

# Determining satisfiability of 3-SAT in polynomial time

Ortho Flint, Asanka Wickramasinghe, Jay Brasse, Chris Fowler

## Abstract

In this paper, we provide a polynomial time (and space), algorithm that determines satisfiability of 3-SAT.

## 1 Preliminaries and Definitions

**Definition 1.1.** *A 3-SAT is a collection of literals or variables (usually represented by integers), in groups called clauses where no clause has more than 3 literals, and at least one clause does have 3 literals. If it's possible to select exactly one literal from each clause such that no literal  $l$ , and its negation  $\neg l$  (or denoted  $\neg l$ , meaning not  $l$ ), appear in the collection of chosen literals, we say that the 3-SAT is satisfiable, otherwise we say it's unsatisfiable. For satisfiability, the collection of literals chosen is called a solution. Note that the size of a solution set is smaller than the size of the collection, if the collection had at least two clauses of which the same literal was chosen.*

It is important to note, that our definition of a solution (definition 1.8), is inextricably tied to our constructs for a collection of clauses.

When we think of literals (also called *atoms*), we can consider an edge joining two vertices, each with an associated literal, if and only if, it's not a literal and its negation. Under no circumstance would a literal and its negation be connected by an edge. There are also no edges between two literals from the same clause. So conceptually, there exist edges that connect every literal to every other literal with the two restrictions that were just stated. Then it follows, that a collection of literals for some solution is such that, a literal from each clause is connected to every other literal from that collection. In graph theory, such a graph is called a *complete* graph  $K_n$ ,  $n$  being the number of vertices, which here it's also the number of clauses. We shall denote this graph as:  $K_C$  where  $c$  is the number of clauses.

**Definition 1.2.** *An edge-sequence is an ordered sequence with elements 1 and 0. The ordering is an ordering of the clauses, with indexing:  $C_1, C_2, C_3, \dots, C_c$  where a corresponding  $C_i$  has its literals ordered the same way for each sequence*

constructed for a 3-SAT. An edge-sequence  $I$ , for an edge with endpoints labelled  $x$  and  $y$ , where  $x \neq -y$ , the literals associated with the endpoints, is denoted by  $I_{x,y}$ . The endpoints must always be from different clauses. We call the positions in  $I_{x,y}$  that correspond to a clause  $C_i$  the cell  $C_i$ . The cells  $C_j$  and  $C_k$  containing the endpoints,  $x$  and  $y$  for  $I_{x,y}$  have only one entry that is 1 in the positions associated to  $x$  and  $y$ . When an edge-sequence is constructed, a given position in  $I_{x,y}$  is 1 if the associated literal is not  $-x$  or  $-y$ . The initial construction of  $I_{x,y}$  is subject to certain rules defined in 1.6 and 1.7, which may produce more zero entries. Lastly, removing one or more cells from  $I_{x,y}$  is again a (sub) edge-sequence, denoted by  $I_{x,y}^*$ , if the cells containing the endpoints for  $I_{x,y}$  remain.

**Definition 1.3.** A loner cell contains just one 1 entry for some literal. And a loner clause contains just one literal.

**Definition 1.4.** A vertex-sequence is an ordered sequence with elements 1 and 0. The ordering is an ordering of the clauses, with indexing:  $C_1, C_2, C_3, \dots, C_c$  where a corresponding  $C_i$  has its literals ordered the same way for each sequence constructed for a 3-SAT. A vertex-sequence  $V$ , for a vertex associated with literal  $x$ , is denoted by  $V_x$ . We call the positions in  $V_x$  that correspond to a clause  $C_i$  the cell  $C_i$ . The cell  $C_j$  containing the vertex  $x$  for  $V_x$  has only one entry that is 1 in the position associated to  $x$ . When a vertex-sequence is constructed, a given position in  $V_x$  is 1 if the associated literal is not  $-x$ . The initial construction of  $V_x$  is subject to certain rules defined in 1.6 and 1.7, which may produce more zero entries. Removing one or more cells from  $V_x$  is again a (sub) vertex-sequence, denoted by  $V_x^*$ , if the cell containing  $x$  remains.

**Definition 1.5.** When an entry 1 in an edge-sequence or a vertex-sequence, becomes zero, we call it a bit-change. If a bit-change has occurred in an edge-sequence or a vertex-sequence, we say the sequence has been refined, or a refinement has occurred. A zero entry never becomes a 1 entry.

It's worth noting here that if an edge-sequence  $I_{a,b}$  has a zero entry in some position for a literal  $c$ , then there is no  $K_C$ , using literals  $a, b$  and  $c$  together. In fact, this is what a bit-change is documenting in an edge-sequence.

**Definition 1.6.** The loner cell rule, LCR, is that no negation of a literal belonging to a loner cell can exist in an edge-sequence or vertex-sequence. If such a scenario exists in an edge-sequence  $I_{x,y}$  or a vertex-sequence  $V_x$  where  $z$  is the loner cell literal, then all positions associated with literal  $-z$  incur a bit-change. If this action of a bit-change for  $-z$ , creates another loner cell where the negation of the literal in the newly created loner cell is still present in  $I_{x,y}$  or  $V_x$  the action of a bit-change for the negation is repeated. Hence, to be LCR compliant may be recursive, but all refinements are permanent for any edge or vertex sequence.

*LCR compliancy is determined for an edge-sequence  $I_{x,y}$  or a vertex-sequence  $V_x$  if either  $I_{x,y}$  or  $V_x$  is being constructed. LCR compliancy is determined after any intersection between two or more edge-sequences is performed. LCR compliancy is determined if an edge-sequence or vertex-sequence incurred any refinement.*

**Definition 1.7.** *The K-rule is that no cell from an edge-sequence  $I_{x,y}$  or a vertex-sequence  $V_x$  can have all zero entries. If this is the case, then  $I_{x,y}$  or  $V_x$ , equals zero, and  $I_{x,y}$  is removed from its S-set, or  $V_x$  is removed from the vertex-sequence table. Note that their respective removals, is a refinement.*

*K-rule compliancy is determined for an edge-sequence  $I_{x,y}$  or a vertex-sequence  $V_x$ , if either  $I_{x,y}$  or  $V_x$  are being constructed. K-rule compliancy is determined after any intersection between two or more edge-sequences is performed. K-rule compliancy is determined if an edge-sequence or vertex-sequence incurred any refinement. And finally, the K-rule is violated if all the vertex-sequences associated with a clause, are zero. In such a case, it's reported that the 3-SAT is unsatisfiable.*

**Definition 1.8.** *A solution for a collection of  $c$  clauses must have a corresponding collection of edge-sequences, for some  $K_C$ . More precisely, the intersection of all the edge-sequences together, for a  $K_C$ , does not equal zero. ie. A solution  $K_C$  exists if  $\bigcap_{i,j} I_{i,j} \neq 0$ , where  $i$  and  $j$  are every pair of endpoints from the collection of edge-sequences for a  $K_C$ . A  $K_P$ ,  $p < c$ , exists if the set of all sub edge-sequences  $\mathcal{P}$  for  $K_P$  are such that the intersection of  $\mathcal{P}$  does not equal zero. ie. A  $K_P$  exists if  $\bigcap_{i,j} I_{i,j}^* \neq 0$ , where  $i$  and  $j$  are every pair of endpoints from the collection of sub edge-sequences for  $K_P$ . It is to be understood that an edge-sequence for a  $K_C$  or  $K_P$ , means the edge-sequence associated with the edge for a  $K_C$  or  $K_P$ .*

**Definition 1.9.** *A S-set is a collection of edge-sequences whose endpoints are from two clauses,  $C_i$  and  $C_j$  where  $i \neq j$ . The number of constructed edge-sequences to be a S-set is  $|C_i||C_j|$  minus the non edge-sequences of the form:  $I_{i,-i}$ . For 3-SAT, there can be at most 9 edge-sequences in a S-set.*

Now, we must define what it means to take an intersection or union of two or more edge-sequences. No intersections or unions are taken with vertex-sequences.

**Definition 1.10.** *We take the intersection or union of two  $n$  length edge-sequences,  $A$  and  $B$ , by comparing position  $i$  of  $A$  and  $B$ , using the Boolean rules for intersections (denoted by  $\cap$ ), and unions (denoted by  $\cup$ ), for all positions,  $i = 0, 1, 2, \dots, n-1$ .*

Recall that the entry for position  $i$  of  $A$  and  $B$ , is either 1 or 0.

Then, for an intersection, we have:

$$1_A \cap 0_B = 0_A \cap 1_B = 0_A \cap 0_B = 0. \text{ And } 1_A \cap 1_B = 1.$$

And for a union we have:

$$1_A \cup 0_B = 0_A \cup 1_B = 1_A \cup 1_B = 1. \text{ And } 0_A \cup 0_B = 0.$$

We provide serial code for this algorithm at: [polynomial3sat.org](http://polynomial3sat.org). This code includes pre-processing, but we remark that the algorithm described, does not require any pre-processing to remove duplicates or *pure* literals.

## 2 Description of the algorithm

### Construction of the edge and vertex sequences

Let  $n \leq 3c$ , where  $c$  is the number of remaining clauses and  $n$  is the sum of the sizes, for the  $c$  clauses. Then, after pre-processing, the  $n$  vertex-sequences, grouped by clause association, are constructed first, as outlined in definition 1.4, and then *LCR* and *K*-rule are applied. It would be common practice to order the clauses, and the literals within each clause, and use this same ordering for both the edge and vertex sequences. After pre-processing, the remaining clauses not removed, have at most, 9 edge-sequences constructed from them pairwise. The edge-sequences are constructed as outlined in definition 1.2, and then *LCR* and *K*-rule are applied. Observe that the number of edge-sequences would be less than  $\binom{n}{2}$ . It must always be less than, because we did not subtract the over count of non-existent edges with i) both endpoints in the same clause or ii) the non edge-sequences between a literal and its negation. Of course, if each clause had just one literal and there was a solution, pre-processing would have presented the solution or pre-processing removed all literals from at least one clause, establishing unsatisfiability. Either way, no edge-sequences would have been constructed. Each pair of clauses from the collection of  $c$  clauses, forms a *S*-set. Thus, the number of *S*-sets is  $\binom{c}{2}$ , where any *S*-set contains at most, 9 edge-sequences. We shall denote a *S*-set with the indices of the two clauses used to construct its edge-sequences. ie.  $S_{i,j}$  has edge-sequences whose endpoints are from clauses  $C_i$  and  $C_j$ .

The refinement rules (four efficiency rules creating permanent refinements. see: [polynomial3sat.org](http://polynomial3sat.org)), refer to a bit-change occurring, an edge removed from its *S*-set, or a literal having a zero entry in every edge and vertex sequence, all being the result of the Comparing of *S*-sets. Given a collection of clauses, if any of these refinements occurred that were not the result of the Comparing

of  $S$ -sets, it was the result of  $LCR$  and  $K$ -rule compliancy, while constructing the edge-sequences and vertex-sequences. We shall apply the actions outlined in the refinement rules even when constructing the vertex and edge sequences. The example (at polynomial3sat.org), demonstrated that certain edge-sequences were zero upon construction, as they failed  $LCR$  and  $K$ -rule compliancy. To be systematic, we would first construct all the vertex-sequences as described in definition 1.4. Then, apply  $LCR$  and  $K$ -rule to all of the vertex-sequences. If the actions outlined in the refinement rules can be taken on any vertex-sequence, we do so. Next, we construct all the edge-sequences as described in definition 1.2. Then, apply  $LCR$  and  $K$ -rule to all of the edge-sequences. If the actions outlined in the refinement rules can be taken on any vertex or edge sequence, we do so. This process may be recursive where all refinements are permanent.

### The Comparing of the $S$ -sets

Essentially, the Comparing process is the algorithm. All data structures are simply updated based on the outcome of Comparing  $S$ -sets with one another.

**Definition 2.1.** *When every  $S$ -set has been Compared with every other  $S$ -set, we say that a **run** has been completed. If  $c$  clauses are considered, then there are  $\binom{c}{2}$   $S$ -sets, thus the number of  $S$ -set comparisons for a **run** is  $\binom{\binom{c}{2}}{2} < c^4$ .*

**Definition 2.2.** *A **round** is completed if the Comparing process stops because no refinement occurred during an entire **run**. We say that the  $S$ -sets are **equivalent** when a round is completed.*

We note that if the first round was not completed, it was the case that the vertex-sequences associated to a clause, were evaluated to be zero, so they were discarded. This violation of the  $K$ -rule stops all processing, as there is no solution for the collection of clauses given.

To Compare, we take two  $S$ -sets and **determine** if an edge-sequence  $I_{x,y}$  from one of the  $S$ -sets, can be refined by a union of the intersections between  $I_{x,y}$  with each of the edge-sequences, from the other  $S$ -set. Either  $I_{x,y}$  the edge-sequence under determination, is refined or it remains the same. This is done for each edge-sequence from both of the  $S$ -sets, in the same manner. As a matter of practice, we determine in turn, each edge-sequence from one  $S$ -set first, and then we determine in turn, each edge-sequence from the other  $S$ -set. Below, we construct two  $S$ -sets to describe in more detail all the steps to be taken.

Let the  $S$ -set:  $S_{i,j}$  contain 9 edge-sequences with endpoints from clauses:  $C_i = (1, 2, 3)$  and  $C_j = (a, b, c)$  giving:  $I_{1,a}, I_{1,b}, I_{1,c}, I_{2,a}, I_{2,b}, I_{2,c}, I_{3,a}, I_{3,b}, I_{3,c}$

Let the  $S$ -set:  $S_{k,l}$  contain 9 edge-sequences with endpoints from clauses:  $C_k = (4, 5, 6)$  and  $C_l = (d, e, f)$  giving:  $I_{4,d}, I_{4,e}, I_{4,f}, I_{5,d}, I_{5,e}, I_{5,f}, I_{6,d}, I_{6,e}, I_{6,f}$

If  $S_{i,j}$  and  $S_{k,l}$  have 9 edge-sequences each, then there were no negations between the literals in  $C_i$  and  $C_j$ , or between the literals in  $C_k$  and  $C_l$ .

We say that **determining** all edge-sequences from one  $S$ -set first, is doing one direction denoted by:  $S_{k,l} \stackrel{1}{\leftarrow} S_{i,j}$ . And, determining all edge-sequences once, for both  $S$ -sets, is doing both directions, denoted by:  $S_{k,l} \stackrel{1}{\rightleftharpoons} S_{i,j}$

Suppose we **determine**  $I_{4,d}$  of  $S_{k,l}$  first. Then we have:

$$(I_{1,a} \cap I_{4,d}) \cup (I_{1,b} \cap I_{4,d}) \cup (I_{1,c} \cap I_{4,d}) \cup (I_{2,a} \cap I_{4,d}) \cup (I_{2,b} \cap I_{4,d}) \cup (I_{2,c} \cap I_{4,d}) \cup (I_{3,a} \cap I_{4,d}) \cup (I_{3,b} \cap I_{4,d}) \cup (I_{3,c} \cap I_{4,d}) \leq I_{4,d}$$

The one efficiency present even in the original *naive* version, was eliminating any unnecessary intersections by one easy check. After an edge-sequence is selected for determination, say  $I_{x_r, y_s}$  where  $x_r \in C_r$ ,  $y_s \in C_s$ , the edge-sequences from the other  $S$ -set in the Comparing, that do not have 1 entries for the endpoints  $x_r$  and  $y_s$  when intersected with  $I_{x_r, y_s}$ , will be zero. Recall, that the two cells containing the endpoints, only have a single 1 entry corresponding to the two endpoints' positions, in their respective cells. Thus, if the other edge-sequence does not have a 1 entry for those same positions, the intersection will be zero, due to  $K$ -rule violation. So, after the selection of an edge-sequence to be determined, we select the edge-sequences from the other  $S$ -set, if they have 1 entries in both positions corresponding to the endpoints of  $I_{x_r, y_s}$ . Of course, we could also check to see if there are 1 entries in  $I_{x_r, y_s}$  corresponding to the endpoints of the other edge-sequence as well.

Let's suppose then, that every edge-sequence in  $S_{i,j}$  above, did have 1 entries for both endpoints  $4_k$  and  $d_l$  of  $I_{4,d}$ . Now suppose 6 intersections become zero, after the intersections were taken and  $LCR$  and  $K$ -rule was applied to each intersection, and we now have:

$$0 \cup (I_{1,b} \cap I_{4,d}) \cup 0 \cup (I_{2,a} \cap I_{4,d}) \cup 0 \cup 0 \cup 0 \cup 0 \cup (I_{3,c} \cap I_{4,d}) \leq I_{4,d}$$

$$\text{which is equivalent to: } (I_{1,b} \cap I_{4,d}) \cup (I_{2,a} \cap I_{4,d}) \cup (I_{3,c} \cap I_{4,d}) \leq I_{4,d}$$

Now, we take their union. Of course,  $LCR$  and  $K$ -rule compliancy need not be checked for any union, since it would not have been possible to create a new loner cell scenario, nor a cell with all zero entries.

Then, to complete the determination of  $I_{4,d}$  we need to compare position by position, to see if  $I_{4,d}$  has been refined.

More precisely, if we have:  $(I_{1,b} \cap I_{4,d}) \cup (I_{2,a} \cap I_{4,d}) \cup (I_{3,c} \cap I_{4,d}) = I_{4,d}$ , then  $I_{4,d}$  is unchanged, and we move on to the next edge-sequence to be determined. Or instead, we have:  $(I_{1,b} \cap I_{4,d}) \cup (I_{2,a} \cap I_{4,d}) \cup (I_{3,c} \cap I_{4,d}) < I_{4,d}$ , then  $I_{4,d}$

has been refined. We need to know which literals incurred a bit-change, and then we apply the appropriate actions of the refinements rules, and as always, followed by testing *LCR* and *K*-rule compliancy.

To summarize, an edge-sequence  $I_{4,d}$  to be **determined**, has 4 possible scenarios.

- 1)  $I_{4,d} \neq 0$ , and is unchanged.
- 2)  $I_{4,d} \neq 0$ , and is refined. We determine which literals had a bit-change and follow all appropriate refinement rule actions, recursively if need be.
- 3)  $I_{4,d} = 0$ , because  $(I_{1,b} \cap I_{4,d}) \cup (I_{2,a} \cap I_{4,d}) \cup (I_{3,c} \cap I_{4,d}) \leq I_{4,d}$  became zero after an appropriate refinement rule action was taken, and then *LCR* and *K*-rule was applied. In this case, edge-sequence  $I_{4,d}$  is discarded, and the actions stated in refinement rule 3 are taken, recursively if need be.
- 4) If each intersection:  $(I_{1,b} \cap I_{4,d})$ ,  $(I_{2,a} \cap I_{4,d})$  and  $(I_{3,c} \cap I_{4,d})$  had also been zero at the outset, then  $I_{4,d} = 0$ . And, as with 3),  $I_{4,d}$  is discarded and the actions stated in refinement rule 3 are taken, recursively if need be. When an edge-sequence equals zero, it was the case that none of the edge-sequences from a *S*-set could be part of a solution with the edge-sequence that was being determined.

Recall definition 2.1, that after all pairs of *S*-sets have been compared with each other, a **run** has been completed, which is  $\binom{c}{2} < c^4$ , for  $c$  clauses. Another **run** will commence if any refinement occurred. Eventually, a **run** will incur no refinement, not even a bit-change, at which point a **round** has been completed, and the *S*-sets are said to be **equivalent** which means at least one solution exists for the given 3-SAT. Or, the algorithm stopped because unsatisfiability had been discovered during **round** 1. Discovering unsatisfiability is when every literal from some clause is such that their vertex-sequences equal zero.

**Summary:** Pre-processing begins with a DIMACS file submission, providing clauses, where each clause is at most size 3. After pre-processing, edge and vertex sequences are constructed from the remaining clauses. The edge-sequences are grouped in their respective *S*-sets and the vertex-sequences are grouped by their clause association in the vertex-sequence table. When the vertex and edge sequences are *LCR* and *K*-rule compliant, the Comparing process begins. The Comparing process stops if: i) a clause was such that all its literals' vertex-sequences are zero, where it's reported that the given collection of clauses has no solution. Or, ii) one or more **runs** take place, where the last **run** had no refinement. This signals the end of a round, and the *S*-sets are said to be **equivalent**.

Proof of correctness and termination can be found at: [polynomial3sat.org](http://polynomial3sat.org).