2 c r vx x + 2 c r vy y + vx^2 x^2 + 4 vx vy x y + vy^2 y^2)}{\sqrt{-M^2 c^2 (c^2 - vx^2 - vy^2)} r^3 (c^2 - vx^2 - vy^2)} - \frac{M^2 c^3 (2 c r + 2 vx x + 2 vy y)}{r^2 \sqrt{-M^2 c^2 (c^2 - vx^2 - vy^2)}} \right) mp \quad (22)$$

> H2:=convert(asympt(H2,c,4),polynom);

$$H2 := \left(\frac{M^2}{\sqrt{-M^2}} - \frac{M^2 mp}{\sqrt{-M^2} r} \right) c^2 + \left(\frac{M^2 (2 r vx x + 2 r vy y)}{\sqrt{-M^2} r^3} - \frac{M^2 (2 vx x + 2 vy y)}{r^2 \sqrt{-M^2}} \right) mp c \quad (23)$$

> simplify(H2);

$$- \frac{M^2 (mp - r) c^2}{\sqrt{-M^2} r} \quad (24)$$

> Hnumer:=collect(numer(H),mp);

$$Hnumer := -M^2 c^3 (2 c r + 2 vx x + 2 vy y + 2 vz z) mp + M^2 c^4 r^2 \quad (25)$$

> Hdenom:=collect(denom(H),mp);

$$Hdenom := r^2 \quad (26)$$

$$\left(\frac{1}{r^3} (M^2 c^2 (2 c^2 mp r^2 - c^2 r^3 + 4 c mp r vx x + 4 c mp r vy y + 4 c mp r vz z + 2 mp vx^2 x^2 + 8 mp vx vy x y + 8 mp vx vz x z + 2 mp vy^2 y^2 + 8 mp vy vz y z + 2 mp vz^2 z^2 + r^3 vx^2 + r^3 vy^2 + r^3 vz^2)) \right)^{1/2}$$

> r:=sqrt(x^2+y^2+z^2);

$$r := \sqrt{x^2 + y^2 + z^2} \quad (27)$$

> coord := [x,y,z,t]:

> g_compts := array(symmetric,sparse,1..4,1..4):

> g_compts[4,4]:=g[4,4]:

> g_compts[4,1]:=g[4,1]:

> g_compts[4,2]:=g[4,2]:

> g_compts[4,3]:=g[4,3]:

> g_compts[1,1]:=g[1,1]:

```

> g_compts[2,2]:=g[2,2]:
> g_compts[3,3]:=g[3,3]:
> g_compts[1,2]:=g[1,2]:
> g_compts[2,3]:=g[2,3]:
> g_compts[3,1]:=g[3,1]:
> g := create([-1,-1],eval(g_compts)):
> ginv:=invert(g,'detg'):
> D1g:=d1metric(g,coord): D2g:=d2metric(D1g,coord):
> Cf1 :=Christoffel1(D1g):

-----
> #RMN:=Riemann(ginv, D2g, Cf1):
> #RICCI:=simplify(Ricci(ginv,RMN));

-----
> `tensor/Christoffel2/simp`:=proc(x) simplify(x,trig) end proc:
> Cf2:=Christoffel2(ginv,Cf1):
> Cf2c:=get_compts(Cf2):
> Cf2p:=act(subs,mp=m,Cf2):
> Cf2pc:=get_compts(Cf2p):

```

Two bodies plane motion-----

```

> z:=0; vz:=0;
          z := 0
          vz := 0

```

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> Cf2c[4,4,4]:=simplify(Cf2c[4,4,4]):
> Cf2c[4,4,1]:=simplify(Cf2c[4,4,1]):
> Cf2c[4,4,2]:=simplify(Cf2c[4,4,2]):
> Cf2c[4,1,1]:=simplify(Cf2c[4,1,1]):
> Cf2c[4,2,2]:=simplify(Cf2c[4,2,2]):
> Cf2c[4,1,2]:=simplify(Cf2c[4,1,2]):

```

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> Cf2c[1,4,4]:=simplify(Cf2c[1,4,4]):
> Cf2c[1,4,1]:=simplify(Cf2c[1,4,1]):
> Cf2c[1,4,2]:=simplify(Cf2c[1,4,2]):
> Cf2c[1,1,1]:=simplify(Cf2c[1,1,1]):
> Cf2c[1,2,2]:=simplify(Cf2c[1,2,2]):
> Cf2c[1,1,2]:=simplify(Cf2c[1,1,2]):

```

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> Cf2c[2,4,4]:=simplify(Cf2c[2,4,4]);
          Cf2c2,4,4 :=  $\frac{(-2mp + \sqrt{x^2 + y^2})mp y c^2}{x^4 + 2x^2y^2 + y^4}$ 

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> Cf2c[2,4,1]:=simplify(Cf2c[2,4,1]);
          Cf2c2,4,1 :=  $-\frac{2ycxmp^2}{(x^2 + y^2)^{5/2}}$ 

```

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```

> Cf2c[2,4,2]:=simplify(Cf2c[2,4,2]);
          Cf2c2,4,2 :=  $-\frac{2cy^2mp^2}{(x^2 + y^2)^{5/2}}$ 

```

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> Cf2c[2,1,1]:=simplify(Cf2c[2,1,1]);

$$Cf2c_{2,1,1} := -\frac{(2mpx^2 + x^2\sqrt{x^2+y^2} - 2\sqrt{x^2+y^2}y^2) y mp}{x^6 + 3x^4y^2 + 3x^2y^4 + y^6} \quad (32)$$

> Cf2c[2,2,2]:=simplify(Cf2c[2,2,2]);

$$Cf2c_{2,2,2} := \frac{(-2mpy^2 + 2x^2\sqrt{x^2+y^2} - \sqrt{x^2+y^2}y^2) y mp}{x^6 + 3x^4y^2 + 3x^2y^4 + y^6} \quad (33)$$

> Cf2c[2,1,2]:=simplify(Cf2c[2,1,2]);

$$Cf2c_{2,1,2} := -\frac{(2mp + 3\sqrt{x^2+y^2}) y^2 x mp}{x^6 + 3x^4y^2 + 3x^2y^4 + y^6} \quad (34)$$


```

```

> Cf2pc[4,4,4]:=simplify(Cf2pc[4,4,4]);

$$Cf2pc_{4,4,4} := \frac{2m^2 c}{(x^2 + y^2)^{3/2}} \quad (35)$$

> Cf2pc[4,4,1]:=simplify(Cf2pc[4,4,1]);

$$Cf2pc_{4,4,1} := \frac{(2m + \sqrt{x^2 + y^2}) mx}{x^4 + 2x^2y^2 + y^4} \quad (36)$$

> Cf2pc[4,4,2]:=simplify(Cf2pc[4,4,2]);

$$Cf2pc_{4,4,2} := \frac{(2m + \sqrt{x^2 + y^2}) my}{x^4 + 2x^2y^2 + y^4} \quad (37)$$

> Cf2pc[4,1,1]:=simplify(Cf2pc[4,1,1]);

$$Cf2pc_{4,1,1} := \frac{2(m x^2 + x^2\sqrt{x^2+y^2} - \sqrt{x^2+y^2}y^2) m}{(x^2 + y^2)^{5/2} c} \quad (38)$$

> Cf2pc[4,2,2]:=simplify(Cf2pc[4,2,2]);

$$Cf2pc_{4,2,2} := -\frac{2(-my^2 + x^2\sqrt{x^2+y^2} - \sqrt{x^2+y^2}y^2) m}{(x^2 + y^2)^{5/2} c} \quad (39)$$

> Cf2pc[4,1,2]:=simplify(Cf2pc[4,1,2]);

$$Cf2pc_{4,1,2} := \frac{2(m + 2\sqrt{x^2+y^2}) mx y}{(x^2 + y^2)^{5/2} c} \quad (40)$$


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> Cf2pc[1,4,4]:=simplify(Cf2pc[1,4,4]);

$$Cf2pc_{1,4,4} := \frac{(-2m + \sqrt{x^2 + y^2}) mx c^2}{x^4 + 2x^2y^2 + y^4} \quad (41)$$

> Cf2pc[1,4,1]:=simplify(Cf2pc[1,4,1]);

$$Cf2pc_{1,4,1} := -\frac{2c x^2 m^2}{(x^2 + y^2)^{5/2}} \quad (42)$$

> Cf2pc[1,4,2]:=simplify(Cf2pc[1,4,2]);

$$Cf2pc_{1,4,2} := -\frac{2y c x m^2}{(x^2 + y^2)^{5/2}} \quad (43)$$

> Cf2pc[1,1,1]:=simplify(Cf2pc[1,1,1]);

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$$Cf2pc_{1,1,1} := - \frac{(2mx^2 + x^2\sqrt{x^2+y^2} - 2\sqrt{x^2+y^2}y^2)xm}{x^6 + 3x^4y^2 + 3x^2y^4 + y^6} \quad (44)$$

> Cf2pc[1,2,2]:=simplify(Cf2pc[1,2,2]);

$$Cf2pc_{1,2,2} := \frac{(-2my^2 + 2x^2\sqrt{x^2+y^2} - \sqrt{x^2+y^2}y^2)xm}{x^6 + 3x^4y^2 + 3x^2y^4 + y^6} \quad (45)$$

> Cf2pc[1,1,2]:=simplify(Cf2pc[1,1,2]);

$$Cf2pc_{1,1,2} := - \frac{(2m + 3\sqrt{x^2+y^2})yx^2m}{x^6 + 3x^4y^2 + 3x^2y^4 + y^6} \quad (46)$$

> Cf2pc[2,4,4]:=simplify(Cf2pc[2,4,4]);

$$Cf2pc_{2,4,4} := \frac{(-2m + \sqrt{x^2+y^2})myc^2}{x^4 + 2x^2y^2 + y^4} \quad (47)$$

> Cf2pc[2,4,1]:=simplify(Cf2pc[2,4,1]);

$$Cf2pc_{2,4,1} := - \frac{2ycxm^2}{(x^2+y^2)^{5/2}} \quad (48)$$

> Cf2pc[2,4,2]:=simplify(Cf2pc[2,4,2]);

$$Cf2pc_{2,4,2} := - \frac{2cy^2m^2}{(x^2+y^2)^{5/2}} \quad (49)$$

> Cf2pc[2,4,2]:=simplify(Cf2pc[2,4,2]);

$$Cf2pc_{2,4,2} := - \frac{2cy^2m^2}{(x^2+y^2)^{5/2}} \quad (50)$$

> Cf2pc[2,1,1]:=simplify(Cf2pc[2,1,1]);

$$Cf2pc_{2,1,1} := - \frac{(2mx^2 + x^2\sqrt{x^2+y^2} - 2\sqrt{x^2+y^2}y^2)ym}{x^6 + 3x^4y^2 + 3x^2y^4 + y^6} \quad (51)$$

> Cf2pc[2,2,2]:=simplify(Cf2pc[2,2,2]);

$$Cf2pc_{2,2,2} := \frac{(-2my^2 + 2x^2\sqrt{x^2+y^2} - \sqrt{x^2+y^2}y^2)ym}{x^6 + 3x^4y^2 + 3x^2y^4 + y^6} \quad (52)$$

> Cf2pc[2,1,2]:=simplify(Cf2pc[2,1,2]);

$$Cf2pc_{2,1,2} := - \frac{(2m + 3\sqrt{x^2+y^2})y^2xm}{x^6 + 3x^4y^2 + 3x^2y^4 + y^6} \quad (53)$$

> b:=simplify(Cf2c[4,4,4]+2*Cf2c[4,4,1]*vx+Cf2c[4,1,1]*vx^2+2*Cf2c[4,4,2]*vy+Cf2c[4,2,2]*vy^2+2*Cf2c[4,1,2]*vx*vy);

$$b := \frac{1}{(x^4 + 2x^2y^2 + y^4)c\sqrt{x^2+y^2}} (2(c^2mpx^2 + c^2mypy^2 + 2cmpxvx\sqrt{x^2+y^2}) \quad (54)$$

$$+ 2cmipy\sqrt{x^2+y^2}y + cmvx^3 + cvxx^2y^2 + cvy^2x^2y + cvyy^3 + mpvx^2x^2 \\ + 2vxvympxy + mpvy^2y^2 + vx^2x^2\sqrt{x^2+y^2} - vx^2\sqrt{x^2+y^2}y^2 \\ + 4vxvyx\sqrt{x^2+y^2}y - vyy^2x^2\sqrt{x^2+y^2} + vy^2\sqrt{x^2+y^2}y^2)mp)$$

> bp:=simplify(Cf2pc[4,4,4]+2*Cf2pc[4,4,1]*vxp+Cf2pc[4,1,1]*vxp^2)

$$+2*Cf2c[4,4,2]*vyp+Cf2pc[4,2,2]*vyp^2+2*Cf2pc[4,1,2]*vxp*vyp);$$

$$bp := \frac{1}{(x^4 + 2x^2y^2 + y^4) c \sqrt{x^2 + y^2}} \left(2(c^2 m^2 x^2 + c^2 m^2 y^2 + 2 c m^2 vxp x \sqrt{x^2 + y^2} \right. \\ \left. + c m vxp x^3 + c m vxp x y^2 + 2 c m p^2 vyp \sqrt{x^2 + y^2} y + c m p vyp x^2 y + c m p vyp y^3 \right. \\ \left. + m^2 vxp^2 x^2 + 2 m^2 vxp vyp x y + m^2 vyp^2 y^2 + m vxp^2 x^2 \sqrt{x^2 + y^2} \right. \\ \left. - m vxp^2 \sqrt{x^2 + y^2} y^2 + 4 m vxp vyp x \sqrt{x^2 + y^2} y - m vyp^2 x^2 \sqrt{x^2 + y^2} \right. \\ \left. + m vyp^2 \sqrt{x^2 + y^2} y^2 \right) \right) \quad (55)$$

```
> odevx:=simplify(ax+Cf2c[1,4,4]+Cf2c[1,1,1]*vx^2+Cf2c[1,2,2]*vy^2
+2*(Cf2c[1,1,4]*vx +Cf2c[1,1,2]*vx*vy+Cf2c[1,2,4]*vy)=b*vx):
```

```
> odevy:=simplify/ay+Cf2c[2,4,4]+Cf2c[2,1,1]*vx^2+Cf2c[2,2,2]*vy^2
+2*(Cf2c[2,1,4]*vx +Cf2c[2,1,2]*vx*vy+Cf2c[2,2,4]*vy)=b*vy):
```

```
> odevxp:=simplify(axp+Cf2c[1,4,4]+Cf2c[1,1,1]*vxp^2+Cf2c[1,2,2]*vyp^2
+2*(Cf2c[1,1,4]*vxp +Cf2c[1,1,2]*vxp*vyp+Cf2c[1,2,4]*vyp)
=bp*vxp):
```

```
> odevyp:=simplify/ayp+Cf2c[2,4,4]+Cf2c[2,1,1]*vxp^2+Cf2c[2,2,2]*vyp^2
+2*(Cf2c[2,1,4]*vxp +Cf2c[2,1,2]*vxp*vyp+Cf2c[2,2,4]*vyp)
=bp*vyp):
```

DATA

$$> c:=299792458.0; \# m/s \quad c := 2.997924580 \cdot 10^8 \quad (56)$$

$$> G:=6.6738480*10^{-11}; \# *m^3/(kg*s^2); \quad G := 6.673848000 \cdot 10^{-11} \quad (57)$$

$$> DTS:=149597870700; \# m \quad DTS := 149597870700 \quad (58)$$

$$> MS:=2.0*10^30; \# *kg \quad MS := 2.000000000 \cdot 10^{30} \quad (59)$$

$$> R:=DTS; \quad Rp:=DTS; \quad R := 149597870700 \quad Rp := 149597870700 \quad (60)$$

$$> M:=MS; \quad Mp:=MS; \# kg \quad M := 2.000000000 \cdot 10^{30} \quad Mp := 2.000000000 \cdot 10^{30} \quad (61)$$

```

> GM:=G*M;      #   *kg*s^2;
                           GM := 1.334769600 1020          (62)

```

```

> GMp:=G*Mp;     #   *kg*s^2;
                           GMp := 1.334769600 1020         (63)

```

KONTUZ Gravity waves-----

```

> M:=35*M;   GM:=35*GM;
                           M := 7.000000000 1031
                           GM := 4.671693600 1021          (64)

```

KONTUZ-----

```
> #M:=1; GM:=G;
```

```

> Mp:=35*Mp; GMp :=35*GMp;
                           Mp := 7.000000000 1031
                           GMp := 4.671693600 1021          (65)

```

```

> R:=175*10^3; # R:=256*4*R;           # m
                           R := 175000          (66)

```

```

> Rp:=175*10^3; # :=256*4*Rp;        # m
                           Rp := 175000          (67)

```

```

> m:=GM/c^2; mp:=GMp/c^2;
                           m := 51979.60146
                           mp := 51979.60146          (68)

```

KONTUZ-----

```
> #m:=0;
```

```

> Omega:=sqrt(GMp/(4*R^3)); Initial value. Guess from Newton's theory
                           Ω := 466.8207016          (69)

```

```

> Omega := Omega;
                           Ω := 466.8207016          (70)

```

```

> #Omega:=0.001;
> #Omega:=0.0005;
> #Omega:=0.0004;

```

```

> #Omega:=0.0003; No answer
> #Omega:=0.0002; No answer
> #Omega:=0.0001; No answer

```

```

> Per:=evalf(2*Pi/Omega); # s
                           Per := 0.01345952587          (71)

```

```

> Per/(60*24*365); # years
                           2.560792593 10-8          (72)

```

```

> x0:=R; xp0:=-x0; y0:=0; yp0:=0;
                           x0 := 175000
                           xp0 := -175000
                           y0 := 0

```

$$yp0 := 0 \quad (73)$$

```
> vx0:=0; vxp0:=-vx0; vy0:=x0*Omega; vyp0:=-vy0;
      vx0 := 0
      vxp0 := 0
      vy0 := 8.169362278 107
      vyp0 := -8.169362278 107 \quad (74)
```

Kontuz: Initial rotation data

```
> #vy0:=0; vyp0:=0;

> odex := diff(x(t), t) = vx(t); odexp := diff(xp(t), t) = vxp(t)
;
odex :=  $\frac{d}{dt} x(t) = vx(t)$ 
odexp :=  $\frac{d}{dt} xp(t) = vxp(t) \quad (75)$ 
```

```
> odehy := diff(y(t), t) = vy(t); odeyp := diff(yp(t), t) = vyp(t)
;
odehy :=  $\frac{d}{dt} y(t) = vy(t)$ 
odeyp :=  $\frac{d}{dt} yp(t) = vyp(t) \quad (76)$ 
```

Whitehead-----

```
> odevx:=subs(x=(x(t)-xp(t)),y=(y(t)-yp(t)),vx=vx(t),vy=vy(t),ax=
diff(vx(t),t),odevx):
> odevy:=subs(x=(x(t)-xp(t)),y=(y(t)-yp(t)),vx=vx(t), vy=vy(t),
ay=diff(vy(t),t),odevy):
> odevxp:=subs(x=(xp(t)-x(t)),y=(yp(t)-y(t)),vxp=vxp(t),vyp=vyp
(t),axp=diff(vxp(t),t),odevp):
> odevyp:=subs(x=(xp(t)-x(t)),y=(yp(t)-y(t)),vxp=vxp(t), vyp=vyp
(t),ayp=diff(vyp(t),t),odevp):
```

Newton -----

```
> sys:=odex,odexp,odehy,odeyp,odevx,odevp,odevy,odevyp:
> fncts:={x(t),xp(t),vx(t),vxp(t),y(t),yp(t),vy(t),vyp(t)};
fncts := {vx(t), vxp(t), vy(t), vyp(t), x(t), xp(t), y(t), yp(t)} \quad (77)
```

```
> ics:=x(0)=x0, xp(0)=xp0, y(0)=0, yp(0)=0, vx(0)=vx0, vxp(0)=
vxp0, vy(0)=vy0,
vyp(0)=-vy0;
ics := x(0) = 175000, xp(0) = -175000, y(0) = 0, yp(0) = 0, vx(0) = 0, vxp(0) = 0, vy(0) = 8.169362278 107, vyp(0) = -8.169362278 107 \quad (78)
```

```
> dsn:=dsolve({sys,ics},fncts,numeric,method=gear,abserr=1.*10^
(-10),relerr=1.*10^(-10),output=listprocedure);
dsn := [t=proc(t) ... end proc, vx(t)=proc(t) ... end proc, vxp(t)=proc(t)
```

```
...
end proc, vy(t)=proc(t) ... end proc, vyp(t)=proc(t) ... end proc, x(t)=proc(t)
...
end proc, xp(t)=proc(t) ... end proc, y(t)=proc(t) ... end proc, yp(t)=proc(t)
...
end proc]
```

```

> x,xp,vx,vxp,y,yp,vy,vyp:=op(subs(dsn,[x(t),xp(t),vx(t),vxp(t),y
  (t),yp(t),vy(t),vyp(t)]));
x, xp, vx, vxp, y, yp, vy, vyp := proc(t) ... end proc, proc(t) ... end proc, proc(t)
...
end proc, proc(t) ... end proc, proc(t) ... end proc, proc(t) ... end proc, proc(t)
...
end proc, proc(t) ... end proc

```

```

> Omega:=Omega; Per:=evalf(2*Pi/Omega);
           $\Omega := 466.8207016$ 
           $Per := 0.01345952587$  (81)

```

```

> x(Per); xp(Per); y(Per); yp(Per);
           $-4.50140020452582 \cdot 10^5$ 
           $4.50140020476698 \cdot 10^5$ 
           $-11420.2679878751$ 
           $11420.2679727990$  (82)

```

```

> Ti:=-Per; Tf:=9*Per;
           $Ti := -0.01345952587$ 
           $Tf := 0.1211357328$  (83)

```

```

> r:=t->sqrt((x(t)-xp(t))^2+(y(t)-yp(t))^2);
           $r := t \rightarrow \sqrt{(x(t) - xp(t))^2 + (y(t) - yp(t))^2}$  (84)

```

```

> r(0);
           $3.500000000 \cdot 10^5$  (85)

```

```

> Omega:=Omega;
           $\Omega := 466.8207016$  (86)

```

```

> sqrt(1-(vx(0)^2+vy(0)^2)/c^2);
           $0.9621556144$  (87)

```

```

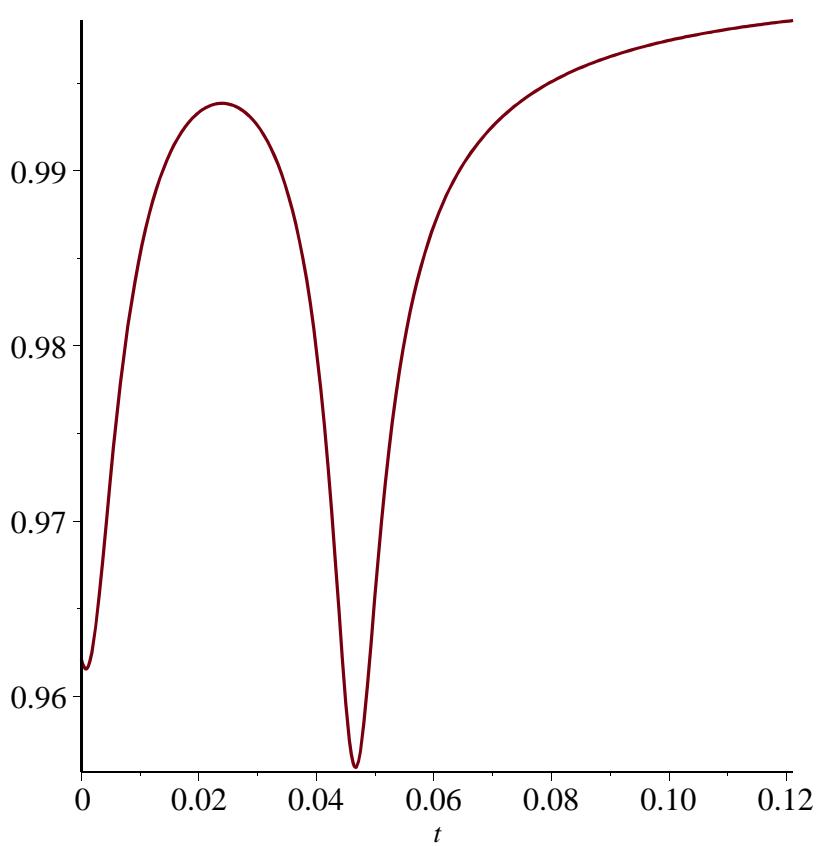
> TestV:=t->sqrt(1-(vx(t)^2+vy(t)^2)/c^2);
           $TestV := t \rightarrow \sqrt{1 - \frac{vx(t)^2 + vy(t)^2}{c^2}}$  (88)

```

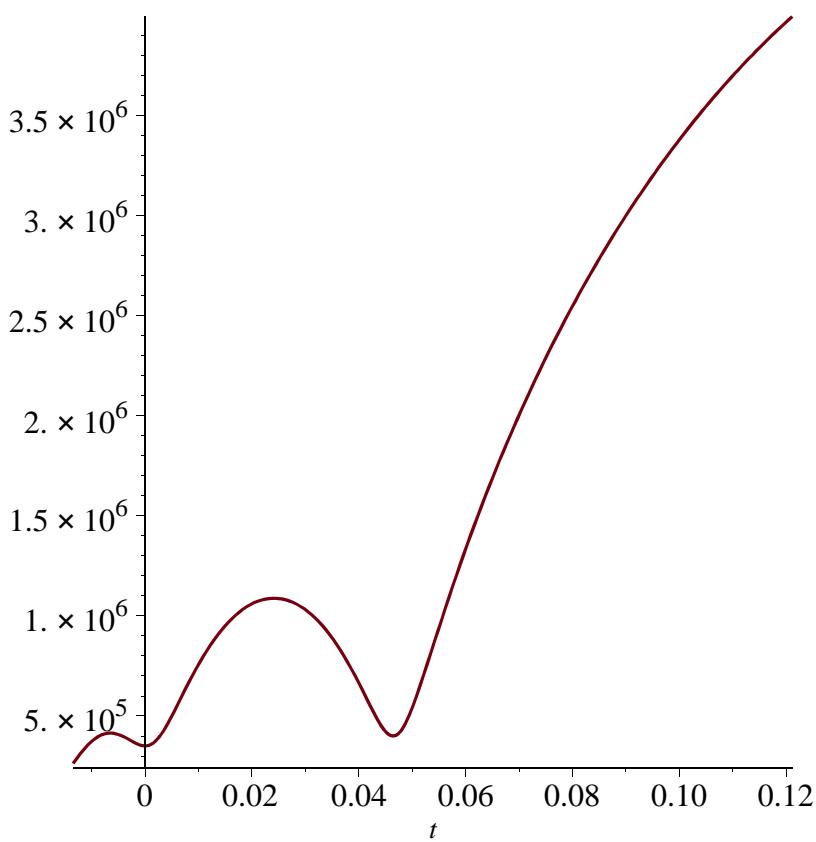
```

> plot(TestV(t),t=0..Tf);

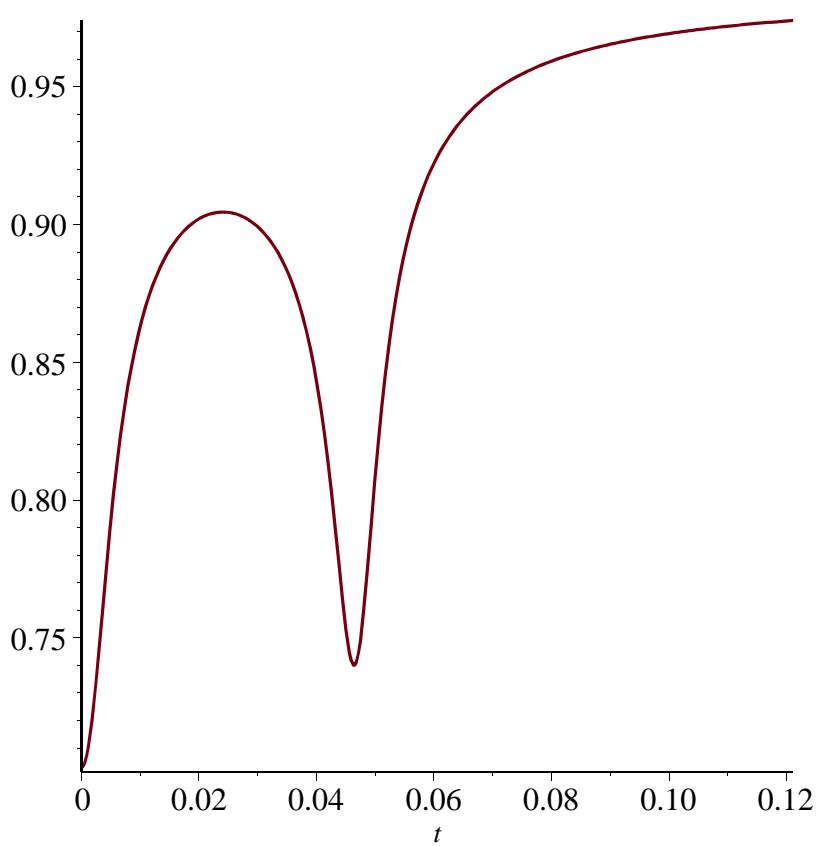
```



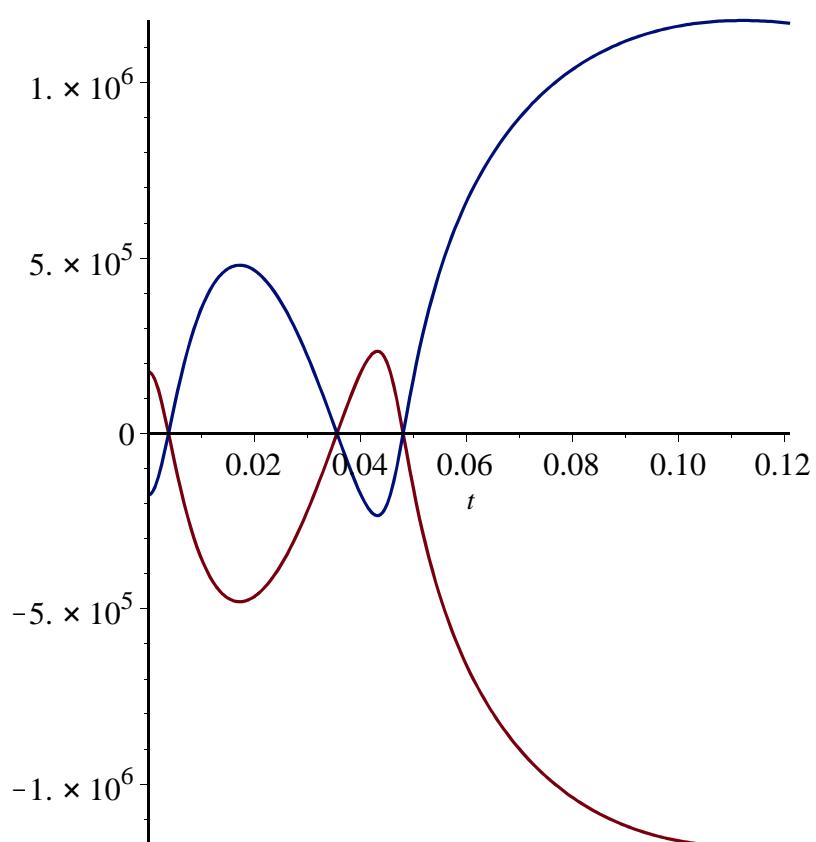
```
> plot(r(t),t=Ti..Tf);
```



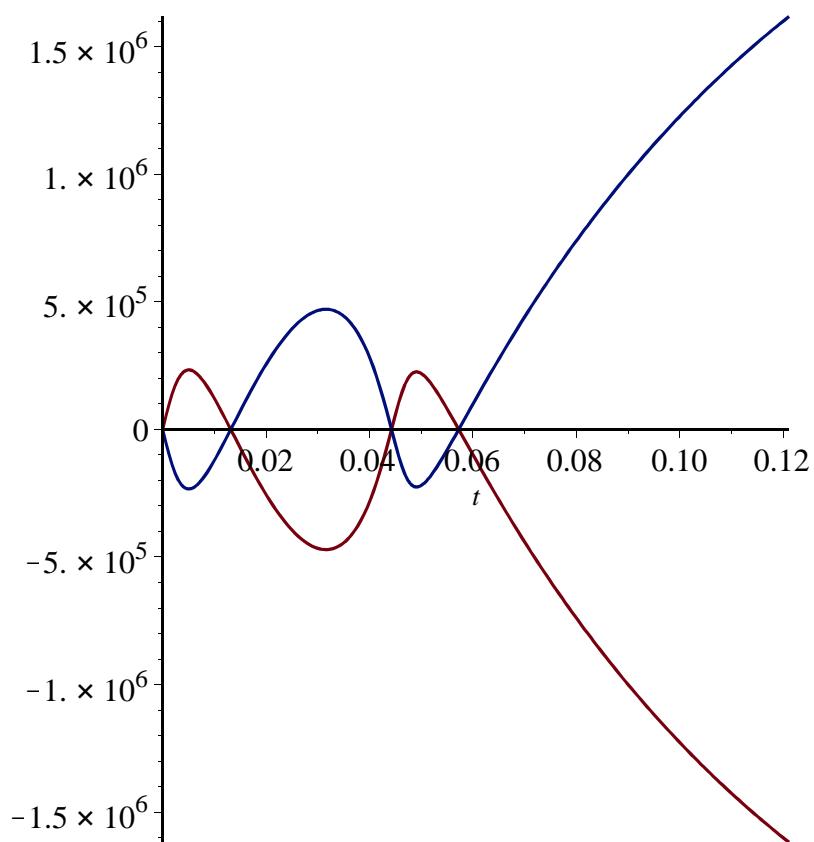
```
> plot(1-2*m/r(t),t=0..Tf);
```



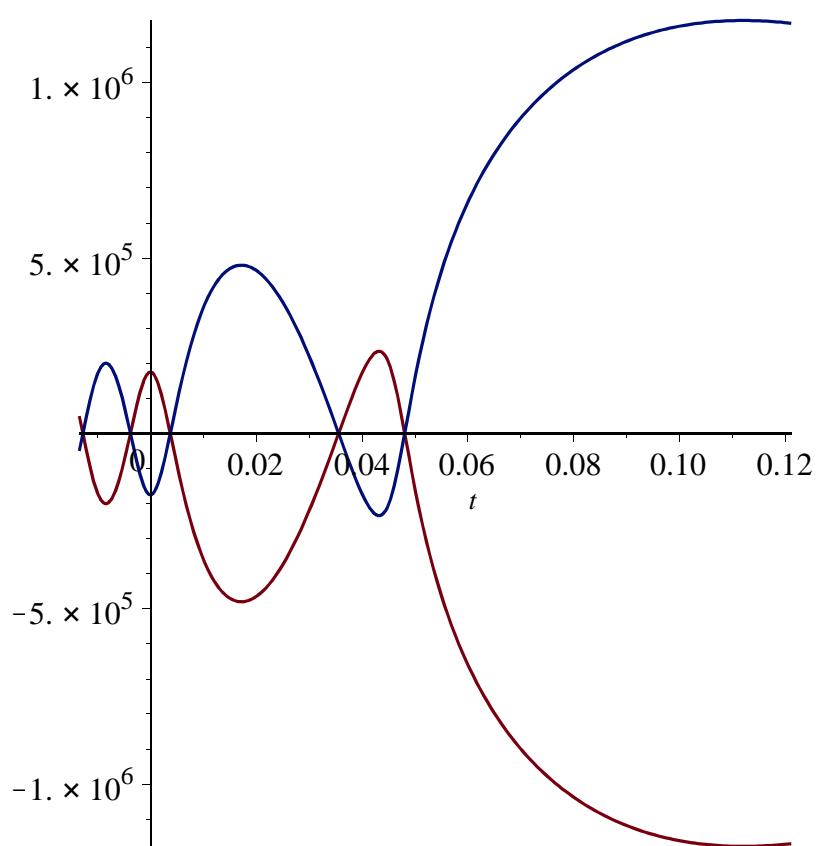
```
> plot([x(t),xp(t)],t=0..Tf);
```



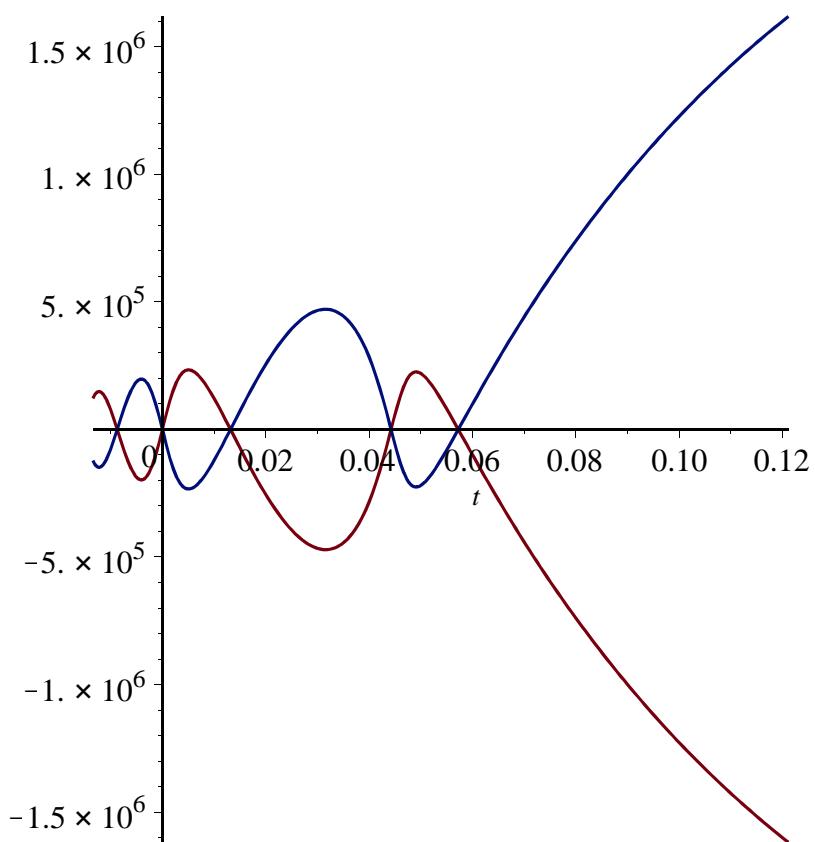
```
> plot([y(t),yp(t)],t=0..Tf);
```



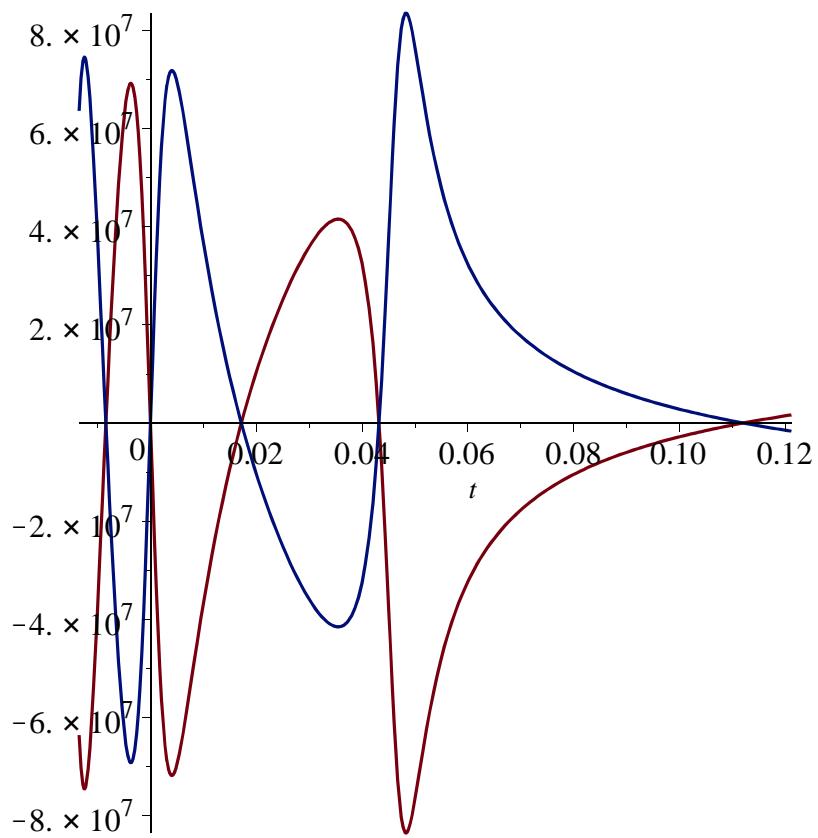
```
> plot([x(t),xp(t)],t=Ti..Tf);
```



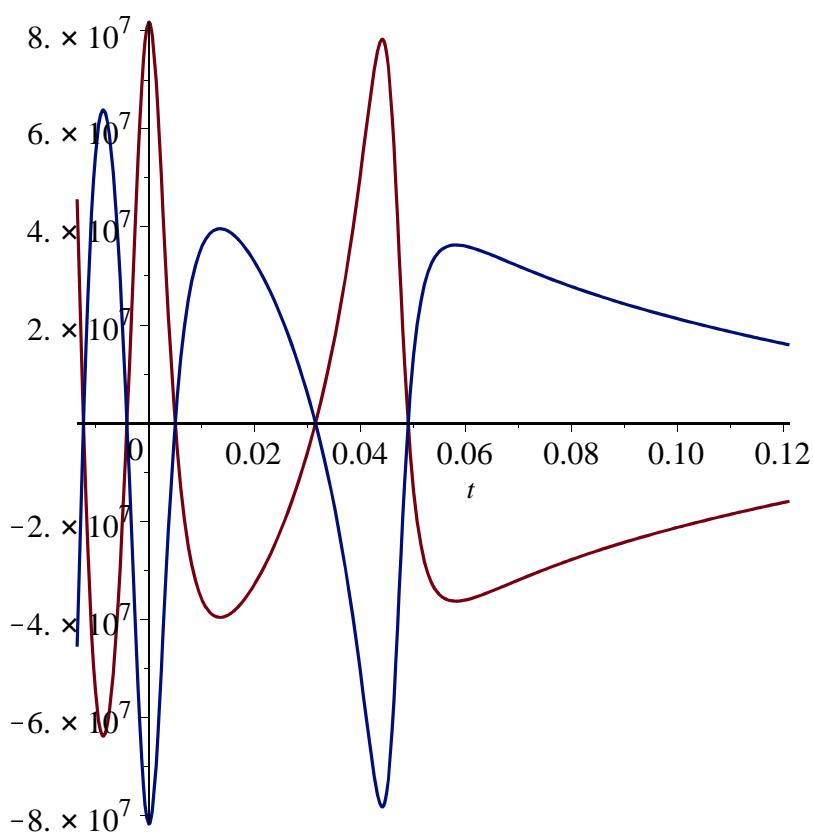
```
> plot([y(t),yp(t)],t=Ti..Tf);
```



```
> plot([vx(t),vxp(t)],t=Ti..Tf);
```



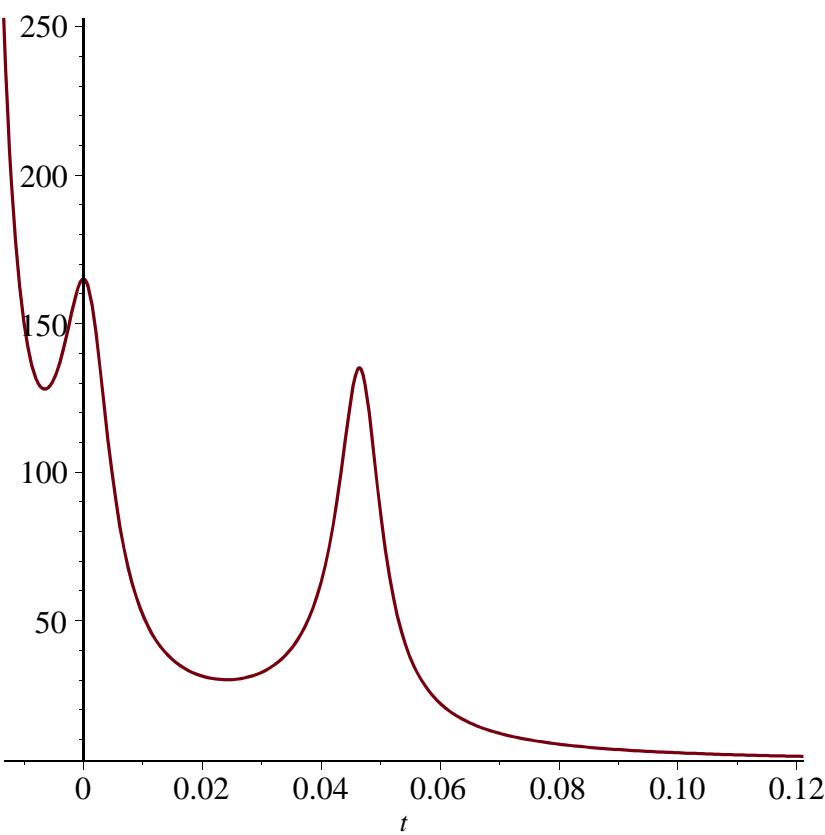
```
> plot([vy(t),vyp(t)],t=Ti..Tf);
```



```
> Tf:=Tf;
 $Tf := 0.1211357328$  (89)
```

```
> Omega:=t->sqrt(GM/(4*r(t)^3));
 $\Omega := t \mapsto \sqrt{\frac{1}{4} \frac{GM}{r(t)^3}}$  (90)
```

```
> plot([Omega(t)],t=Ti..Tf);
```



$$> \theta := t \rightarrow \arctan\left(\frac{y(t)}{x(t)}\right) \quad (91)$$

$$\begin{aligned} &> \# \text{plot}([\theta(t)], t = T_i .. T_f); \\ &> \text{evalf}(\pi/2); \end{aligned} \quad 1.570796327 \quad (92)$$

Kontuz: +M^2, -----

$$\begin{aligned} &> H := t \rightarrow (M^2 c^3 (2 c r(t) + 2 v_x(t) x(t) + 2 v_y(t) y(t)) m_p - M^2 c^4 r(t)^2) / (r(t)^2 \sqrt{-M^2 c^2 r(t)^2 + 2 c^2 r(t)^3 + 4 c^4 r(t)^4}); \\ &H := t \rightarrow \left(M^2 c^3 (2 c r(t) + 2 v_x(t) x(t) + 2 v_y(t) y(t)) m_p - M^2 c^4 r(t)^2 \right) / \left(r(t)^2 \left(-\frac{1}{r(t)^3} (M^2 c^2 (2 c^2 m_p r(t)^2 - c^2 r(t)^3 + 4 c m_p r(t) v_x(t) x(t) + 2 c m_p r(t) v_y(t) y(t) + 2 m_p v_x(t)^2 x(t)^2 + 8 m_p v_x(t) v_y(t) x(t) y(t)) \right) \right) \end{aligned} \quad (93)$$

$$\left. \left[+ 2 mp vy(t)^2 y(t)^2 + r(t)^3 vx(t)^2 + r(t)^3 vy(t)^2 \right) \right]^{1/2} \right)$$

> H(0);

$$-1.047538485 \cdot 10^{138}$$
 (94)
 Kontuz: +Mp^2, -----

> Hp:=t->(Mp^2*c^3*(2*c*r(t)+2*vxp(t)*xp(t)+2*vyp(t)*yp(t)*m-Mp^2*c^4*r(t)^2)/(r(t)^2*sqrt(-Mp^2*c^2*(2*c^2*m*r(t)^2-c^2*r(t)^3+4*c*m*r(t)*vxp(t)*xp(t)+4*c*m*r(t)*vyp(t)*yp(t)+2*m*vxp(t)^2*xp(t)^2+8*m*vxp(t)*vyp(t)*xp(t)*yp(t)+2*m*vyp(t)^2*yp(t)^2+r(t)^3*vxp(t)^2+r(t)^3*vyp(t)^2)/r(t)^3));

$$Hp := t \rightarrow \left(Mp^2 c^3 (2 c r(t) + 2 vxp(t) xp(t) + 2 vyp(t) yp(t) m - Mp^2 c^4 r(t)^2) \right)$$
 (95)

$$\left. \left(r(t)^2 \left(-\frac{1}{r(t)^3} (Mp^2 c^2 (2 c^2 m r(t)^2 - c^2 r(t)^3 + 4 c m r(t) vxp(t) xp(t) + 4 c m r(t) vyp(t) yp(t) + 2 m vxp(t)^2 xp(t)^2 + 8 m vxp(t) vyp(t) xp(t) yp(t) + 2 m vyp(t)^2 yp(t)^2 + r(t)^3 vxp(t)^2 + r(t)^3 vyp(t)^2)) \right)^{1/2} \right)$$

> subs(m=0,Hp(0)); subs(mp=0,H(0));

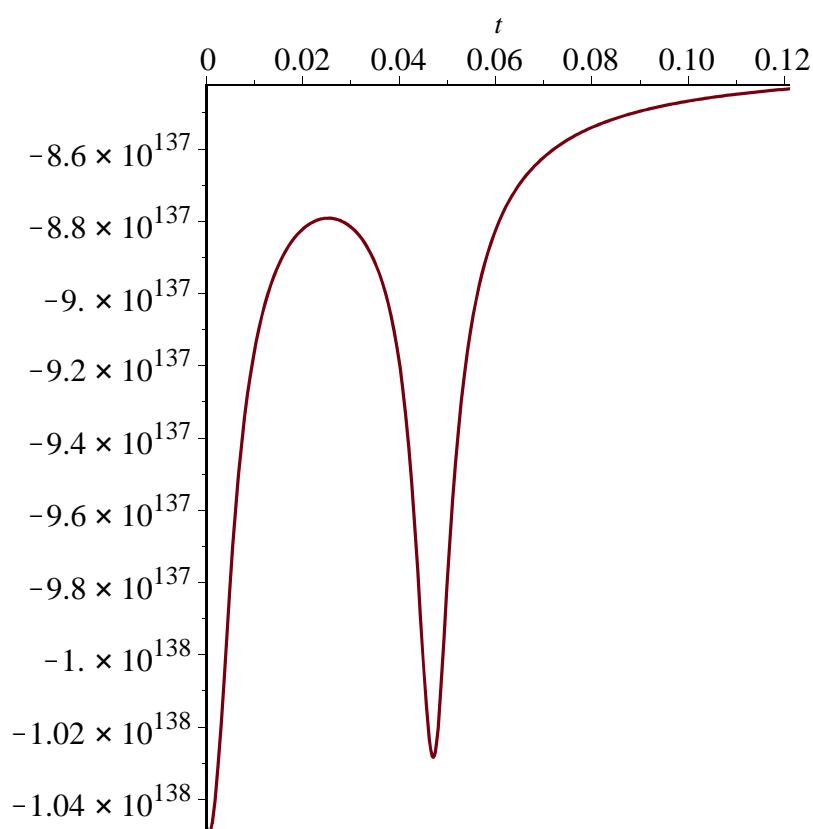
$$-1.047538485 \cdot 10^{138}$$

$$-1.047538485 \cdot 10^{138}$$
 (96)

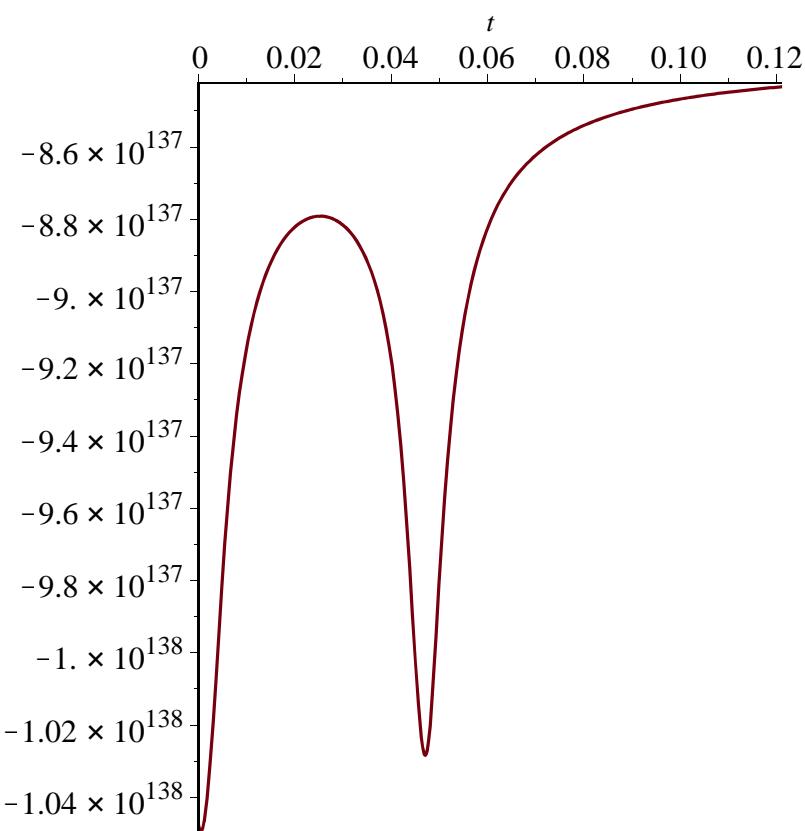
> H(0); Hp(0);

$$-1.047538485 \cdot 10^{138}$$

$$-1.047538485 \cdot 10^{138}$$
 (97)
> plot([H(t)], t=0..Tf);



```
> plot([H_p(t)], t=0..Tf);
```



```
> (H(Tf)-H(0))/(H(Tf)+H(0));
```

$$-0.107998748081240 \quad (98)$$

```
> H(0);
```

$$-1.047538485 \cdot 10^{138} \quad (99)$$

```
> Tf:=Tf; H(Tf);
```

$$\begin{aligned} Tf &:= 0.1211357328 \\ &-8.43327342807222 \cdot 10^{137} \end{aligned} \quad (100)$$