

A Note About A Solution of Navier-Stokes Equations

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Abstract. This note represents an attempt to give a solution of Navier-Stokes equations under the assumptions (A) of the problem as described by the Clay Institute [1]. We give a proof of the condition of bounded energy when the velocity vector u and vorticity vector $\Omega = \text{curl}(u)$ are collinear.

1. Introduction

As it was described in the paper cited above, the Euler and Navier-Stokes equations describe the motion of a fluid in \mathbb{R}^n ($n = 2$ or 3). These equations are to be solved for an unknown velocity vector $u(x, t) = (u_i(x, t))_{i=1, n} \in \mathbb{R}^n$ and pressure $p(x, t) \in \mathbb{R}$ defined for position $x \in \mathbb{R}^n$ and time $t \geq 0$.

Here we are concerned with incompressible fluids filling all of \mathbb{R}^n . The Navier-Stokes equations are given by:

$$\frac{\partial u_i}{\partial t} + \sum_{j=1}^n u_j \frac{\partial u_i}{\partial x_j} = \nu \Delta u_i - \frac{\partial p}{\partial x_i} + f_i(x, t) \quad i \in \{1, \dots, n\} \quad (x \in \mathbb{R}^n, t \geq 0) \quad (1)$$

$$\text{div} u = \sum_{i=1}^n \frac{\partial u_i}{\partial x_i} = 0 \quad (x \in \mathbb{R}^n, t \geq 0) \quad (2)$$

with the initial conditions:

$$u(x, 0) = u^o(x) \quad (x \in \mathbb{R}^n) \quad (3)$$

where $u^o(x)$ a given vector function of class C^∞ , $f_i(x, t)$ are the components of a given external force (e.g gravity), ν is a positive coefficient (viscosity), and Δ is the Laplacian in the space variables. Euler equations are equations (1) (2) (3) with $\nu = 0$.

2. The Navier-Stokes Equations

We try to present a solution to the Navier-Stokes equations following assumptions (A) as described in [1] that summarized here:

* (A) **Existence and smooth solutions** $\in \mathbb{R}^3$ **the Navier-Stokes equations:**

- Take $\nu > 0$. Let $u^0(x)$ a smooth function such that $\text{div}(u^0(x)) = 0$ and satisfying:

$$\|\partial_{x_j}^\delta u^0(x)\| \leq C_{\delta K} (1 + \|x\|)^{-K} \text{ in } \mathbb{R}^3 \quad \forall \delta, K \quad (4)$$

- Take $f \equiv 0$. Then show that there are functions $p(x, t), u(x, t)$ of class C^∞ on $\mathbb{R}^3 \times [0, +\infty)$ satisfying (1),(2),(3),(4) and:

$$\int_{\mathbb{R}^3} \|u(x, t)\|^2 dx < C \quad \forall t \geq 0, \text{ (bounded energy)} \quad (5)$$

We consider the Navier-Stokes equations in this case, we take $\nu > 0$ and $f_i \equiv 0$, then equations (1) are written:

$$\frac{\partial u_i}{\partial t} + \sum_{j=1}^n u_j \frac{\partial u_i}{\partial x_j} - \nu \Delta u_i = -\frac{\partial p}{\partial x_i} \quad (6)$$

Considering the case $n = 3$, we write:

$$\frac{\partial u_1}{\partial t} + u_1 \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_1}{\partial y} + u_3 \frac{\partial u_1}{\partial z} - \nu \Delta u_1 = -\frac{\partial p}{\partial x} \quad (7)$$

$$\frac{\partial u_2}{\partial t} + u_1 \frac{\partial u_2}{\partial x} + u_2 \frac{\partial u_2}{\partial y} + u_3 \frac{\partial u_2}{\partial z} - \nu \Delta u_2 = -\frac{\partial p}{\partial y} \quad (8)$$

$$\frac{\partial u_3}{\partial t} + u_1 \frac{\partial u_3}{\partial x} + u_2 \frac{\partial u_3}{\partial y} + u_3 \frac{\partial u_3}{\partial z} - \nu \Delta u_3 = -\frac{\partial p}{\partial z} \quad (9)$$

As:

$$dp = \frac{\partial p}{\partial x} dx + \frac{\partial p}{\partial y} dy + \frac{\partial p}{\partial z} dz + \frac{\partial p}{\partial t} dt \quad (10)$$

Using equations (7 - 8 - 9), we get:

$$\begin{aligned} dp = & - \left(\frac{\partial u_1}{\partial t} - \nu \Delta u_1 + u_1 \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_1}{\partial y} + u_3 \frac{\partial u_1}{\partial z} \right) dx \\ & - \left(\frac{\partial u_2}{\partial t} - \nu \Delta u_2 + u_1 \frac{\partial u_2}{\partial x} + u_2 \frac{\partial u_2}{\partial y} + u_3 \frac{\partial u_2}{\partial z} \right) dy \\ & - \left(\frac{\partial u_3}{\partial t} - \nu \Delta u_3 + u_1 \frac{\partial u_3}{\partial x} + u_2 \frac{\partial u_3}{\partial y} + u_3 \frac{\partial u_3}{\partial z} \right) dz + \frac{\partial p}{\partial t} dt \end{aligned} \quad (11)$$

But:

$$\frac{du^2}{2} = \frac{d(u_1^2 + u_2^2 + u_3^2)}{2} = \sum_i u_i du_i = \sum_i u_i (\partial_x u_i dx + \partial_y u_i dy + \partial_z u_i dz + \partial_t u_i dt) \quad (12)$$

noting $\partial_x = \frac{\partial}{\partial x}$. Then equation (11) becomes:

$$\begin{aligned}
 -dp + \partial_t p \cdot dt &= \left(\frac{\partial u_1}{\partial t} - \nu \Delta u_1 + u_2 \frac{\partial u_1}{\partial y} + u_3 \frac{\partial u_1}{\partial z} - u_2 \frac{\partial u_2}{\partial x} - u_3 \frac{\partial u_3}{\partial x} \right) dx \\
 &+ \left(\frac{\partial u_2}{\partial t} - \nu \Delta u_2 + u_1 \frac{\partial u_2}{\partial x} + u_3 \frac{\partial u_2}{\partial z} - u_1 \frac{\partial u_1}{\partial y} - u_3 \frac{\partial u_3}{\partial y} \right) dy \\
 &+ \left(\frac{\partial u_3}{\partial t} - \nu \Delta u_3 + u_1 \frac{\partial u_3}{\partial x} + u_2 \frac{\partial u_3}{\partial y} - u_1 \frac{\partial u_1}{\partial z} - u_2 \frac{\partial u_2}{\partial z} \right) dz \\
 &- \left(u_1 \frac{\partial u_1}{\partial t} + u_2 \frac{\partial u_2}{\partial t} + u_3 \frac{\partial u_3}{\partial t} \right) dt + d \left(\frac{u^2}{2} \right) \quad (13)
 \end{aligned}$$

Let Ω the vector $\text{curl}(u)$, then:

$$\Omega = \begin{pmatrix} \omega_1 \\ \omega_2 \\ \omega_3 \end{pmatrix} = \begin{vmatrix} \partial_x & & \\ & \partial_y & \\ & & \partial_z \end{vmatrix} \wedge \begin{vmatrix} u_1 \\ u_2 \\ u_3 \end{vmatrix} = \begin{pmatrix} \partial_y u_3 - \partial_z u_2 \\ \partial_z u_1 - \partial_x u_3 \\ \partial_x u_2 - \partial_y u_1 \end{pmatrix} \quad (14)$$

Then, equation (13) is written as follows:

$$\begin{aligned}
 -d \left(p + \frac{u^2}{2} \right) &= -\partial_t \left(p + \frac{1}{2} u^2 \right) dt + \left(\frac{\partial u_1}{\partial t} - \nu \Delta u_1 - u_2 \omega_3 + u_3 \omega_2 \right) dx + \\
 &\left(\frac{\partial u_2}{\partial t} - \nu \Delta u_2 + u_1 \omega_3 - u_3 \omega_1 \right) dy + \left(\frac{\partial u_3}{\partial t} - \nu \Delta u_3 - u_1 \omega_2 + u_2 \omega_1 \right) dz \quad (15)
 \end{aligned}$$

We write the above equation in the form:

$$\begin{aligned}
 d \left(p + \frac{u^2}{2} \right) &= \partial_t \left(p + \frac{1}{2} u^2 \right) dt + \left(-\frac{\partial u_1}{\partial t} + \nu \Delta u_1 + u_2 \omega_3 - u_3 \omega_2 \right) dx + \\
 &\left(-\frac{\partial u_2}{\partial t} + \nu \Delta u_2 - u_1 \omega_3 + u_3 \omega_1 \right) dy \\
 &+ \left(-\frac{\partial u_3}{\partial t} + \nu \Delta u_3 + u_1 \omega_2 - u_2 \omega_1 \right) dz \quad (16)
 \end{aligned}$$

or as:

$$d \left(p + \frac{u^2}{2} \right) = \partial_t \left(p + \frac{1}{2} u^2 \right) dt + A \cdot dx + B \cdot dy + C \cdot dz \quad (17)$$

with:

$$A = u_2 \omega_3 - u_3 \omega_2 - \frac{\partial u_1}{\partial t} + \nu \Delta u_1 \quad (18)$$

$$B = u_3 \omega_1 - u_1 \omega_3 - \frac{\partial u_2}{\partial t} + \nu \Delta u_2 \quad (19)$$

$$C = u_1 \omega_2 - u_2 \omega_1 - \frac{\partial u_3}{\partial t} + \nu \Delta u_3 \quad (20)$$

Let h the vector:

$$h = \begin{pmatrix} A \\ B \\ C \end{pmatrix} \quad (21)$$

The left member of equation (17) is a total differential, we can write the conditions:

$$\partial_y A = \partial_x B \quad (22)$$

$$\partial_z A = \partial_x C \quad (23)$$

$$\partial_z B = \partial_y C \quad (24)$$

Which give:

$$\text{curl}(h) = \begin{pmatrix} \partial_y C - \partial_z B \\ \partial_z A - \partial_x C \\ \partial_x B - \partial_y A \end{pmatrix} = 0 \quad (25)$$

But h is written as:

$$h = \begin{pmatrix} A \\ B \\ C \end{pmatrix} = u \wedge \Omega - \frac{\partial}{\partial t} \begin{pmatrix} u_1 \\ u_2 \\ u_2 \end{pmatrix} + \nu \Delta \begin{pmatrix} u_1 \\ u_2 \\ u_2 \end{pmatrix} = u \wedge \Omega - \frac{\partial u}{\partial t} + \nu \Delta u \quad (26)$$

The conditions (22 - 23 - 24) are summarized by $\text{curl}(h) = 0$:

$$\boxed{\text{curl}(u \wedge \Omega) = \frac{\partial \Omega}{\partial t} - \nu \Delta \Omega} \quad (27)$$

because $\Omega = \text{curl}(u)$. Recall now the formula [2]:

$$\text{curl}(a \wedge b) = (b \cdot \nabla) \cdot a - (a \cdot \nabla) \cdot b + a \cdot \text{div} b - b \cdot \text{div} a \quad (28)$$

In our study, we have $a = u \implies \text{div} a = \text{div} u = \partial_x u_1 + \partial_y u_2 + \partial_z u_3 = 0$ and $b = \Omega = \text{curl}(u)$ then $\text{div} b = \text{div} \Omega = \text{div}(\text{curl}(u)) = 0$. As a result:

$$(\Omega \cdot \nabla) \cdot u - (u \cdot \nabla) \cdot \Omega = \frac{\partial \Omega}{\partial t} - \nu \Delta \Omega \quad (29)$$

Or in matrix form:

$$\begin{pmatrix} \frac{\partial u_1}{\partial x} & \frac{\partial u_1}{\partial y} & \frac{\partial u_1}{\partial z} \\ \frac{\partial u_2}{\partial x} & \frac{\partial u_2}{\partial y} & \frac{\partial u_2}{\partial z} \\ \frac{\partial u_3}{\partial x} & \frac{\partial u_3}{\partial y} & \frac{\partial u_3}{\partial z} \end{pmatrix} \cdot \begin{pmatrix} \omega_1 \\ \omega_2 \\ \omega_3 \end{pmatrix} - \begin{pmatrix} \frac{\partial \omega_1}{\partial x} & \frac{\partial \omega_1}{\partial y} & \frac{\partial \omega_1}{\partial z} \\ \frac{\partial \omega_2}{\partial x} & \frac{\partial \omega_2}{\partial y} & \frac{\partial \omega_2}{\partial z} \\ \frac{\partial \omega_3}{\partial x} & \frac{\partial \omega_3}{\partial y} & \frac{\partial \omega_3}{\partial z} \end{pmatrix} \cdot \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} = \nu \begin{pmatrix} \Delta \omega_1 \\ \Delta \omega_2 \\ \Delta \omega_3 \end{pmatrix} - \begin{pmatrix} \frac{\partial \omega_1}{\partial t} \\ \frac{\partial \omega_2}{\partial t} \\ \frac{\partial \omega_3}{\partial t} \end{pmatrix} \quad (30)$$

Let:

$$A(u) = \begin{pmatrix} \frac{\partial u_1}{\partial x} & \frac{\partial u_1}{\partial y} & \frac{\partial u_1}{\partial z} \\ \frac{\partial u_2}{\partial x} & \frac{\partial u_2}{\partial y} & \frac{\partial u_2}{\partial z} \\ \frac{\partial u_3}{\partial x} & \frac{\partial u_3}{\partial y} & \frac{\partial u_3}{\partial z} \end{pmatrix} \quad (31)$$

$$A(\Omega) = \begin{pmatrix} \frac{\partial \omega_1}{\partial x} & \frac{\partial \omega_1}{\partial y} & \frac{\partial \omega_1}{\partial z} \\ \frac{\partial \omega_2}{\partial x} & \frac{\partial \omega_2}{\partial y} & \frac{\partial \omega_2}{\partial z} \\ \frac{\partial \omega_3}{\partial x} & \frac{\partial \omega_3}{\partial y} & \frac{\partial \omega_3}{\partial z} \end{pmatrix} \quad (32)$$

In this case, equation (30) becomes:

$$\boxed{A(u).\Omega - A(\Omega).u = \nu\Delta\Omega - \frac{\partial\Omega}{\partial t}} \quad (33)$$

The equations (33) are the fundamental equations of this study. These are nonlinear partial differential equations of the third order. Their resolutions are the solutions of the Navier-Stokes equations.

3. The Study of The Fundamental Equations (33)

3.1. Preliminaries

Call respectively:

$$F(u, \Omega) = A(u).\Omega - A(\Omega).u \quad (34)$$

$$G(\Omega) = \nu\Delta\Omega - \frac{\partial\Omega}{\partial t} \quad (35)$$

If you exchange u, Ω in $-u, -\Omega$, we get:

$$F(-u, -\Omega) = F(u, \Omega) \quad (36)$$

$$G(-\Omega) = -G(\Omega) \quad (37)$$

According to equation (33), we get:

$$\begin{cases} F(u, \Omega) = G(\Omega) \\ F(-u, -\Omega) = G(-\Omega) = -G(\Omega) = F(u, \Omega) \end{cases} \implies G(\Omega) = 0 \implies F(u, \Omega) = 0 \quad (38)$$

It was therefore the differential system:

$$\left\{ \begin{array}{l} \nu \Delta \Omega - \frac{\partial \Omega}{\partial t} = 0 \\ A(u) \cdot \Omega - A(\Omega) \cdot u = 0 \\ \text{with } \Omega = \text{curl}(u) \\ \text{and } \text{curl}(u \wedge \Omega) = \nu \Delta \Omega - \frac{\partial \Omega}{\partial t} \implies \text{curl}(u \wedge \Omega) = 0 \end{array} \right. \quad (39)$$

under equation (27).

3.2. Case $\Omega \equiv 0$

In this case, obviously:

$$\begin{aligned} \nu \Delta \Omega - \frac{\partial \Omega}{\partial t} &= 0 \\ A(u) \cdot \Omega - A(\Omega) \cdot u &= 0 \end{aligned}$$

So:

$$\Omega = \text{curl}(u) = 0 \implies \left\{ \begin{array}{l} u \equiv 0 \text{ which is a contradiction,} \\ u = \text{a constant vector which is a contradiction,} \\ \exists \text{ a scalaire function } \Phi / u = \text{grad} \Phi \end{array} \right. \quad (40)$$

In the latter case, as $\Omega = \text{curl}(u) \implies \text{curl}(u) = 0$ then:

$$\left\{ \begin{array}{l} \frac{\partial u_1}{\partial y} = \frac{\partial u_2}{\partial x} \\ \frac{\partial u_2}{\partial z} = \frac{\partial u_3}{\partial y} \\ \frac{\partial u_3}{\partial x} = \frac{\partial u_1}{\partial z} \end{array} \right. \quad (41)$$

and as $\text{div}(u) = 0$, it is easily obtained:

$$\frac{\partial^2 u_1}{\partial x^2} + \frac{\partial^2 u_1}{\partial y^2} + \frac{\partial^2 u_1}{\partial z^2} = \Delta u_1 = 0 \quad (42)$$

Similarly, we have also:

$$\left\{ \begin{array}{l} \Delta u_2 = 0 \\ \Delta u_3 = 0 \end{array} \right. \quad (43)$$

Using $\text{div}(u) = 0$, we have also:

$$\Delta \Phi = 0 \quad (44)$$

Thus $\Phi = \Phi(x, y, z, t)$ is a harmonic function of (x, y, z) .

Equation (7) becomes:

$$\begin{aligned} \frac{\partial^2 \Phi}{\partial x \partial t} + \frac{\partial \Phi}{\partial x} \frac{\partial^2 \Phi}{\partial x^2} + \frac{\partial \Phi}{\partial y} \frac{\partial^2 \Phi}{\partial x \partial y} + \frac{\partial \Phi}{\partial z} \frac{\partial^2 \Phi}{\partial x \partial z} = \\ \nu \frac{\partial}{\partial x} \left[\frac{\partial^2 \Phi}{\partial x^2} + \frac{\partial^2 \Phi}{\partial y^2} + \frac{\partial^2 \Phi}{\partial z^2} \right] - \frac{\partial p}{\partial x} \end{aligned} \quad (45)$$

But $\Delta \Phi = 0$ then:

$$\frac{\partial}{\partial x} \left[\frac{2\partial \Phi}{\partial t} + \left(\frac{\partial \Phi}{\partial x} \right)^2 + \left(\frac{\partial \Phi}{\partial y} \right)^2 + \left(\frac{\partial \Phi}{\partial z} \right)^2 \right] = -\frac{\partial p}{\partial x} \quad (46)$$

And integrating with respect to x , we obtain:

$$p = \frac{\partial \Phi}{\partial t} - \frac{1}{2}u^2 + \psi_1(y, z, t) \quad (47)$$

Similarly, we also obtain:

$$p = -\frac{\partial \Phi}{\partial t} - \frac{1}{2}u^2 + \psi_2(x, z, t) \quad (48)$$

$$p = -\frac{\partial \Phi}{\partial t} - \frac{1}{2}u^2 + \psi_3(x, y, t) \quad (49)$$

As a result:

$$p + \frac{1}{2}u^2 - \psi_1(y, z, t) = p + \frac{1}{2}u^2 - \psi_2(x, z, t) = p + \frac{1}{2}u^2 - \psi_3(x, y, t) \quad (50)$$

Which gives:

$$\psi_1(t) = \psi_2(t) = \psi_3(t) = \psi(t) \quad (51)$$

a function that is added to the function Φ , and the result:

$$\Delta \Phi = 0 \quad (52)$$

$$\left. \frac{\partial \Phi(x, y, z, t)}{\partial x} \right|_{t=0} = u_1^0(x, y, z); \quad \left. \frac{\partial \Phi(x, y, z, t)}{\partial y} \right|_{t=0} = u_2^0(x, y, z) \quad (53)$$

$$\left. \frac{\partial \Phi(x, y, z, t)}{\partial z} \right|_{t=0} = u_3^0(x, y, z) \quad (54)$$

and:

$$\Delta u_i(x, y, z, t)|_{t=0} = \Delta u_i^0(x, y, z) = 0, \quad i = 1, n \quad (55)$$

$$p(x, y, z, t) = -\frac{\partial \Phi}{\partial t} - \frac{1}{2}u^2 = -\frac{\partial \Phi}{\partial t} - \frac{1}{2} \|\text{grad} \Phi\|^2 \quad (56)$$

3.3. Case Ω is not the zero function

We rewrite the differential system (39)

$$\begin{cases} \frac{\partial \Omega}{\partial t} - \nu \Delta \Omega = 0 \\ A(u) \cdot \Omega - A(\Omega) \cdot u = 0 \\ \text{with } \Omega = \text{curl}(u) \\ \text{and } \text{curl}(u \wedge \Omega) = \frac{\partial \Omega}{\partial t} - \nu \Delta \Omega \implies \text{curl}(u \wedge \Omega) = 0 \end{cases}$$

From $\text{curl}(u \wedge \Omega) = 0$, we deduce that:

1. There is a scalar function $\varphi(x, y, z)$ as $u \wedge \Omega = \text{grad} \varphi$.
2. $u \wedge \Omega = C$ where $C = (c_1, c_2, c_3)^T$ is a nonzero constant vector or vector function of t of $\mathbb{R} \rightarrow \mathbb{R}^3$.
3. $u \wedge \Omega = 0 \implies$ as u and Ω are not nuls, it is that u and Ω collinear.

3.3.1. Case 2. As $C = u \wedge \Omega$, one can write:

$$c_1 \cdot u_1 + c_2 \cdot u_2 + c_3 \cdot u_3 = 0 \quad (57)$$

because C is orthogonal to u . Let us differentiate the previous equation, respectively, to x, y and z , we get:

$$\begin{cases} c_1 \cdot \frac{\partial u_1}{\partial x} + c_2 \cdot \frac{\partial u_2}{\partial x} + c_3 \cdot \frac{\partial u_3}{\partial x} = 0 \\ c_1 \cdot \frac{\partial u_1}{\partial y} + c_2 \cdot \frac{\partial u_2}{\partial y} + c_3 \cdot \frac{\partial u_3}{\partial y} = 0 \\ c_1 \cdot \frac{\partial u_1}{\partial z} + c_2 \cdot \frac{\partial u_2}{\partial z} + c_3 \cdot \frac{\partial u_3}{\partial z} = 0 \end{cases} \quad (58)$$

that in matrix form:

$$A^T(u) \cdot C = 0 \quad (59)$$

where $A(u)$ is the matrix given by (31). However, the matrix $A(u)$ is the Jacobian matrix of $(x, y, z) \rightarrow u(x, y, z, t)$ therefore its determinant is nonzero. As a result, we deduce from (59) that the vector C is necessarily zero. It is the case 3.

3.3.2. Case 3 where $u // \Omega \Rightarrow u$ is a Beltrami vector field [3]. Assume now that u and Ω are collinear. Let $u // \Omega$.

Case $u = \lambda \Omega$ with $\lambda \in \mathbb{R}^*$. Then there is a coefficient $\lambda \neq 0$ such that:

$$u = \lambda \Omega \quad (60)$$

Using the equation:

$$A(u) \cdot \Omega - A(\Omega) \cdot u = 0$$

it is verified. Then we have the system:

$$\frac{\partial \Omega}{\partial t} - \nu \Delta \Omega = 0$$

But the above equation is the heat equation. Let the change of variables:

$$x = \nu X \quad (61)$$

$$y = \nu Y \quad (62)$$

$$z = \nu Z \quad (63)$$

$$t = \nu T \quad (64)$$

$$u(x, y, z, t) = U(X, Y, Z, T) \quad (65)$$

$$p(x, y, z, t) = P(X, Y, Z, T) \quad (66)$$

$$\Omega(x, y, z, t) = \bar{\Omega}(X, Y, Z, T) \quad (67)$$

Then:

$$\begin{aligned} \partial_x u dx + \partial_y u dy + \partial_z u dz + \partial_t u dt &= \partial_X U dX + \partial_Y U dY + \partial_Z U dZ + \partial_T U dT \\ \nu(\partial_x u dx + \partial_y u dy + \partial_z u dz + \partial_t u dt) &= \partial_X U dX + \partial_Y U dY + \partial_Z U dZ + \partial_T U dT \\ \partial_x u &= \frac{1}{\nu} \partial_X U, \partial_y u = \frac{1}{\nu} \partial_Y U, \partial_z u = \frac{1}{\nu} \partial_Z U, \partial_t u = \frac{1}{\nu} \partial_T U \end{aligned} \quad (68)$$

Then the equation

$$\frac{\partial \Omega}{\partial t} - \nu \Delta \Omega = 0$$

becomes:

$$\boxed{\frac{\partial \bar{\Omega}}{\partial T} - \Delta \bar{\Omega} = 0} \quad (69)$$

This is the heat equation!

4. Resolution of the Equation (69)

Noting that $U^0(X, Y, Z) = U^0(\mathbf{X}) = U(X, Y, Z, 0) = u(x, y, z, 0) = u^0(x, y, z)$ and $\bar{\Omega}^0 = \text{rot}U^0(\mathbf{X})$. Then the solution of (69) with $T \geq 0$ satisfying:

$$\bar{\Omega} \in \mathbb{R}^3 \text{ and of class } C^\infty(\mathbb{R}^3 \times [0, +\infty)) \quad (70)$$

$$\bar{\Omega}(\mathbf{X}, 0) = \bar{\Omega}^0(\mathbf{X}) \quad (71)$$

is given by [4]:

$$\bar{\Omega}(\mathbf{X}, T) = \frac{1}{2\sqrt{\pi}} \int_{\mathbb{R}^3} \frac{\bar{\Omega}^0(\alpha, \beta, \gamma)}{\sqrt{T}} e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{4T}} dV \quad (72)$$

where $dV = d\alpha d\beta d\gamma$.

4.1. Expression of U

We have:

$$U = \begin{pmatrix} U_1 \\ U_2 \\ U_3 \end{pmatrix} = \lambda \cdot \bar{\Omega} = \lambda \cdot \begin{pmatrix} \bar{\Omega}_1 \\ \bar{\Omega}_2 \\ \bar{\Omega}_3 \end{pmatrix} \quad (73)$$

Let :

$$U_1 = \lambda \bar{\Omega}_1 = \frac{\lambda}{2\sqrt{\pi}} \int_{\mathbb{R}^3} \frac{\bar{\Omega}_1^0(\alpha, \beta, \gamma)}{\sqrt{T}} e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{4T}} dV \quad (74)$$

$$U_2 = \lambda \bar{\Omega}_2 = \frac{\lambda}{2\sqrt{\pi}} \int_{\mathbb{R}^3} \frac{\bar{\Omega}_2^0(\alpha, \beta, \gamma)}{\sqrt{T}} e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{4T}} dV \quad (75)$$

$$U_3 = \lambda \bar{\Omega}_3 = \frac{\lambda}{2\sqrt{\pi}} \int_{\mathbb{R}^3} \frac{\bar{\Omega}_3^0(\alpha, \beta, \gamma)}{\sqrt{T}} e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{4T}} dV \quad (76)$$

4.2. Checking $\text{div}(U) = 0$

Let us calculate $\partial_X U_1$, we get:

$$\frac{\partial U_1}{\partial X} = \frac{-\lambda}{4\sqrt{\pi}} \int_{\mathbb{R}^3} \frac{(X-\alpha)\bar{\Omega}_1^0(\alpha, \beta, \gamma)}{T\sqrt{T}} e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{4T}} dV \quad (77)$$

We can write the above expression as follows:

$$\frac{\partial U_1}{\partial X} = \frac{-\lambda}{2\sqrt{\pi T}} \int_{\mathbb{R}^2} d\beta d\gamma \int_{\alpha=-\infty}^{\alpha=+\infty} \bar{\Omega}_1^0(\alpha, \beta, \gamma) \frac{\partial}{\partial \alpha} \left(e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{4T}} \right) d\alpha \quad (78)$$

Now we do an integration by parts, we get:

$$\begin{aligned} \frac{\partial U_1}{\partial X} &= \frac{-\lambda}{2\sqrt{\pi T}} \int_{\mathbb{R}^2} d\beta d\gamma \left[\bar{\Omega}_1^0(\alpha, \beta, \gamma) \cdot e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{4T}} \right]_{\alpha=-\infty}^{\alpha=+\infty} + \\ &\quad \frac{\lambda}{2\sqrt{\pi T}} \int_{\mathbb{R}^2} d\beta d\gamma \int_{\alpha=-\infty}^{\alpha=+\infty} e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{4T}} \frac{\partial \bar{\Omega}_1^0(\alpha, \beta, \gamma)}{\partial \alpha} \cdot d\alpha \quad (79) \end{aligned}$$

Taking into account the assumption that:

$$\|\partial_{X_j}^\delta U^0(\mathbf{X})\| \leq \nu C_{\delta K} (1 + \nu \|\mathbf{X}\|)^{-K} \text{ in } \mathbb{R}^3 \quad \forall \delta, K \quad (80)$$

where X_j denotes one of the coordinates X, Y, Z , and choosing $K > 1$, the first term of the right member is zero. Then:

$$\frac{\partial U_1}{\partial X} = \frac{\lambda}{2\sqrt{\pi T}} \int_{\mathbb{R}^2} d\beta d\gamma \int_{\alpha=-\infty}^{\alpha=+\infty} e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{4T}} \frac{\partial \bar{\Omega}_1^0(\alpha, \beta, \gamma)}{\partial \alpha} \cdot d\alpha \quad (81)$$

or:

$$\frac{\partial U_1}{\partial X} = \frac{\lambda}{2\sqrt{\pi T}} \int_{\mathbb{R}^3} e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{4T}} \frac{\partial \bar{\Omega}_1^0(\alpha, \beta, \gamma)}{\partial \alpha} \cdot dV \quad (82)$$

As a result:

$$\text{div}(U) = \sum_{X_j} \frac{\partial U_j}{\partial X_j} = \frac{\lambda}{2\sqrt{\pi T}} \int_{\mathbb{R}^3} e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{4T}} \sum_{\alpha_j} \frac{\partial \bar{\Omega}_j^0(\alpha, \beta, \gamma)}{\partial \alpha} \cdot dV = 0 \quad (83)$$

because $\bar{\Omega}^0(\alpha, \beta, \gamma)$ satisfies $div(\bar{\Omega}^0) = \sum_{\alpha_j} \frac{\partial \bar{\Omega}_j^0(\alpha, \beta, \gamma)}{\partial \alpha_j} = 0$.

4.3. Estimation of $\int_{\mathbb{R}^3} \|U(\mathbf{X}, T)\|^2 dV$

We have:

$$\begin{aligned} \|U(\mathbf{X}, T)\|^2 &= \sum_i U_i^2 = \lambda^2 \|\bar{\Omega}(\mathbf{X}, T)\|^2 = \\ &= \frac{\lambda^2}{4\pi T} \left\| \int_{\mathbb{R}^3} \bar{\Omega}^0(\alpha, \beta, \gamma) \cdot e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{4T}} dV \right\|^2 \\ &\leq \frac{\lambda^2}{4\pi T} \int_{\mathbb{R}^3} \|\bar{\Omega}^0(\alpha, \beta, \gamma)\|^2 \cdot e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{2T}} dV \end{aligned} \quad (84)$$

As :

$$\|\bar{\Omega}^0(\alpha, \beta, \gamma)\|^2 = (\omega_1^{(0)})^2 + (\omega_2^{(0)})^2 + (\omega_3^{(0)})^2$$

and taking into account the assumption that:

$$|\partial_{x_j}^\delta u_i^0(\mathbf{x})| \leq C_{\delta K} (1 + \|\mathbf{x}\|)^{-K} \text{ in } \mathbb{R}^3 \quad \forall \delta, K \text{ with } \|\mathbf{x}\| = \sqrt{x^2 + y^2 + z^2}$$

and passing to the coordinates (X, Y, Z) , we have the inequalities:

$$\begin{aligned} \left| \frac{\partial^\delta U_i^0(\mathbf{X})}{\partial X_j} \right| &\leq \nu C_{\delta K} (1 + \nu \|\mathbf{X}\|)^{-K} \text{ in } \mathbb{R}^3 \quad \forall \delta, K \in \mathbb{R} \\ &\text{with } \|\mathbf{X}\| = \sqrt{X^2 + Y^2 + Z^2} \end{aligned} \quad (85)$$

But:

$$(\omega_i^{(0)})^2 = \left(\frac{\partial u_k}{\partial x_j} - \frac{\partial u_j}{\partial x_k} \right)^2 \leq \left(\left| \frac{\partial u_k}{\partial x_j} \right| + \left| \frac{\partial u_j}{\partial x_k} \right| \right)^2 \leq 4\nu^2 C_K^2 (1 + \nu \|X\|)^{-2K} \quad (86)$$

then :

$$\|\bar{\Omega}^0(\alpha, \beta, \gamma)\|^2 \leq 12\nu^2 C_K^2 (1 + \nu \|X\|)^{-2K} = 12\nu^2 C_K^2 (1 + \nu \|\sqrt{\alpha^2 + \beta^2 + \gamma^2}\|)^{-2K} \quad (87)$$

As a result:

$$\|U(\mathbf{X}, T)\|^2 \leq \frac{3\nu^2 \lambda^2 C_K^2}{\pi T} \int_{\mathbb{R}^3} \frac{e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{2T}}}{(1 + \nu \|\sqrt{\alpha^2 + \beta^2 + \gamma^2}\|)^{2K}} d\alpha d\beta d\gamma \quad (88)$$

Let us now majorize $\int_{\mathbb{R}^3} \|u(\mathbf{x}, t)\|^2 dx dy dz$:

$$\begin{aligned} \int_{\mathbb{R}^3} \|u(\mathbf{x}, t)\|^2 dx dy dz &= \int_{\mathbb{R}^3} \|U(\mathbf{X}, T)\|^2 dx dy dz = \nu^3 \int_{\mathbb{R}^3} \|U(\mathbf{X}, T)\|^2 dX dY dZ \\ &\leq \frac{3\nu^5 \lambda^2 C_K^2}{\pi T} \int_{\mathbb{R}^3} \left[\int_{\mathbb{R}^3} \frac{e^{-\frac{(X-\alpha)^2 + (Y-\beta)^2 + (Z-\gamma)^2}{2T}}}{(1 + \nu \|\sqrt{\alpha^2 + \beta^2 + \gamma^2}\|)^{2K}} d\alpha d\beta d\gamma \right] dX dY dZ \end{aligned} \quad (89)$$

As the integral $\int_{\mathbb{R}^3} e^{-X^2-Y^2-Z^2} dXdYdZ < +\infty$, we can permute the two triple integrals of the above equation. Let:

$$\tau_0 = \frac{3\nu^5 \lambda^2 C_K^2}{\pi} \quad (90)$$

we obtain:

$$\int_{\mathbb{R}^3} \|u(\mathbf{x}, t)\|^2 dx dy dz \leq \frac{\tau_0}{T} \int_{\mathbb{R}^3} \left[\int_{\mathbb{R}^3} e^{-\frac{(X-\alpha)^2+(Y-\beta)^2+(Z-\gamma)^2}{2T}} dXdYdZ \right] \frac{d\alpha d\beta d\gamma}{(1+\nu\|\sqrt{\alpha^2+\beta^2+\gamma^2}\|)^{2K}} \quad (91)$$

Let:

$$I = \int_{\mathbb{R}^3} e^{-\frac{(X-\alpha)^2+(Y-\beta)^2+(Z-\gamma)^2}{2T}} dXdYdZ \quad (92)$$

and let the following change of variables:

$$\begin{cases} \bar{X} = \frac{X-\alpha}{\sqrt{2T}} \implies dX = \sqrt{2T}d\bar{X} & \text{et } \bar{X}^2 = \frac{(X-\alpha)^2}{2T} \\ \bar{Y} = \frac{Y-\beta}{\sqrt{2T}} \implies dY = \sqrt{2T}d\bar{Y} & \text{et } \bar{Y}^2 = \frac{(Y-\beta)^2}{2T} \\ \bar{Z} = \frac{Z-\gamma}{\sqrt{2T}} \implies dZ = \sqrt{2T}d\bar{Z} & \text{et } \bar{Z}^2 = \frac{(Z-\gamma)^2}{2T} \end{cases} \quad (93)$$

I is written as:

$$I = (\sqrt{2T})^3 \left[\int_{-\infty}^{+\infty} e^{-\bar{X}^2} d\bar{X} \right]^3 = 2T\sqrt{2T} \left[2 \int_0^{+\infty} e^{-\xi^2} d\xi \right]^3 = 2T\sqrt{T} \cdot \pi\sqrt{\pi} = 2\pi T\sqrt{\pi T} \quad (94)$$

using the formula $2 \int_0^{+\infty} e^{-\xi^2} d\xi = \sqrt{\pi}$. Then the equation (91) becomes:

$$\int_{\mathbb{R}^3} \|u(\mathbf{x}, t)\|^2 dx dy dz \leq 2\tau_0\pi\sqrt{\pi T} \int_{\mathbb{R}^3} \frac{d\alpha d\beta d\gamma}{(1+\nu\|\sqrt{\alpha^2+\beta^2+\gamma^2}\|)^{2K}} \quad (95)$$

Let us now:

$$B = \int_{\mathbb{R}^3} \frac{d\alpha d\beta d\gamma}{(1+\nu\|\sqrt{\alpha^2+\beta^2+\gamma^2}\|)^{2K}} \quad (96)$$

and we use the spherical coordinates:

$$\begin{cases} \alpha = r \sin\theta \cos\varphi \\ \beta = r \sin\theta \sin\varphi \\ \gamma = r \cos\theta \end{cases} \quad (97)$$

the form of the volume $d\alpha d\beta d\gamma = r^2 \sin\theta dr d\theta d\varphi$ and B becomes:

$$B = \int_{\theta=0}^{\theta=\pi} \sin\theta d\theta \int_{\varphi=0}^{\varphi=2\pi} d\varphi \int_0^r \frac{r^2 dr}{(1+\nu r)^{2K}} = 4\pi \int_0^r \frac{r^2 dr}{(1+\nu r)^{2K}} \quad (98)$$

We take $K = 2$, the integral B is convergent when $r \rightarrow +\infty$. Let:

$$F = \lim_{r \rightarrow +\infty} \int_0^r \frac{r^2 dr}{(1+\nu r)^4} = \int_0^{+\infty} \frac{r^2 dr}{(1+\nu r)^4} = \int_0^1 \frac{r^2 dr}{(1+\nu r)^4} + \int_1^{+\infty} \frac{r^2 dr}{(1+\nu r)^4} \quad (99)$$

But :

$$\int_0^1 \frac{r^2 dr}{(1 + \nu r)^4} < \int_0^1 r^2 dr = \left[\frac{r^3}{3} \right]_0^1 = \frac{1}{3} \quad (100)$$

We calculate now $\int_1^{+\infty} \frac{r^2 dr}{(1 + \nu r)^4}$. Let the change of variables:

$$\xi = 1 + \nu r \Rightarrow r = \frac{\xi - 1}{\nu} \Rightarrow dr = \frac{d\xi}{\nu} \quad (101)$$

then:

$$\int_1^{+\infty} \frac{r^2 dr}{(1 + \nu r)^4} = \frac{1}{\nu^3} \int_{1+\nu}^{+\infty} \frac{\xi^2 - 2\xi + 1}{\xi^4} d\xi = l(\nu) \text{ avec } l(\nu) = \frac{3\nu^2 + 9\nu + 5}{\nu^3(1 + \nu)^3} \quad (102)$$

As a result:

$$B < 4\pi \left(\frac{1}{3} + l(\nu) \right) \quad (103)$$

Hence the important result:

$$\int_{\mathbb{R}^3} \|u(\mathbf{x}, t)\|^2 dx dy dz < 8\tau_0 \pi^2 \sqrt{\pi T} \left(\frac{1}{3} + l(\nu) \right) \quad (104)$$

or:

$$\boxed{\int_{\mathbb{R}^3} \|u(\mathbf{x}, t)\|^2 dx dy dz < +\infty \quad \forall t} \quad (105)$$

let:

$$\boxed{\int_{\mathbb{R}^3} \|U(\mathbf{X}, T)\|^2 dX dY dZ < +\infty \quad \forall T} \quad (106)$$

because:

$$\int_{\mathbb{R}^3} \|U(\mathbf{X}, T)\|^2 dX dY dZ = \frac{1}{\nu^3} \int_{\mathbb{R}^3} \|u(\mathbf{x}, t)\|^2 dx dy dz$$

5. The expression of $p(x, y, z, t)$

We rewrite equation (6):

$$\frac{\partial u_i}{\partial t} + \sum_{j=1}^n u_j \frac{\partial u_i}{\partial x_j} - \nu \Delta u_i = -\frac{\partial p}{\partial x_i}$$

It can be written under vectorial form:

$$\nabla p = \nu \Delta u - \frac{\partial u}{\partial t} - A(u).u \quad (107)$$

with the matrice $A(u)$ given by (31). As $u = \lambda \Omega$ and $\nu \Delta \Omega - \frac{\partial \Omega}{\partial t} = 0$, then the equation (107) becomes:

$$\nabla p = -A(u).u \quad (108)$$

As $\Omega \in \mathbb{R}^3$ and of class $C^\infty(\mathbb{R}^3 \times [0, +\infty))$, see equation (70), then $u, \partial_i u$ are of class $C^\infty(\mathbb{R}^3 \times [0, +\infty)) \Rightarrow p(x, y, z, t)$ also.

6. Conclusion

In this work, we have obtained a solution u that verifies the conditions (A) of existence and smooth solutions $\ni \mathbb{R}^3$ of the Navier-Stokes equation. It remains the study of the cases:

- $u = \lambda \Omega$, with λ is a function of (x, y, z, t) ;
- there is a scalar function $\varphi(x, y, z)$ and $u \wedge \Omega = \text{grad}\varphi$.

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