#### SPECIAL RELATIVITY WITH MASSIVE AND NON-MASSIVE PARTICLES

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In special relativity, this article presents a relativistic dynamics of massive and non-massive particles which can be applied in any inertial reference frame.

#### Introduction

In special relativity, the total position ( $\bar{\mathbf{r}}$ ) of a (massive or non-massive) particle is always zero.

 $\bar{\mathbf{r}} = 0$ 

The total position  $(\bar{\mathbf{r}})$  of a (massive or non-massive) particle is defined by the kinetic position  $(\hat{\mathbf{r}})$  and the dynamic position  $(\check{\mathbf{r}})$  as follows:

 $\hat{\mathbf{r}} - \check{\mathbf{r}} = 0$ 

The kinetic position ( $\hat{\mathbf{r}}$ ) of a (massive or non-massive) particle is given by:

$$\hat{\mathbf{r}} \doteq \frac{1}{\mu} \int m \, \mathbf{v} \, dt$$

where  $(\mu)$  is an arbitrary (universal) constant, (m) is the relativistic mass of the particle,  $(\mathbf{v})$  is the velocity of the particle and (t) is time.

The dynamic position ( $\check{\mathbf{r}}$ ) of a (massive or non-massive) particle is given by:

$$\check{\mathbf{r}} \doteq \frac{1}{\mu} \iint \mathbf{F} \, dt \, dt$$

where  $(\mu)$  is the arbitrary (universal) constant,  $(\mathbf{F})$  is the net force acting on the particle and (t) is time.

The relativistic mass (m) of a massive particle is given by:

$$m \doteq \frac{m_o}{\sqrt{1 - \frac{v^2}{c^2}}}$$

where  $(m_o)$  is the rest mass of the massive particle, (v) is the speed of the massive particle and (c) is the speed of light in vacuum.

The relativistic mass (m) of a non-massive particle is given by:

$$m \doteq \frac{h\nu}{c^2}$$

where ( h ) is the Planck constant, (  $\nu$  ) is the frequency of the non-massive particle and ( c ) is the speed of light in vacuum.

Now, the total position ( $\bar{\mathbf{r}}$ ) of a (massive or non-massive) particle can also be expressed as follows:

$$\frac{1}{\mu} \left[ \int m \, \mathbf{v} \, dt - \iint \mathbf{F} \, dt \, dt \right] = 0$$

Differentiating the above equation with respect to time, yields:

$$\frac{1}{\mu} \left[ m \mathbf{v} - \int \mathbf{F} \, dt \right] = 0$$

Differentiating again with respect to time, we have:

$$\frac{1}{\mu} \left[ m \mathbf{a} + \frac{dm}{dt} \mathbf{v} - \mathbf{F} \right] = 0$$

Multiplying by (  $\mu$  ) and rearranging, we finally obtain:

$$\mathbf{F} = m \mathbf{a} + \frac{dm}{dt} \mathbf{v}$$

This equation ( similar to Newton's second law for  $v \ll c$  ) will be used in the next section of this article.

### The Relativistic Dynamics

If we consider a (massive or non-massive) particle with relativistic mass m then the linear momentum **P** of the particle, the angular momentum **L** of the particle, the net force **F** acting on the particle, the work W done by the net force acting on the particle, and the kinetic energy K of the particle, for an inertial reference frame, are given by:

$$\mathbf{P} \doteq m \mathbf{v}$$
$$\mathbf{L} \doteq \mathbf{P} \times \mathbf{r}$$
$$\mathbf{F} = \frac{d\mathbf{P}}{dt} = m \mathbf{a} + \frac{dm}{dt} \mathbf{v}$$
$$W \doteq \int_{1}^{2} \mathbf{F} \cdot d\mathbf{r} = \int_{1}^{2} \frac{d\mathbf{P}}{dt} \cdot d\mathbf{r} = \Delta \mathbf{K}$$
$$\mathbf{K} \doteq m c^{2}$$

where  $(\mathbf{r}, \mathbf{v}, \mathbf{a})$  are the position, the velocity and the acceleration of the particle relative to the inertial reference frame and (c) is the speed of light in vacuum. The kinetic energy  $(K_o)$  of a massive particle at rest is  $(m_o c^2)$ 

## **Bibliography**

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# Appendix

## System of Equations

$$\begin{bmatrix} \mathbf{I} \\ \downarrow dt \downarrow \\ \hline \mathbf{I} \\ \mathbf{I$$