

A new belief entropy: possible generalization of Deng entropy, Tsallis entropy and Shannon entropy

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Abstract

Shannon entropy is the mathematical foundation of information theory, Tsallis entropy is the roots of nonextensive statistical mechanics, Deng entropy was proposed to measure the uncertainty degree of belief function very recently. In this paper, A new entropy H was proposed to generalize Deng entropy, Tsallis entropy and Shannon entropy. The new entropy H can be degenerated to Deng entropy, Tsallis entropy, and Shannon entropy under different conditions, and also can maintains the mathematical property of Deng entropy, Tsallis entropy and Shannon entropy.

Keywords: Uncertainty measure, Entropy, Belief entropy, Deng entropy, Tsallis entropy, Shannon entropy, Dempster-Shafer evidence theory

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1. Introduction

How to measure the uncertainty has attracted much attention [1, 2]. A lot of theories has been developed, such as probability theory [3], fuzzy set theory [4], possibility theory [5], Dempster-Shafer evidence theory [6, 7], rough sets[8], DSMT[9, 10], generalized evidence theory [11] and D numbers[12, 13].

Since firstly proposed by Clausius in 1865 for thermodynamics [14], various types of entropies are presented, such as information entropy [15], Tsallis entropy [16], nonadditive entropy [17, 18, 19]. Information entropy [15], derived from the Boltzmann-Gibbs (BG) entropy [20] in thermodynamics and statistical mechanics, has been an indicator to measures uncertainty which is associated with the probability density function (PDF).

Dempster-Shafer theory evidence theory[6, 7] is mainly proposed to handle such uncertainty. In Dempster-Shafer evidence theory, the epistemic uncertainty simultaneously contains nonspecificity and discord [21] which are coexisting in a basic probability assignment function (BPA). Several uncertainty measures, such as AU [22, 23], AM [21], have been proposed to quantify such uncertainty in Dempster-Shafer theory. What's more, five axiomatic requirements have been further built in order to develop a justifiable measure. These five axiomatic requirements are range, probabilistic consistency, set consistency, additivity, subadditivity, respectively [24]. Existing methods are not efficient to measure uncertain degree of BPA. To address this issue, a new entropy, named as Deng entropy [25], is proposed to measure the uncertainty of basic probability assignment for the evidence theory. In this paper,

a discussin of the maximal value of Deng entropy has been discussed and proofed, which is useful for the real application of Deng entropy.

The paper is organized as follows. The preliminaries Dempster-Shafer evidence theory and Deng entropy and Tsallis entropy are briefly introduced in Section 2. Section 3 makes some discussions about the new entropy. Finally, this paper is concluded in Section 4.

2. Preliminaries

In this section, some preliminaries are briefly introduced.

2.1. Dempster-Shafer evidence theory

Dempster-Shafer theory (short for D-S theory) is presented by Dempster and Shafer [6, 7]. This theory is widely applied to uncertainty modeling [26, 27, 28, 29, 30], decision making [31, 32, 33, 34, 35, 36, 37, 38], information fusion [39, 40] and uncertain information processing [41, 42]. D-S theory has many advantages to handle uncertain information. First, D-S theory can handle more uncertainty in real world. In contrast to the probability theory in which probability masses can be only assigned to singleton subsets, in D-S theory the belief can be assigned to both singletons and compound sets. Second, in D-S theory, prior distribution is not needed before the combination of information from individual information sources. Third, D-S theory allows one to specify a degree of ignorance in some situations instead of being forced to be assigned for probabilities. Some basic concepts in D-S theory are introduced.

Let X be a set of mutually exclusive and collectively exhaustive events, indicated by

$$X = \{\theta_1, \theta_2, \dots, \theta_i, \dots, \theta_{|X|}\} \quad (1)$$

where set X is called a frame of discernment. The power set of X is indicated by 2^X , namely

$$2^X = \{\emptyset, \{\theta_1\}, \dots, \{\theta_{|X|}\}, \{\theta_1, \theta_2\}, \dots, \{\theta_1, \theta_2, \dots, \theta_i\}, \dots, X\} \quad (2)$$

For a frame of discernment $X = \{\theta_1, \theta_2, \dots, \theta_{|X|}\}$, a mass function is a mapping m from 2^X to $[0, 1]$, formally defined by:

$$m : 2^X \rightarrow [0, 1] \quad (3)$$

which satisfies the following condition:

$$m(\emptyset) = 0 \quad \text{and} \quad \sum_{A \in 2^X} m(A) = 1 \quad (4)$$

In D-S theory, a mass function is also called a basic probability assignment (BPA). Assume there are two BPAs indicated by m_1 and m_2 , the Dempster's rule of combination is used to combine them as follows:

$$m(A) = \begin{cases} \frac{1}{1-K} \sum_{B \cap C = A} m_1(B)m_2(C), & A \neq \emptyset; \\ 0, & A = \emptyset. \end{cases} \quad (5)$$

with

$$K = \sum_{B \cap C = \emptyset} m_1(B)m_2(C) \quad (6)$$

Note that the Dempster's rule of combination is only applicable to such two BPAs which satisfy the condition $K < 1$.

2.2. Deng entropy

With the range of uncertainty mentioned above, Deng entropy [25] can be presented as follows

$$E_d = - \sum_i m(F_i) \log \frac{m(F_i)}{2^{|F_i|} - 1} \quad (7)$$

where, F_i is a proposition in mass function m , and $|F_i|$ is the cardinality of F_i . As shown in the above definition, Deng entropy, formally, is similar with the classical Shannon entropy, but the belief for each proposition F_i is divided by a term $(2^{|F_i|} - 1)$ which represents the potential number of states in F_i (of course, the empty set is not included).

Specially, Deng entropy can definitely degenerate to the Shannon entropy if the belief is only assigned to single elements. Namely,

$$E_d = - \sum_i m(\theta_i) \log \frac{m(\theta_i)}{2^{|\theta_i|} - 1} = - \sum_i m(\theta_i) \log m(\theta_i)$$

2.3. Tsallis entropy

For a discrete random variable $X = \{X_i, i = 1, 2, \dots, N\}$ that has a probability distribution $P = \{p_i, i = 1, 2, \dots, N\}$ [p_i is the probability of $X = x_i$]. Scaling p_i to p_i^m , where m is any real number, Tsallis Entropy [16] H_m can be denoted as

$$H_m = k \frac{1 - \sum_{i=1}^N p_i^m}{m - 1} = \frac{k}{m - 1} \sum_{i=1}^N [p_i - p_i^m] \quad (8)$$

where k is often taken as unity. For $m \rightarrow 1$, the Tsallis entropy reduces to Shannon entropy

3. Proposed new Entropy: possible generalization of Deng entropy, Tsallis Entropy, Shannon entropy

Assume F_i is the focal element and $m(F_i)$ is the basic probability assignment for F_i , then the possible generalization of Deng entropy and Tsallis entropy can be defined as H

$$H = \frac{1 - \sum_i [m(F_i)]^m}{m-1} + \sum_i m(F_i) \log(2^{|F_i|} - 1) \quad (9)$$

where $i = 1, 2, \dots, 2^X - 1$, and X is the scale of the frame of discernment.

(1) For $m \rightarrow 1$, the new entropy H reduces to Deng entropy, namely

$$E_d = - \sum_i m(F_i) \log \frac{m(F_i)}{2^{|F_i|} - 1} \quad (10)$$

Proof. For $m \rightarrow 1$, the new entropy can be shown as

$$H_{m \rightarrow 1} = \lim_{m \rightarrow 1} \left\{ \frac{1 - \sum_i [m(F_i)]^m}{m-1} + \sum_i m(F_i) \log(2^{|F_i|} - 1) \right\} \quad (11)$$

Then

$$H_{m \rightarrow 1} = \lim_{m \rightarrow 1} \left\{ \frac{1 - \sum_i [m(F_i)]^m}{m-1} \right\} + \sum_i m(F_i) \log(2^{|F_i|} - 1) \quad (12)$$

Because

$$\begin{aligned} & \lim_{m \rightarrow 1} \left\{ \frac{1 - \sum_i [m(F_i)]^m}{m-1} \right\} \\ &= \lim_{m \rightarrow 1} \frac{\frac{\partial}{\partial m} \left\{ 1 - \sum_i [m(F_i)]^m \right\}}{\frac{\partial}{\partial m} (m-1)} \\ &= - \lim_{m \rightarrow 1} \sum_i [m(F_i)]^m \log [m(F_i)] \\ &= - \sum_i m(F_i) \log [m(F_i)] \end{aligned} \quad (13)$$

Then

$$\begin{aligned}
H_{m \rightarrow 1} &= - \sum_i m(F_i) \log [m(F_i)] + \sum_i m(F_i) \log (2^{|F_i|} - 1) \\
&= - \sum_i \{ m(F_i) \log [m(F_i)] - m(F_i) \log (2^{|F_i|} - 1) \} \\
&= - \sum_i m(F_i) \log \frac{m(F_i)}{2^{|F_i|} - 1}
\end{aligned} \tag{14}$$

Hence

$$H_{m \rightarrow 1} = E_d = - \sum_i m(F_i) \log \frac{m(F_i)}{2^{|F_i|} - 1} \tag{15}$$

End proof □

(2) For the belief is only assigned to single elements, the new entropy H reduces to Tsallis entropy, namely

$$H_m = k \frac{1 - \sum_{i=1}^N p_i^m}{m-1} = \frac{k}{m-1} \sum_{i=1}^N [p_i - p_i^m] \tag{16}$$

Proof. For the belief is only assigned to single elements, the $|F_i| = 1$, we can easily get that

$$\sum_i m(F_i) \log (2^{|F_i|} - 1) = 0 \tag{17}$$

Hence

$$\begin{aligned}
H &= \frac{1 - \sum_i [m(F_i)]^m}{m-1} + \sum_i m(F_i) \log (2^{|F_i|} - 1) \\
&= \frac{1 - \sum_i [m(F_i)]^m}{m-1} = \frac{1 - \sum_i [m(\theta_i)]^m}{m-1} = H_s
\end{aligned} \tag{18}$$

□

End proof

(3) For $m \rightarrow 1$ and the belief is only assigned to single elements, the new entropy H reduces to Shannon entropy, namely

$$H = - \sum_i m(\theta_i) \log \frac{m(\theta_i)}{2^{|\theta_i|} - 1} = - \sum_i m(\theta_i) \log m(\theta_i) \tag{19}$$

Proof. When $m \rightarrow 1$, from Eq. (15), we can get

$$H_{m \rightarrow 1} = E_d = - \sum_i m(F_i) \log \frac{m(F_i)}{2^{|F_i|} - 1} \quad (20)$$

When the belief is only assigned to single elements, the $|F_i| = 1$, we can easily get that

$$H = - \sum_i m(F_i) \log \frac{m(F_i)}{2^{|F_i|} - 1} = - \sum_i m(\theta_i) \log m(\theta_i) \quad (21)$$

End proof □

4. Conclusion

Shannon entropy is the mathematical foundation of information theory, Tsallis entropy is the roots of nonextensive statistical mechanics, Deng entropy was proposed to measure the uncertainty degree of belief function very recently. In this paper, A new entropy H was proposed to generalize Deng entropy, Tsallis entropy and Shannon entropy. The new entropy H can be degenerated to Deng entropy, Tsallis entropy, and Shannon entropy under different conditions, and also can maintains the mathematical property of Deng entropy, Tsallis entropy and Shannon entropy.

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