

TEM waves guided between many conductors

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Abstract

Guided TEM waves have been extensively investigated between 2 conductors. The multiconductor case, in spite of some important publications in this direction, did not get into the mainstream of the electromagnetic education, and therefore deserves some more attention. The simple case of lossless multiconductor TEM waves in homogeneous media is a good approximation for many practical cases and is easily derivable by usage of potentials only. In this work we derive the formalism for lossless multiconductor TEM waves in homogeneous media, and show several examples for the usage of this formalism.

Keywords: TEM, guided waves, crosstalk

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I. INTRODUCTION

The purpose of this work is to show a simple derivation for TEM waves guided between many perfect conductors, in a homogeneous media and to develop multiconductor models and applications for several geometries.

Multiconductor transmission lines have been first analyzed in the orientation of power systems. Matrix methods for power systems trace back to the seminal works of R.H. Park [1, 2], and known as Park transformations. Methods similar to the above, known as DQO transformations and $\alpha\beta\gamma$ transformations have been developed to ease manipulations of 3 phase networks.

Traveling waves phenomena in polyphase systems have been analyzed by Wedepohl et al. [3, 4]. Those works generalized the telegraph equations for more than one dimension, and introduced the term of characteristic self impedance and characteristic mutual impedance between phases. Those methods have been used for fault location on transmission lines [5] and medium-frequency modeling of transmission systems [6]. The orientation of all those works was for polyphase power systems.

The term of characteristic impedance matrix has been used in the context of periodic array of wave launchers in [7, 8], for transmission line approximations, but they treated very specific geometries, and their matrices were always 2x2.

In 1988 Clayton R. Paul issued a book [9] on multiconductor transmission lines. This book treats from a very high theoretical level this subject, analyzing both homogeneous and non homogeneous media, the lossy and lossless case. Unfortunately, this subject did not get yet into the main stream of electromagnetic education, hence it deserves more attention and different approaches.

Most practical cases of multiconductor transmission line may be approximated as TEM in the homogeneous model, the inhomogeneity being expressed by an average equivalent dielectric constant. The waves propagate in quasi TEM, which may be well approximated by TEM [12]. Also losses, if they are small, may be introduced a posteriori.

It appears that the homogeneous lossless case can be very easily derived and formulated using only the scalar and vector potentials, and we present this formulation in the current work. Some preliminary work has been presented at [10].

In section 2 we define the general configuration which consists of any number of parallel

ideal conductors in a homogeneous lossless medium. In section 3 we discuss the basic formulation for guided TEM waves. In section 4 we obtain the propagation characteristic for multiconductor TEM and in section 5 we formulate the interface connections between source, termination and the multiconductor TEM transmission line, with some examples. In section 6 we formulate an alternative representation for the multiconductor guided TEM, with an example and in section 7 we perform a flat cable analysis for which we discuss the cross talk issue. In section 8 we generalize the results of sections 4 and 5 for the time harmonic case, discuss the VSWR issue, and present a short example. The work is ended with some concluding remarks.

II. CONFIGURATION AND FORMULATION

We consider an arbitrary number $N + 1$ of parallel perfect conductors in the z direction. The cross section of each conductor is fixed, hence z independent. The medium between the conductors is homogeneous having constant electric permittivity ϵ and magnetic permeability μ . The general configuration is shown in Figure (1). The conductors are numbered 1, 2, .. N , $N + 1$, where the “last” ($N + 1$) conductor is defined as *common*.

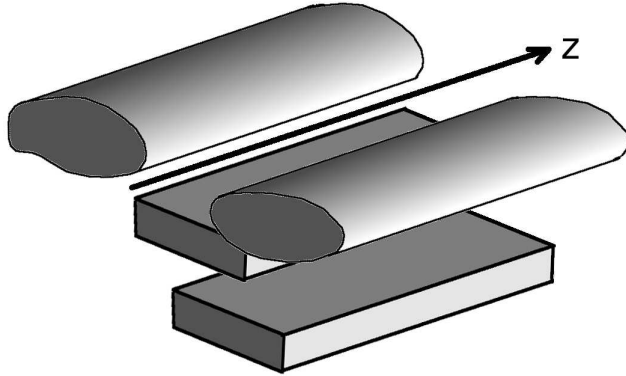


FIG. 1: General configuration: several parallel perfect conductors (here shown 4 conductors), having a fixed cross section in the $x - y$ plane in a homogeneous lossless medium.

III. BASICS OF GUIDED TEM

In a homogeneous medium the scalar potential V , each component of the vector potential \mathbf{A} and of the electric and magnetic fields, satisfy the homogeneous wave equation [11–13].

$$\left(\nabla^2 - \frac{1}{v^2}\partial_t^2\right)U = 0, \quad (1)$$

where U denotes any of the above entities, and $v \equiv \frac{1}{\sqrt{\epsilon\mu}}$ is the light velocity in the medium. The Lorentz gauge

$$\nabla \cdot \mathbf{A} + \frac{1}{v^2}\partial_t V = 0, \quad (2)$$

must also be satisfied. Now separating $\nabla^2 \equiv \nabla_{\text{tr}}^2 + \partial_z^2$ in eq. (1), where ∇_{tr}^2 is the transversal Laplacian operator, we obtain

$$\left(\nabla_{\text{tr}}^2 + \partial_z^2 - \frac{1}{v^2}\partial_t^2\right)U = 0, \quad (3)$$

By separating variables $U = U_{\text{tr}}(x, y)U_l(z, t)$ in eq. (3) one obtains

$$\frac{\nabla_{\text{tr}}^2 U_{\text{tr}}}{U_{\text{tr}}} + \frac{\partial_z^2 U_l - \frac{1}{v^2}\partial_t^2 U_l}{U_l} = 0, \quad (4)$$

and the TEM are *special* solutions for which each part of eq. (4) is separately 0, namely

$$\nabla_{\text{tr}}^2 U_{\text{tr}} = 0 \quad (5)$$

and

$$\partial_z^2 U_l - \frac{1}{v^2}\partial_t^2 U_l = 0. \quad (6)$$

Those special solutions exist only when the number of conductors is bigger than 1 (see Figure (1)), because for a single conductor the Laplace eq. (5) solved for the scalar potential V , yields a constant solution, hence 0 electric field.

For our general configuration in Figure (1), the surface currents cannot be circular, because this implies non zero \mathbf{B} field inside the conductors, which is impossible for perfect conductors. Hence the surface currents must be only in the \hat{z} direction, imply-

ing the vector potential to be $\mathbf{A} = A_z \hat{z}$. So setting $V(x, y, z, t) = V_{\text{tr}}(x, y)V_l(z, t)$ and $A_z(x, y, z, t) = A_{z\text{tr}}(x, y)A_{zl}(z, t)$ and solving the one dimensional wave equation eq. (6) for $V_l(z, t)$ and $A_{zl}(z, t)$ yields any functions of a single variable, say p which equals to $p = t \mp z/v$:

$$V_l(z, t) = f(p) = f(t \mp z/v) \quad (7)$$

and

$$A_{zl}(z, t) = g(p) = g(t \mp z/v) \quad (8)$$

where f and g are any functions of a single argument, the upper and lower signs describing forward and backward moving waves, respectively.

To simplify, we shall go on for now only with the forward moving wave, because the backward moving wave describes the same physics in the opposite direction and one easily derives the backward solution from the forward solution. So we drop for now the lower sign.

Requiring now the Lorentz condition in eq. (2), we obtain

$$\frac{vA_{z\text{tr}}}{V_{\text{tr}}} = \frac{f'(t - z/v)}{g'(t - z/v)} \equiv \kappa, \quad (9)$$

where f' and g' are the derivatives of the functions f and g with respect to their argument. Now because the left side is only a function of x, y and the right side is only a function of z, t , each must equal a constant which we name κ . So the right side yields $f'(q) = \kappa g'(q)$, where $q = t - z/v$ is the argument. We look for the dynamic solution for transients so by integrating from $q = -\infty$ to $q = p$, and assuming that $f(-\infty) = g(-\infty) = 0$, i.e. no constant values before the transient started, we may express the solution for transients as $f(p) = \kappa g(p)$, namely:

$$f(t - z/v) = \kappa g(t - z/v). \quad (10)$$

Now combining the left side of eq. (9) with eq. (10) we find the connection between the general solution of A_z and V

$$A_z = A_{z\text{tr}}g(t - z/v) = \frac{\kappa V_{\text{tr}}}{v} \frac{f(t - z/v)}{\kappa} = \frac{V}{v}, \quad (11)$$

because $V = V_{\text{tr}}f(t - z/v)$. So we see that κ cancels out and we obtain that at any coordinate x, y, z and at any time t the scalar potential V equals to vA_z . So without loss of generality we may omit κ by setting it to 1, and use

$$A_{z \text{ tr}} = \frac{V_{\text{tr}}}{v}. \quad (12)$$

IV. MULTICONDUCTOR TEM CHARACTERIZATION

To obtain the propagation characteristics, we need to solve the transversal Laplace equation (5) for $V_{\text{tr}}(x, y)$, which represents the transverse function of the forward moving wave voltage.

One may start by establishing N arbitrary potential differences between $N+1$ conductors. We choose conductor number $N + 1$ as the common, and we call the potential difference between conductor i and the common V_i . Such relative voltages only move charges from one conductor to another, so that the total charge on the $N + 1$ conductors is 0. Therefore the charge on conductor $N + 1$ is minus the sum of charges on all other conductors. We therefore deal with N voltages and N charges. After solving for $V_{\text{tr}}(x, y)$, one may calculate the charge surface density on each conductor using, e.g. on conductor i

$$\eta_i = -\epsilon \partial_n V_{\text{tr}}|_{\text{conductor } i} \quad (13)$$

where ∂_n is the derivative normal to the surface of conductor i . The charge per unit of length on conductor i is

$$\lambda_i = \oint \eta_i dc, \quad (14)$$

where dc is a length element along the circumference of the conductor i . The $N \times N$ elastance per unit of length matrix \mathcal{P} is defined by the connection

$$\mathbf{V} = \mathcal{P}\boldsymbol{\lambda}. \quad (15)$$

where $\boldsymbol{\lambda}$ and \mathbf{V} are column vectors of size N , their components being the charges per unit of length and the voltages V_{tr} on the conductors.

Now for the magnetic part, $A_{z \text{ tr}}$ satisfies the normal derivative boundary condition

$$K_i = -\frac{1}{\mu} \partial_n A_{z \text{ tr}} |_{\text{conductor } i}, \quad (16)$$

where K_i is the surface current density on the conductor i , and we omitted the vector notation, knowing that the current is only in the \hat{z} direction. Similarly with eq. (14), the current on conductor i is obtained via

$$I_i = \oint K_i dc. \quad (17)$$

Now combining eqs. (12),(13) and (16), one obtains

$$K_i = v\eta_i \quad (18)$$

and using eqs. (14) and (17) we get $I_i = v\lambda_i$. This connection being true for any i , can be put in vectorial form

$$\mathbf{I} = v\boldsymbol{\lambda}, \quad (19)$$

where \mathbf{I} is a column vector of size N , its components being the currents in the conductors. Now combining eqs. (15) and (19), we obtain

$$\mathbf{V} = \frac{1}{v} \mathcal{P} \mathbf{I} \equiv \mathcal{Z}_0 \mathbf{I}, \quad (20)$$

defining the characteristic impedance matrix

$$\mathcal{Z}_0 \equiv \mathcal{P}/v. \quad (21)$$

This is in analogy with the one dimensional case, i.e. $N + 1 = 2$, for which the characteristic impedance is $Z_0 = \frac{1}{vC'}$, where C' is the capacity per unit of length.

We may as well define the vector \mathbf{A}_z , its components being the magnetic potential vector $A_{z \text{ tr}}$ on the conductors, and according to eq. (12), we have

$$\mathbf{A}_z = \frac{\mathbf{V}}{v}. \quad (22)$$

We now define the inductance matrix per length unit \mathcal{L} by the connection

$$\mathbf{A}_z = \mathcal{L}\mathbf{I}, \quad (23)$$

and using eqs. (22), (19) and (15), we obtain the connection $\mathcal{L} = \mathcal{P}/v^2$ or by defining the capacitance per unit length matrix \mathcal{P} and inserting the unit matrix \mathcal{I} , we may express

$$\mathbf{C}\mathcal{L} = \mathcal{I}/v^2 = \mathcal{I}\mu\epsilon \quad (24)$$

which is the analogue of the formula $C'L' = \mu\epsilon$ for the one dimensional case. We may also express Z_0 from eq. (21) as

$$Z_0^2 = \mathcal{P}^2/v^2 = \mathcal{L}\mathcal{P} = \mathcal{L}\mathbf{C}^{-1}, \quad (25)$$

analogue to the formula $Z_0^2 = L'/C'$ for the one dimensional case.

A. The power carried by a forward moving wave

We shall calculate now the power carried by a forward moving wave, using Poynting theorem.

We first define U'_E as the electric energy per unit of length, which is calculated as half the sum on all conductors of the charge per length unit multiplied by the voltage

$$U'_E = \frac{1}{2} \sum_{j=1}^{N+1} \lambda_j V|_{\text{conductor } j} = \frac{1}{2} \left(\lambda_{N+1} V|_{\text{conductor } N+1} + \sum_{j=1}^N \lambda_j V|_{\text{conductor } j} \right). \quad (26)$$

The total charge being 0, $\lambda_{N+1} = -\sum_{j=1}^N \lambda_j$, so we obtain

$$U'_E = \frac{1}{2} \sum_{j=1}^N \lambda_j (V|_{\text{conductor } j} - V|_{\text{conductor } N+1}) = \frac{1}{2} \sum_{j=1}^N \lambda_j V_j = \frac{1}{2} \boldsymbol{\lambda}^T \mathbf{V}, \quad (27)$$

because we defined V_j as the potential difference between conductor j and the common conductor $N+1$. The last expression is in vectorial form, as multiplication between the row vector $\boldsymbol{\lambda}^T$ and the column vector \mathbf{V} , the superscript “T” meaning transposed, i.e. a row vector.

Now by inverting eq. (15), we may express the energy per length unit

$$U'_E = \frac{1}{2} \mathbf{V}^T \mathcal{C} \mathbf{V}, \quad (28)$$

Similarly, we define U'_H as the magnetic energy per unit of length. It may be expressed as half the sum on N conductors of the current multiplied by the magnetic flux per length unit enclosed between the conductor and the common. The magnetic flux per length unit enclosed between conductor j and the common is $A_z|_{\text{conductor } j} - A_z|_{\text{conductor } N+1}$, or simply A_{zj} so that

$$U'_H = \frac{1}{2} \sum_{j=1}^N I_j A_{zj} = \frac{1}{2} \mathbf{I}^T \mathbf{A}_z, \quad (29)$$

and by using eq. (23), we express it as

$$U'_H = \frac{1}{2} \mathbf{I}^T \mathcal{L} \mathbf{I}. \quad (30)$$

For a forward moving wave, eq. (20) is satisfied, so by using it and the eqs. (24) and (25), one easily shows that the electric and magnetic energies per length unit are equal, so that the total energy per length unit U' is given by

$$U' = U'_E + U'_H = 2U'_E = \mathbf{V}^T \mathcal{C} \mathbf{V} = \frac{1}{v} \mathbf{V}^T \mathcal{Z}_0^{-1} \mathbf{V}. \quad (31)$$

We now apply the Poynting theorem at time t , on a volume enclosed between the surfaces $z = z_1$ and $z = z_2$

$$P(t, z_1) - P(t, z_2) = \frac{\partial}{\partial t} U|_{\text{inside volume}} = \frac{\partial}{\partial t} \int_{z_1}^{z_2} U'(t, z) dz \quad (32)$$

where P is the forward power. We remember that any forward wave solution is not a function of the 2 separate variables t and z , but rather a function of one variable $p = t - z/v$ (see eqs. (7) and (8)), so that we may call

$$U'(t, z) \equiv h(p) = h(t - v/z), \quad (33)$$

h being the adequate function, according to the excitation of the system. So we obtain

$$P(t, z_1) - P(t, z_2) = \int_{z_1}^{z_2} \frac{\partial}{\partial t} h(t - z/v) dz = \int_{z_1}^{z_2} h'(t - z/v) dz, \quad (34)$$

h' being the derivative of h with respect to its argument p . We are left with a total derivative of a function having the argument linear in z , so integrating we obtain

$$P(t, z_1) - P(t, z_2) = \left. \frac{h(t - z/v)}{-1/v} \right|_{z_1}^{z_2} = v[h(t - z_1/v) - h(t - z_2/v)]. \quad (35)$$

Now we may take $z_2 \rightarrow \infty$, so that the power and the function h (which represents the energy per length unit) are 0 at $z = z_2$. So using eqs. (31) and (33), we rewrite eq. (35) for z_1 being any z , knowing that everything is a function of $t - z/v$:

$$P(t - z/v) = \mathbf{V}^T(t - z/v) \mathcal{Z}_0^{-1} \mathbf{V}(t - z/v), \quad (36)$$

which looks like a natural generalization of the forward power $P(t - z/v) = V^2(t - z/v)/Z_0$ for the one dimensional case.

So TEM waves guided by many conductors, may be specified in terms of voltages and currents, like in the two conductor case, but instead of the characteristic impedance we deal here with a characteristic impedance matrix, the voltages and currents being vectors.

V. TERMINATION AND SOURCE

In this section we deal with the interface of the multiconductor transmission line with the load and with the feeding source.

In principle, one may treat the multiconductor transmission line as a $2N$ port network, N ports at feed, and N ports at termination, see [9] Chapter 7.5, however this is usually an overcomplication.

The calculations are done for general excitation, and we consider for now only resistive loads and resistive source internal impedances.

A. The matching network

The matching network, i.e. the termination network of resistors that ensures zero reflected wave must satisfy the connection between voltages and currents dictated by the \mathcal{Z}_0 matrix.

In other words, the matching network must have an impedance matrix \mathcal{Z} that is identical to \mathcal{Z}_0 .

The most general resistors network consists of one resistor between each pair of conductors. So starting to connect the resistors between conductor 1 and the other N conductors, we have to connect N resistors. Now, between conductor 2 and the others we have to connect only $N - 1$ resistors, because between 1 and 2 we already connected, and so on, the total number of resistors is $N + (N - 1) + \dots + 1 = N(N + 1)/2$.

Let us call the resistor between conductor i and conductor $N + 1$ (which is the common), R_i , and let us call R_{ij} the resistor between conductor i and conductor j , where i and j have values between 1 and N . The resistors network has N ports, port i being defined between conductor i and the common. We need to define a generic connection between those resistors and the impedance matrix of the network \mathcal{Z} .

From the definition of the impedance matrix \mathcal{Z} , the ji component is

$$Z_{ji} = \left. \frac{V_j}{I_i} \right|_{\substack{I_k=0 \\ k \neq i}}. \quad (37)$$

The admittance matrix \mathcal{Y} is the inverse of the impedance matrix, hence

$$\mathcal{Y}\mathcal{Z} = \mathcal{I} \quad (38)$$

where \mathcal{I} is the unit matrix. Eq. (38) may be written in form of a sum, as follows:

$$\sum_{k=1}^N Y_{mk} Z_{ki} = \delta_{mi}, \quad (39)$$

where δ is the Kronecker delta.

Now let us feed the network from port i with a current I_i , leaving the other ports open (i.e. $I_k = 0$ for $k \neq i$). The voltages at the ports are called V_j , for j between 1 and N .

The KCL for port i yields:

$$I_i = \frac{V_i}{R_i} + \sum_{\substack{k=1 \\ k \neq i}}^N \frac{V_i - V_k}{R_{ik}}, \quad (40)$$

and the KCL for any other port m , where $m \neq i$, yields:

$$0 = \frac{V_m}{R_m} + \sum_{\substack{k=1 \\ k \neq m}}^N \frac{V_m - V_k}{R_{mk}}. \quad (41)$$

We may unify eqs. (40) and (41):

$$I_i \delta_{im} = \frac{V_m}{R_m} + \sum_{\substack{k=1 \\ k \neq m}}^N \frac{V_m - V_k}{R_{mk}} = V_m \left(\frac{1}{R_m} + \sum_{\substack{k=1 \\ k \neq m}}^N \frac{1}{R_{mk}} \right) - \sum_{\substack{k=1 \\ k \neq m}}^N \frac{V_k}{R_{mk}}. \quad (42)$$

so that m is any number between 1 and N . In the right side we rearranged the equation, so that the V_m terms are put together.

Now dividing by I_i and using eq. (37), we have

$$\delta_{im} = Z_{mi} \left(\frac{1}{R_m} + \sum_{\substack{k=1 \\ k \neq m}}^N \frac{1}{R_{mk}} \right) - \sum_{\substack{k=1 \\ k \neq m}}^N \frac{Z_{ki}}{R_{mk}}, \quad (43)$$

and we remark that the condition $I_k = 0$ for $k \neq i$ is satisfied here because we fed only port i . One observes that eqs. (39) and (43) are the same if we identify:

$$Y_{mk} = -\frac{1}{R_{mk}} \quad \text{for } (m \neq k) \quad (44)$$

and

$$Y_{mm} = \frac{1}{R_m} + \sum_{\substack{k=1 \\ k \neq m}}^N \frac{1}{R_{mk}} = \frac{1}{R_m} - \sum_{\substack{k=1 \\ k \neq m}}^N Y_{mk} \quad (45)$$

where the last equality used eq. (44). So the diagonal element of \mathcal{Y} at position m is the sum of all the conductances connected to port m , and the off diagonal element of \mathcal{Y} at position mk is minus the conductance between ports m and k .

Figure (2) shows the physical interpretation of eqs. (44) and (45).

It is worth to remark, that the characteristic admittance matrix \mathcal{Y}_0 is proportional to the capacitance per length unit matrix \mathcal{C} , the way \mathcal{Z}_0 is proportional to \mathcal{P} , see eq. (21). Therefore, the relations above between the admittance matrix and the conductances constituting the network, are the same as the relations between the capacitance matrix \mathcal{C} and the capacitances constituting a capacitance network - see [9], Chapter 3.1 . Also Figure (2) may

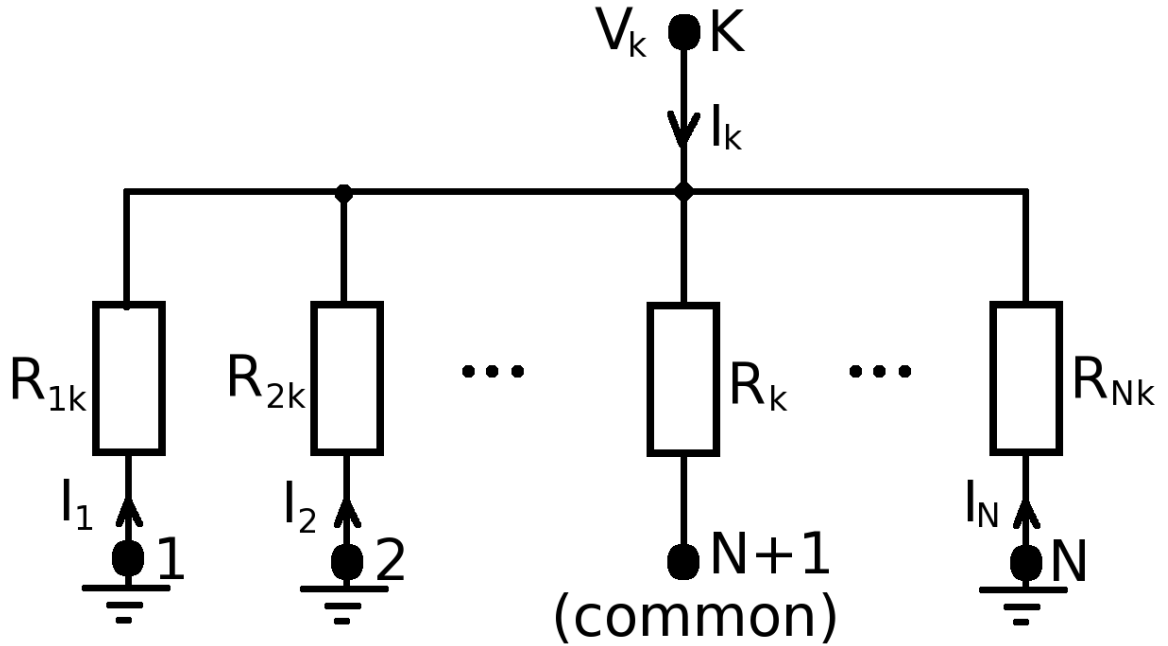


FIG. 2: Configuration for calculating Y_{mk} : network fed at conductor k by V_k , and all other conductors are grounded. The conductors are shown by big points, and the common is by definition at 0 potential. The value of Y_{mk} is given by I_m/V_k . All the resistors not having the index k are at 0 potential on both sides, so the only resistors entering the calculations are R_k and R_{jk} , for $j \neq k$, and they are all in parallel. The current I_m (for $m \neq k$) is the current entering from ground into resistor R_{mk} , hence equals $-V_k/R_{mk}$, and I_k is V_k divided by the resistors in parallel.

be modified to show the calculation of the capacitance matrix, by replacing the resistors by capacitors, and the currents by static charges.

To conclude, if the resistors of a network are known, one may calculate the elements of the \mathcal{Y} matrix using eqs. (44) and (45), and invert it to obtain the \mathcal{Z} matrix.

If one needs to implement a network to satisfy a given \mathcal{Z} matrix, say the needed \mathcal{Z}_0 , one inverts \mathcal{Z} to obtain \mathcal{Y} , and calculates the resistors between 2 ports (say m and k), using

$$R_{mk} = -\frac{1}{Y_{mk}} \quad (46)$$

and the resistor between port m and common may be extracted from the right side of eq. (45):

$$R_m = \frac{1}{\sum_{k=1}^N Y_{mk}} \quad (47)$$

Two examples of geometries have been calculated in [10] and we show the results of those examples in Figure (3).

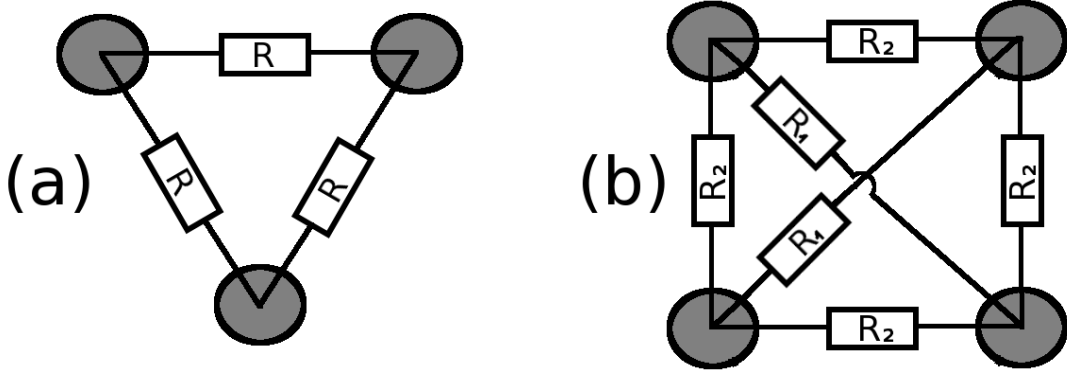


FIG. 3: Multiconductor transversal cross sections and their matching networks. Panel (a) shows a 3 phase geometry with wires of radii a , at the corners of an equilateral triangle of sides d , so that $a \ll d$. The matching network consists of resistors in triangle, where each resistor has the value $R = \frac{3}{2} \frac{\eta_0}{\pi} \ln \frac{d}{a}$. Panel (b) shows a 4 phase geometry with wires of radii a , at the corners of a square of sides d , so that $a \ll d$. The matching network consists of 6 resistors: 4 of value $R_2 = \frac{\eta_0}{\pi} \ln \frac{d^2}{2a^2}$ and 2 of value $R_1 = \frac{\eta_0}{\pi} \ln \frac{\sqrt{2}d}{a} \ln \frac{d^2}{2a^2} / \ln \frac{d}{\sqrt{8}a}$.

The characteristic impedance for the 3 phase geometry in panel (a) of Figure (3) is given by

$$\mathcal{Z}_0 = \begin{pmatrix} 2R/3 & R/3 \\ R/3 & R/3 \end{pmatrix}, \quad (48)$$

where $R = \frac{3}{2} \frac{\eta_0}{\pi} \ln \frac{d}{a}$, d being the side of the triangle and a the radius of the wire in the 3 phase geometry.

The characteristic impedance for the 4 phase geometry in panel (b) of Figure (3) is given

by

$$\mathcal{Z}_0 = \begin{pmatrix} \frac{R_2}{4} \frac{R_2+3R_1}{R_2+R_1} & \frac{1}{2} \frac{R_2 R_1}{R_2+R_1} & \frac{R_2}{4} \\ \frac{1}{2} \frac{R_2 R_1}{R_2+R_1} & \frac{R_2 R_1}{R_2+R_1} & \frac{1}{2} \frac{R_2 R_1}{R_2+R_1} \\ \frac{R_2}{4} & \frac{1}{2} \frac{R_2 R_1}{R_2+R_1} & \frac{R_2}{4} \frac{R_2+3R_1}{R_2+R_1} \end{pmatrix} \quad (49)$$

where $R_2 = \frac{\eta_0}{\pi} \ln \frac{d^2}{2a^2}$ and $R_1 = \frac{\eta_0}{\pi} \ln \frac{\sqrt{2}d}{a} \ln \frac{d^2}{2a^2} / \ln \frac{d}{\sqrt{8}a}$, d being the side of the rectangle and a the radius of the wire in the 4 phase geometry.

B. The reflection matrix

In case the line is terminated by a loading network having an impedance matrix $\mathcal{Z}_L \neq \mathcal{Z}_0$, the forward moving wave does not satisfy the termination condition, so there must be a backward wave. Dealing here with the 2 waves we shall denote the forward and backward waves by \pm superscripts, respectively. The most general solution for the voltages vector is a forward wave voltages vector plus a backward wave voltages vector:

$$\mathbf{V} = \mathbf{V}^+ + \mathbf{V}^- \quad (50)$$

and keeping the backward current agreed direction toward the positive z axis, same as the forward current has been defined, we have

$$\mathbf{I} = \mathbf{I}^+ + \mathbf{I}^-, \quad (51)$$

and at the load size we require the termination condition:

$$\mathbf{V} = \mathcal{Z}_L \mathbf{I}. \quad (52)$$

We showed that the connection between forward voltage and current is

$$\mathbf{V}^+ = \mathcal{Z}_0 \mathbf{I}^+, \quad (53)$$

(see eq. (20)), hence the connection for the backward wave is

$$\mathbf{V}^- = -\mathcal{Z}_0 \mathbf{I}^-, \quad (54)$$

because \mathbf{I}^- is defined the direction opposite to its propagation and this may be proved directly by continuing the formalism started in eq. (7) for the backward wave.

By combining eq. (51) with eqs. (53) and (54) we obtain

$$\mathcal{Z}_0 \mathbf{I} = \mathbf{V}^+ - \mathbf{V}^-, \quad (55)$$

and by adding and subtracting eqs. (50) and (55) we obtain:

$$2\mathbf{V}^+ = \mathbf{V} + \mathcal{Z}_0 \mathbf{I} \quad (56)$$

and

$$2\mathbf{V}^- = \mathbf{V} - \mathcal{Z}_0 \mathbf{I} . \quad (57)$$

We set now the termination condition in eq. (52) into eqs. (56) and (57), and by isolating \mathbf{I} from eq. (56) and setting it into eq. (57), we obtain the connection between \mathbf{V}^- and \mathbf{V}^+ :

$$\mathbf{V}^- = (\mathcal{Z}_L - \mathcal{Z}_0)(\mathcal{Z}_L + \mathcal{Z}_0)^{-1} \mathbf{V}^+, \quad (58)$$

which defines the reflection matrix Γ

$$\Gamma = (\mathcal{Z}_L - \mathcal{Z}_0)(\mathcal{Z}_L + \mathcal{Z}_0)^{-1}, \quad (59)$$

in an analogue way to the one dimensional reflection coefficient $\Gamma = (Z_L - Z_0)/(Z_L + Z_0)$, compare with [3, 9].

One remarks that the reflection matrix is a different concept from the scattering matrix used for a multiport network, although the formula is identical. When calculating the scattering matrix from a passive network, \mathcal{Z}_L still represents the network impedance matrix, but \mathcal{Z}_0 is a *diagonal* matrix representing the characteristic impedances of the ports.

Here we deal with a single port termination for a multiconductor TEM transmission line and \mathcal{Z}_0 must not be diagonal.

Because the load impedance matrix may not exist, it would be useful to derive an alter-

native expression for Γ based on the load admittance matrix, yielding

$$\Gamma = (\mathcal{Y}_0 + \mathcal{Y}_L)^{-1}(\mathcal{Y}_0 - \mathcal{Y}_L). \quad (60)$$

Unlike in the one dimensional case, Γ does not need to be the 0 matrix to satisfy $\Gamma \mathbf{V}^+ = 0$. From eq. (60) it is clear that in the case the determinant of $\mathcal{Y}_0 - \mathcal{Y}_L$ is 0, there exist incident voltage vectors yielding 0 reflection.

C. Interfacing to the source network

The most general source network has $N(N + 1)/2$ Thevenin branches of source voltage V_g is series with a source impedance R_g between each pair of conductors. We shall call the resistor and source between conductor i and $N + 1$ (the common) $R_{g,i}$ and $V_{g,i}$ and the resistor and source between conductor i and j , $R_{g,ij}$ and $V_{g,ij}$, where the + of the source is at the lower index. The naming of the resistors is like in the matching network section.

Calling the current exiting from conductor i of the source network I_i , and the voltage at conductor i of the source network V_i we write the KCL for the intersection i

$$\frac{V_{g,i} - V_i}{R_{g,i}} + \sum_{\substack{j=1 \\ j \neq i}}^N \frac{V_j + V_{g,ij} - V_i}{R_{g,ij}} = I_i. \quad (61)$$

where $V_{g,ij}$ is understood to be taken with positive sign if $i < j$ and vice versa if $i > j$. eq. (61) may be rearranged:

$$\frac{V_{g,i}}{R_{g,i}} + \sum_{\substack{j=1 \\ j \neq i}}^N \frac{V_{g,ij}}{R_{g,ij}} + \sum_{\substack{j=1 \\ j \neq i}}^N \frac{V_j}{R_{g,ij}} - V_i \left(\frac{1}{R_{g,i}} + \sum_{\substack{j=1 \\ j \neq i}}^N \frac{1}{R_{g,ij}} \right) = I_i. \quad (62)$$

The first 2 expressions represents the sum off all Norton currents connected to conductor i , and we shall call it $I_{g,i}$. The second 2 expressions may be written as $\left(- \sum_{j=1}^N Y_{g,ij} V_j \right)$, where $Y_{g,ij}$ are the elements of the source admittance matrix \mathcal{Y}_g - see eqs. (44) and (45) defining the admittance matrix elements of a passive network.

Hence we may rewrite eq. (62)

$$I_{gi} - \sum_{j=1}^N Y_{gij} V_j = I_i, \quad (63)$$

or in vectorial form

$$\mathbf{I}_g - \mathcal{Y}_g \mathbf{V} = \mathbf{I}. \quad (64)$$

The source network excites a forward wave in the transmission line for which we know the connection between voltage and current $\mathbf{V} = \mathcal{Z}_0 \mathbf{I}$. So we may isolate the voltage for the forward moving wave

$$\mathbf{V} = (\mathcal{Z}_0^{-1} + \mathcal{Y}_g)^{-1} \mathbf{I}_g = (\mathcal{Z}_0^{-1} + \mathcal{Z}_g^{-1})^{-1} \mathbf{I}_g, \quad (65)$$

which is a natural extension for the one dimensional case for which we have $I_g = V_g/Z_g$, hence eq. (65) becomes a voltage divider $V = (Z_0^{-1} + Z_g^{-1})^{-1} \frac{V_g}{Z_g} = V_g \frac{Z_0}{Z_0 + Z_g}$.

VI. THE DIFFERENTIAL REPRESENTATION

We used so far as dynamical variables the voltages between each conductor and an agreed common conductor, and the currents in each conductor (the common carrying minus the sum of the currents in all other conductors).

The convenience of this representation is the easy way of calculating the magnitudes described in the previous section, but of course this representation is not unique.

Given the voltages vector \mathbf{V} , it is sometimes convenient to define the differential voltages vector \mathbf{V}' , as $V'_1 = V_1 - V_2$, $V'_2 = V_2 - V_3$, ... $V'_N = V_N - 0$, which may be written in matrix form

$$\mathbf{V}' = \mathcal{T}_1 \mathbf{V} \quad (66)$$

where the matrix \mathcal{T}_1 has all components 0, except of the diagonal components which are 1 and the first super-diagonal components which are -1, and may be expressed as:

$$T_{1\ i,j} = \delta_{i,j} - \delta_{i,j-1}, \quad (67)$$

where δ is the Kronecker delta, and we assume in this notation that terms with indices smaller than 1 or larger than N are 0.

The differential currents \mathbf{I}' are loop currents so that we may think of the current I_j as the difference between the loop current I'_j and I'_{j-1} , so that $I_1 = I'_1 - 0$, $I_2 = I'_2 - I'_1$, ... $I_N = I'_N - I'_{N-1}$. This may be written in matrix form

$$\mathbf{I} = \mathcal{T}_2 \mathbf{I}' \quad (68)$$

where the matrix \mathcal{T}_2 has all components 0, except of the diagonal components which are 1 and the first sub-diagonal components which are -1, and may be expressed as:

$$T_{2\ i,j} = \delta_{i,j} - \delta_{i,j+1}. \quad (69)$$

Starting with the conductor to ground representation for which the relation between the forward moving voltage and current vectors is $\mathbf{V} = \mathcal{Z}_0 \mathbf{I}$, and using eqs. (66) and (68), we obtain the differential representation

$$\mathbf{V}' = \mathcal{Z}'_0 \mathbf{I}' \quad (70)$$

where

$$\mathcal{Z}'_0 = \mathcal{T}_1 \mathcal{Z}_0 \mathcal{T}_2, \quad (71)$$

and the components of \mathcal{Z}'_0 may be written explicitly in terms of the components of \mathcal{Z}_0

$$Z'_{0\ i,j} = Z_{0\ i,j} + Z_{0\ i+1,j+1} - Z_{0\ i+1,j} - Z_{0\ i,j+1}. \quad (72)$$

again, considering terms with outside range indices as 0. The usefulness of this transformation is show in the following example.

A. Example: multiple parallel plates

We will calculate the characteristic impedance matrix for $N+1$ parallel plates at distance d one from the other all having the width w , so that $w \gg d$, see Figure (4).

To solve Laplace equation (5) for the transverse potential V_{tr} , we consider plate j to

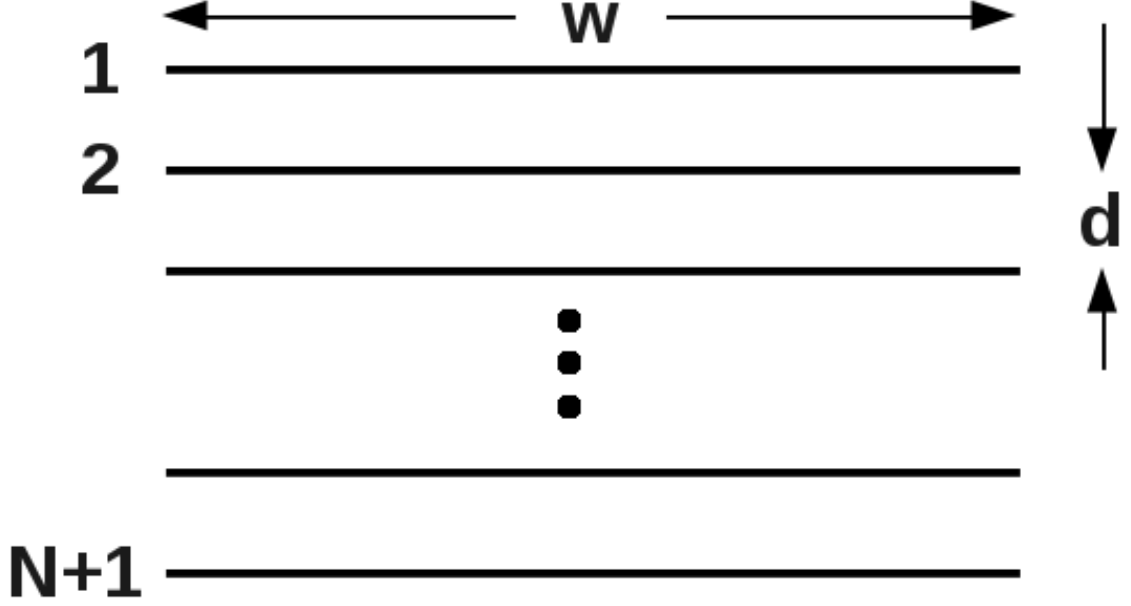


FIG. 4: Multiconductor waveguide consisting of parallel plates of width w , at distance d between them. We assume large plates, i.e. $w \gg d$. The z axis is perpendicular to the paper.

have a surface charge η_j , for $j \neq N + 1$, and the charge surface on conductor $N + 1$ is $\eta_{N+1} = -\sum_{i=1}^N \eta_i$. We shall use the expression for the potential due to an infinite plate $\frac{-\eta}{2\epsilon}|x|$, where η is the charge surface and $|x|$ is the distance from the plate. Also we may express the charge per unit length in the z direction as $\lambda = w\eta$. So we may write the potential on conductor j (for $j \neq N + 1$)

$$V_{\text{tr}}|_{\text{cond}j} = \frac{\eta_j d}{2w\epsilon}(N + 1 - j) + \sum_{i=1}^{j-1} \frac{\eta_i d}{2w\epsilon}(N + 1 + i - 2j) + \sum_{i=j+1}^N \frac{\eta_i d}{2w\epsilon}(N + 1 - i) \quad (73)$$

and the potential on conductor $N + 1$

$$V_{\text{tr}}|_{\text{cond}N+1} = \sum_{i=1}^N \frac{-\eta_i d}{2w\epsilon}(N + 1 - i) \quad (74)$$

and express $V_j = V_{\text{tr}}|_{\text{cond}j} - V_{\text{tr}}|_{\text{cond}N+1}$ obtaining

$$V_j = \sum_{i=1}^{j-1} \frac{\eta_i d}{w\epsilon}(N + 1 - j) + \sum_{i=j}^N \frac{\eta_i d}{w\epsilon}(N + 1 - i). \quad (75)$$

The coefficients are identified as the elastance matrix elements

$$P_{ij} = \begin{cases} \frac{d}{w\epsilon}(N+1-j) & i < j \\ \frac{d}{w\epsilon}(N+1-i) & i \geq j \end{cases}, \quad (76)$$

and the characteristic impedance matrix elements are obtained from eq. (21)

$$Z_{0\ ij} = \begin{cases} \frac{\eta d}{w}(N+1-j) & i < j \\ \frac{\eta d}{w}(N+1-i) & i \geq j \end{cases}. \quad (77)$$

which may also be written as $Z_{0\ ij} = u_{i-j}(j-i) + N+1-j$, where u is the discrete step function, i.e. equals 1 for non negative index and zero otherwise.

This form does not emphasize the separability of this configuration, so we would like to transform to the differential representation with eq. (72). After some algebra, noting that $u_{i-j} - u_{i-j-1} = \delta_{i,j}$, one obtains

$$Z'_{0\ ij} = \delta_{i,j} \frac{\eta d}{w} \quad (78)$$

or in matrix form $Z'_0 = \mathcal{I} \frac{\eta d}{w}$, \mathcal{I} being the unit matrix. So the differential representation results in N separate TEM waveguides, each having the characteristic impedance $\frac{\eta d}{w}$.

This was a special example of separable configuration, but the differential representation may be useful also for non separable configurations, because it emphasizes better the “local impedance”, i.e. the connection between the voltage difference between 2 adjacent conductors, and the loop current between them, as we shall see in the next section.

VII. FLAT CABLE ANALYSIS

The flat cable is the most common multiconductor transmission line, hence we dedicate this section to flat cables and we shall calculate here the characteristic impedance matrix for a flat cable.

The distance between the wires (called pitch) is d and the conductor radius is a , and we consider the common case of $a \ll d$ - see Figure (5).

The wires are numbered 1,2, .. N , $N+1$. We assign the charges per length unit $\lambda_1, \lambda_2, .. \lambda_N$, and the $N+1$ wire (considered the common) has the charges per length unit

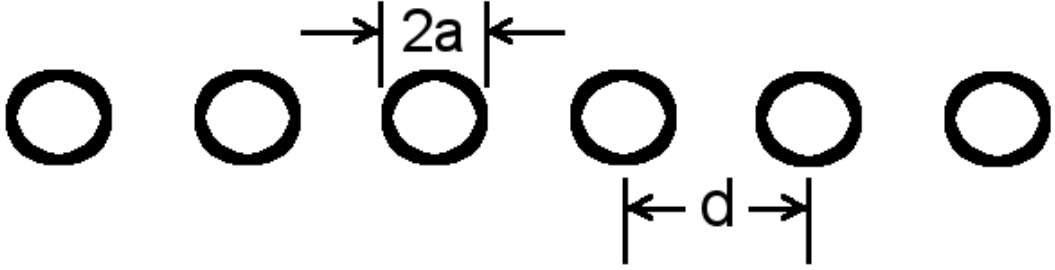


FIG. 5: The geometry of a flat cable: equidistant conductors of radii a . The distance between the conductors d is called *pitch* and is typically much bigger than the conductors radius. We consider the surrounding media to be homogeneous.

$$\lambda_{N+1} = - \sum_{i=1}^N \lambda_i. \quad (79)$$

The solution of the Laplace equation, i.e. the potential at any location may be expressed using the thin wire approximation

$$V_{\text{tr}} = - \sum_{i=1}^{N+1} \frac{\lambda_i}{2\pi\epsilon} \ln r_i, \quad (80)$$

where ϵ is some equivalent dielectric constant, i.e. $\epsilon = \epsilon_0\epsilon_r$, ϵ_r is usually between 1.5 and 3, and r_j is the distance from conductor j .

By putting eq. (79) into eq. (80), we get

$$V_{\text{tr}} = \sum_{i=1}^N \frac{\lambda_i}{2\pi\epsilon} \ln \frac{r_{N+1}}{r_i}, \quad (81)$$

and to express the potential on the conductor j (for $j \neq N+1$) we set $r_{N+1} = d(N+1-j)$. Also, we set $r_i = d|j-i|$ if $i \neq j$ and $r_i = a$ if $i = j$, according to the thin wire approximation, obtaining

$$V_{\text{tr}}|_{\text{conductor } j} = \frac{\lambda_j}{2\pi\epsilon} \ln \frac{d(N+1-j)}{a} + \sum_{\substack{i=1 \\ i \neq j}}^N \frac{\lambda_i}{2\pi\epsilon} \ln \frac{N+1-j}{|j-i|}, \quad (82)$$

and on conductor $N+1$, we set $r_{N+1} = a$ and $r_i = d(N+1-i)$

$$V_{\text{tr}}|_{\text{conductor } N+1} = \sum_{i=1}^N \frac{\lambda_i}{2\pi\epsilon} \ln \frac{a}{d(N+1-i)}. \quad (83)$$

The potential difference V_j is given by $V_{\text{tr}}|_{\text{conductor } j} - V_{\text{tr}}|_{\text{conductor } N+1}$ and comes out:

$$V_j = \frac{\lambda_j}{\pi\epsilon} \ln \frac{d(N+1-j)}{a} + \sum_{\substack{i=1 \\ i \neq j}}^N \frac{\lambda_i}{2\pi\epsilon} \ln \frac{d(N+1-j)(N+1-i)}{a|j-i|}, \quad (84)$$

and this defines the elements of the elastance matrix

$$P_{ij} = \begin{cases} \frac{1}{\pi\epsilon} \ln \frac{d(N+1-j)}{a} & i = j \\ \frac{1}{2\pi\epsilon} \ln \frac{d(N+1-j)(N+1-i)}{a|j-i|} & i \neq j \end{cases}, \quad (85)$$

and the characteristic impedance matrix elements are obtained from eq. (21)

$$Z_{0\ ij} = \begin{cases} \frac{\eta}{\pi} \ln \frac{d(N+1-j)}{a} & i = j \\ \frac{\eta}{2\pi} \ln \frac{d(N+1-j)(N+1-i)}{a|j-i|} & i \neq j \end{cases}, \quad (86)$$

where $\eta = \sqrt{\epsilon/\mu_0}$.

It will be convenient to see also the differential representation of the characteristic impedance matrix. Using eq. (72) we obtain:

$$Z'_{0\ ij} = \begin{cases} \frac{\eta}{\pi} \ln \frac{d}{a} & i = j \\ \frac{-\eta}{2\pi} \ln \frac{d}{2a} & |i-j| = 1 \\ \frac{\eta}{2\pi} \ln \left(1 - \frac{1}{|j-i|^2}\right) & |i-j| > 1 \end{cases}, \quad (87)$$

which is much simpler than regular representation.

We will calculate the balanced crosstalk on a 9L280XX Belden flat cable. The datasheet of the cable can be found at [14]. The cables have a pitch of $d = 0.05'' = 1.27$ mm and wires of type 28 AWG, having a radius of $a = 0.1605$ mm. The measurement configuration is shown in Figure (6).

We shall first suppose the far end is matched and than show how to match it. So given the far end is matched, we have one single forward voltages vector wave \mathbf{V} which satisfies the equation $\mathbf{V} = \mathbf{Z}_0 \mathbf{I}$, \mathbf{I} being the forward currents vector. But all the components of the currents vector are 0 except of the k and $k+1$ components. Also we know that $I_{k+1} = -I_k$, so we may write the n component of the forward voltage vector:

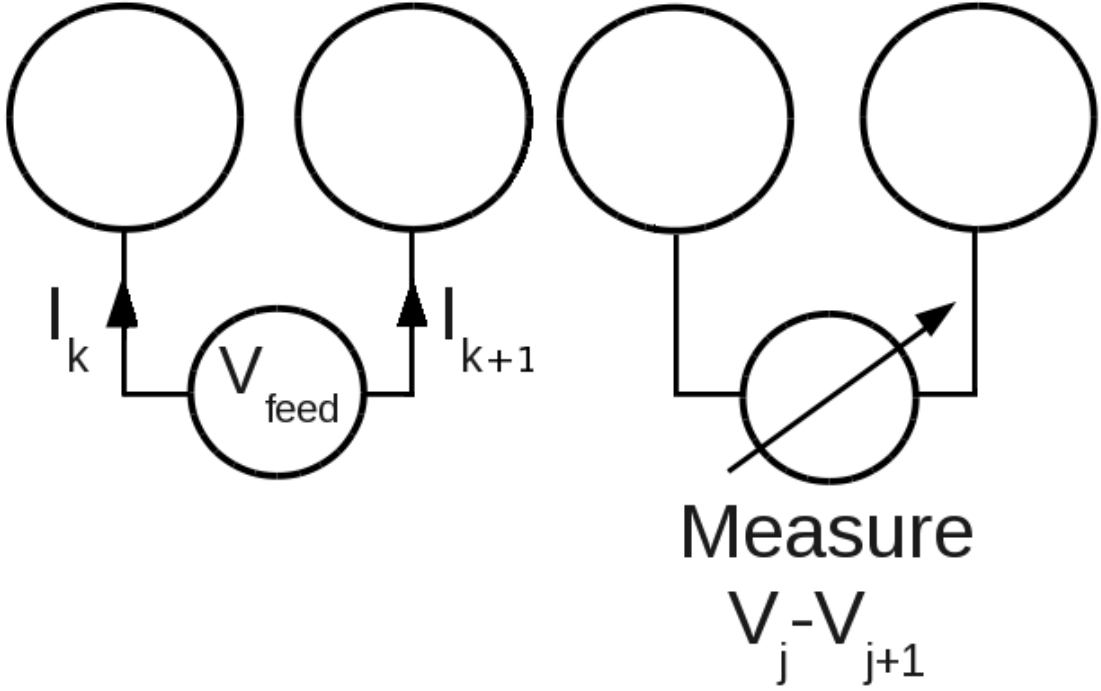


FIG. 6: A balanced cross talk measurement on a flat cable. The conductors k and $k + 1$ are differentially fed, and are called the *drive pair*, and one measures the voltage between two other conductors j and $j + 1$, called the *sample pair*. The biggest crosstalk effect is on neighboring conductors, so we take $j = k + 2$. The far end is matched.

$$V_n = (Z_{0n,k} - Z_{0n,k+1})I_k \quad (88)$$

It looks quite natural that having a non zero current only on conductors k and $k + 1$, one would need at the far end to connect a resistance only between those conductors, so let us call this resistance R_0 . According to eqs. (44) and (45), connecting only this resistor defines the components of the load admittance matrix

$$Y_{Lm,n} = \frac{1}{R_0}(\delta_{m,k}\delta_{n,k} + \delta_{m,k+1}\delta_{n,k+1} - \delta_{m,k}\delta_{n,k+1} - \delta_{m,k+1}\delta_{n,k}), \quad (89)$$

so \mathcal{Y}_L has only 4 non zero components, 2 diagonal components of value $1/R_0$ and 2 off diagonal components of value $-1/R_0$.

For having a 0 reflected voltage one needs $(\mathcal{Y}_0 - \mathcal{Y}_L)\mathbf{V} = 0$ (see eq. (60) and comments after it). Hence we calculate first the m component of $\mathcal{Y}_0\mathbf{V}$, so using V_n from eq. (88) we obtain

$$[\mathcal{Y}_0 \mathbf{V}]_m = \sum_n Y_{0m,n} V_n = I_k (\delta_{m,k} - \delta_{m,k+1}), \quad (90)$$

because \mathcal{Y}_0 is the inverse matrix of \mathcal{Z}_0 . Now the m component of $\mathcal{Y}_L \mathbf{V}$ yields

$$[\mathcal{Y}_L \mathbf{V}]_m = \sum_n Y_{Lm,n} V_n = \frac{I_k}{R_0} (\delta_{m,k} - \delta_{m,k+1}) (Z_{0k,k} - 2Z_{0k+1,k} + Z_{0k+1,k+1}), \quad (91)$$

and we see that the value of R_0 needed to make the results of eqs. (90) and (91) identical is

$$R_0 = Z_{0k,k} - 2Z_{0k+1,k} + Z_{0k+1,k+1} = Z'_{0k,k} = \frac{\eta}{\pi} \ln(d/a), \quad (92)$$

where for the last expression we used the relation (72) and eq. (87), obtaining the diagonal element of the characteristic impedance matrix in the differential representation.

Also, one remarks that the value of R_0 should be the equivalent of what Belden [14] call in their datasheet the “impedance”.

The value they give is 105Ω and for comparing we need to know the value of $\eta = 377\Omega/\sqrt{\epsilon_r}$, where ϵ_r is some equivalent relative dielectric coefficient which is influenced by the isolation material and the surrounding air.

The value of ϵ_r may be calculated using the propagation delay from the datasheet, given as 4.6 nsec/m, so that $\sqrt{\epsilon_r}$ is the light velocity in vacuum, multiplied by the propagation delay, resulting in 1.38. Using the above, R_0 comes out 180Ω , which is about 1.7 times higher than the 105Ω in the datasheet. I suppose the reason for this discrepancy are very big losses given in the datasheet, which imply dispersion and do not allow a simple time domain analysis like this one.

In spite of the discrepancy in the characteristic impedance value, the calculated cross talk compares well with the datasheet, because this value depends on a relation between the characteristic impedance matrix elements, as we shall see below.

So the feeding voltage is expressed as $V_{\text{feed}} = V_k - V_{k+1}$ and using eq. (88) we obtain

$$V_{\text{feed}} = (Z_{0k,k} - 2Z_{0k+1,k} + Z_{0k+1,k+1}) I_k = I_k R_0 \quad (93)$$

Similarly, the sample voltage is $V_{\text{sample}} = V_{k+2} - V_{k+3}$ and using eq. (88) we obtain $V_{\text{sample}} = (Z_{0k+2,k} - Z_{0k+2,k+1} + Z_{0k+3,k+1} - Z_{0k+3,k}) I_k$. By comparing this with eq. (72), we

see that $V_{\text{sample}} = Z'_{0k+2,k} I_k$ and from eq. (87) we obtain

$$V_{\text{sample}} = I_k \frac{\eta}{2\pi} \ln(3/4), \quad (94)$$

The crosstalk is defined as the absolute value of the relation between V_{sample} and V_{feed} :

$$\text{Crosstalk} = \left| \frac{V_{\text{sample}}}{V_{\text{feed}}} \right| = \frac{\ln(4/3)}{2 \ln(d/a)} = 0.06954 = -23.1 \text{ dB} \quad (95)$$

This value is also called crosstalk isolation and is given in the Belden datasheet [14] as -20 dB, showing that the above calculation fits well the measurement.

VIII. MULTICONDUCTOR TEM IN STEADY STATE HARMONIC EXCITATION

In this section we generalize the multiconductor TEM for the case of steady state harmonic excitation. One may rewrite the one dimensional wave equation (6) by replacing ∂_t by $j\omega$, or alternatively replace the solution function (say in eq. (7)) $f(p) = \exp(j\omega p)$, to obtain the phasor solutions of the form $\exp(\mp j\beta z)$ for the forward and backward moving waves, respectively, where

$$\beta \equiv \omega/v \quad (96)$$

is the wave number. For harmonic steady state we need to develop formulas to move along transmission line and express quantities at some location z , given that they are known at other location say z_1 .

The basic solutions for the voltage, i.e. the forward an backward moving voltages behave according to

$$\mathbf{V}^\pm(z) = \mathbf{V}^\pm(z_1) e^{\mp j\beta(z-z_1)}, \quad (97)$$

and the forward an backward moving currents behave the same

$$\mathbf{I}^\pm(z) = \mathbf{I}^\pm(z_1) e^{\mp j\beta(z-z_1)}, \quad (98)$$

and the connection between forward/backward voltages and currents is the same like for

any excitation

$$\mathbf{V}^\pm(z) = \pm \mathcal{Z}_0 \mathbf{I}^\pm(z). \quad (99)$$

we define the reflection matrix at any location z by the connection between the backward and forward voltages

$$\mathbf{V}^-(z) = \Gamma(z) \mathbf{V}^+(z). \quad (100)$$

where Γ is now a complex phasor matrix. By setting eq. (97) into eq. (100) and by replacing $\mathbf{V}^-(z_1) = \Gamma(z_1) \mathbf{V}^+(z_1)$ we obtain:

$$\Gamma(z) \mathbf{V}^+(z_1) = e^{2j\beta(z-z_1)} \Gamma(z_1) \mathbf{V}^+(z_1), \quad (101)$$

which must hold for any set of voltages $\mathbf{V}^+(z_1)$, hence we are left with

$$\Gamma(z) = e^{2j\beta(z-z_1)} \Gamma(z_1), \quad (102)$$

which is the generalization of the one dimensional case $\Gamma(z) = e^{2j\beta(z-z_1)} \Gamma(z_1)$.

The eqs. (50) and (55) hold for harmonic steady state at any z , so we write them at location z and use eq. (97):

$$\mathbf{V}(z) = \mathbf{V}^+(z) + \mathbf{V}^-(z) = \mathbf{V}^+(z_1) e^{-j\beta(z-z_1)} + \mathbf{V}^-(z_1) e^{j\beta(z-z_1)} \quad (103)$$

$$\mathcal{Z}_0 \mathbf{I}(z) = \mathbf{V}^+(z) - \mathbf{V}^-(z) = \mathbf{V}^+(z_1) e^{-j\beta(z-z_1)} - \mathbf{V}^-(z_1) e^{j\beta(z-z_1)}, \quad (104)$$

Now we use eqs. (56) and (57) at location z_1 to extract $\mathbf{V}^+(z_1)$ and $\mathbf{V}^-(z_1)$ and set into eqs. (103) and (104):

$$\mathbf{V}(z) = \frac{1}{2} [\mathbf{V}(z_1) + \mathcal{Z}_0 \mathbf{I}(z_1)] e^{-j\beta(z-z_1)} + \frac{1}{2} [\mathbf{V}(z_1) - \mathcal{Z}_0 \mathbf{I}(z_1)] e^{j\beta(z-z_1)} \quad (105)$$

and after rearranging

$$\mathbf{V}(z) = \mathbf{V}(z_1) \cos \beta(z - z_1) - j \mathcal{Z}_0 \mathbf{I}(z_1) \sin \beta(z - z_1) \quad (106)$$

and similarly for the current

$$\mathbf{I}(z) = \mathbf{I}(z_1) \cos \beta(z - z_1) - j\mathcal{Y}_0 \mathbf{V}(z_1) \sin \beta(z - z_1). \quad (107)$$

We define here the local impedance matrix as:

$$\mathbf{V}(z) = \mathcal{Z}(z)\mathbf{I}(z), \quad (108)$$

so by replacing $\mathbf{V}(z_1) = \mathcal{Z}(z_1)\mathbf{I}(z_1)$ in eqs. (106) and (107), one obtains

$$\mathbf{V}(z) = [\mathcal{Z}(z_1) \cos \beta(z - z_1) - j\mathcal{Z}_0 \sin \beta(z - z_1)]\mathbf{I}(z_1) \quad (109)$$

and

$$\mathbf{I}(z) = [\mathcal{I} \cos \beta(z - z_1) - j\mathcal{Y}_0 \mathcal{Z}(z_1) \sin \beta(z - z_1)]\mathbf{I}(z_1), \quad (110)$$

where \mathcal{I} is the unit matrix. Now isolating $\mathbf{I}(z_1)$ from eq. (110), setting it in eq. (109) and taking $\cos \beta(z - z_1)$ outside parenthesis yields

$$\mathbf{V}(z) = [\mathcal{Z}(z_1) - \mathcal{Z}_0 \tan \beta(z - z_1)][\mathcal{I} - j\mathcal{Y}_0 \mathcal{Z}(z_1) \tan \beta(z - z_1)]^{-1}\mathbf{I}(z), \quad (111)$$

from which we get

$$\mathcal{Z}(z) = [\mathcal{Z}(z_1) - j\mathcal{Z}_0 \tan \beta(z - z_1)][\mathcal{I} - j\mathcal{Y}_0 \mathcal{Z}(z_1) \tan \beta(z - z_1)]^{-1}, \quad (112)$$

which may be rearranged to

$$\mathcal{Z}(z) = [\mathcal{Z}(z_1) - j\mathcal{Z}_0 \tan \beta(z - z_1)][\mathcal{Z}_0 - j\mathcal{Z}(z_1) \tan \beta(z - z_1)]^{-1}\mathcal{Z}_0, \quad (113)$$

which is the analogue of the one dimensional formula $Z(z) = Z_0 \frac{Z(z_1) - jZ_0 \tan \beta(z - z_1)}{Z_0 - jZ(z_1) \tan \beta(z - z_1)}$

For the case the matrix $\mathcal{Z}(z_1)$ does not exist it is useful to express the above connection via admittances. Some matrix algebra yields

$$\mathcal{Y}(z) = [\mathcal{Y}(z_1) - j\mathcal{Y}_0 \tan \beta(z - z_1)][\mathcal{Y}_0 - j\mathcal{Y}(z_1) \tan \beta(z - z_1)]^{-1}\mathcal{Y}_0, \quad (114)$$

and the connection between $\Gamma(z)$, $\mathcal{Z}(z)$ and $\mathcal{Y}(z)$ is given by

$$\Gamma(z) = (\mathcal{Z}(z) - \mathcal{Z}_0)(\mathcal{Z}(z) + \mathcal{Z}_0)^{-1} = (\mathcal{Y}_0 + \mathcal{Y}(z))^{-1}(\mathcal{Y}_0 - \mathcal{Y}(z)) \quad (115)$$

The solution for an harmonic steady state multiconductor transmission line of length l , given the sources and the load impedance matrix is similar to the one dimensional case. First we set

$$\mathcal{Z}(l) = \mathcal{Z}_L \quad (116)$$

where \mathcal{Z}_L is the load impedance matrix. Then we use eq. (113) to calculate the impedance matrix at the source location ($z = 0$ and $z_1 = l$)

$$\mathcal{Z}_{\text{in}} = \mathcal{Z}(0) = [\mathcal{Z}(l) + j\mathcal{Z}_0 \tan \beta l][\mathcal{Z}_0 + j\mathcal{Z}(l) \tan \beta l]^{-1} \mathcal{Z}_0, \quad (117)$$

and this is the input impedance matrix of the multiconductor transmission line. Next we use the interface to source formula eq. (65), developed for transients, only \mathcal{Z}_0 has to be replaced by \mathcal{Z}_{in} , to calculate the voltage near the source

$$\mathbf{V}(0) = (\mathcal{Z}_{\text{in}}^{-1} + \mathcal{Z}_g^{-1})^{-1} \mathbf{I}_g, \quad (118)$$

and the current near the source is

$$\mathbf{I}(0) = \mathcal{Z}_{\text{in}}^{-1} \mathbf{V}(0) = (\mathcal{I} + \mathcal{Z}_g^{-1} \mathcal{Z}_{\text{in}})^{-1} \mathbf{I}_g. \quad (119)$$

Knowing $\mathbf{V}(0)$ and $\mathbf{I}(0)$, one may calculate $\mathbf{V}(z)$ and $\mathbf{I}(z)$ for any location z using eqs. (106) and (107) (by setting $z_1 = 0$).

The power of a forward moving wave (see eq. (36)) is also easily generalized for the time harmonic case

$$P^+ = \mathbf{V}^{+T} \mathcal{Z}_0^{-1} \mathbf{V}^{+*}, \quad (120)$$

where the $*$ denotes the complex conjugate, and according to eq. (97), the result is z independent and real. Also, defining the magnitudes of the phasors we use as *RMS values*, we do not need a $1/2$ factor in eq. (120).

It would be interesting to check what is the multidimensional analog to the standing wave

ratio (SWR). As explained in Section 5.B, the reflection at the termination may depend on the incident voltages vector itself, therefore it is impossible in the general case to generalize the SWR (in [9] the SWR is considered only for the one dimensional case). Another way of understanding this is to look at a separable configuration - see Figure (4). For this case one finds that \mathcal{Z}_0 is diagonal in the differential representation (see eq. (78)), and we have N separate waveguides, each one of them may have its own SWR.

But there is a special case of interest: if the load impedance matrix \mathcal{Z}_L , the characteristic impedance matrix \mathcal{Z}_0 and the source impedance matrix \mathcal{Z}_g are all scalar multiples of the same matrix \mathcal{Q} , one may generalize the SWR and work with scalar waves.

In this case we have $\mathcal{Z}_L = \mathcal{Q}Z_L$, $\mathcal{Z}_0 = \mathcal{Q}Z_0$ and $\mathcal{Z}_g = \mathcal{Q}Z_g$ where Z_L , Z_0 and Z_g are impedances. For this case eq. (113) may be written as

$$\mathcal{Z}(z) = \mathcal{Q}Z_0 \frac{Z(z_1) - jZ_0 \tan \beta(z - z_1)}{Z_0 - jZ(z_1) \tan \beta(z - z_1)} \equiv \mathcal{Q}Z(z) \quad (121)$$

and eq. (115) as

$$\Gamma(z) = \mathcal{I} \frac{Z(z) - Z_0}{Z(z) + Z_0} \quad (122)$$

also the input impedance matrix entering eq. (118) may be written as $\mathcal{Z}_{\text{in}} = \mathcal{Q}Z_{\text{in}}$, so that eq. (118) becomes

$$\mathbf{V}(0) = \frac{Z_{\text{in}}Z_g}{Z_{\text{in}} + Z_g} \mathcal{Q}\mathbf{I}_g, \quad (123)$$

and the power of a forward moving wave becomes

$$P^+ = \frac{1}{Z_0} \mathbf{V}^{+T} \mathcal{Q}^{-1} \mathbf{V}^{+*}, \quad (124)$$

A. Example: three phase network

We shall use here the cross section geometry of 3 thin wires of radii a on the edges of an equilateral triangle of side d , so that $d \gg a$, see Figure (3), panel (a).

The characteristic impedance matrix for this geometry is given in eq. (48), and may be rewritten as

$$Z_0 = Z_0 \mathcal{Q} \quad (125)$$

where \mathcal{Q} is the following matrix

$$\mathcal{Q} = \begin{pmatrix} 2/3 & 1/3 \\ 1/3 & 2/3 \end{pmatrix}, \quad (126)$$

and

$$Z_0 = \frac{3\eta_0}{2\pi} \ln(d/a) \quad (127)$$

has the value of the matching resistors in Figure (3) panel (a).

The network is fed by a 3 phase generator, each phase having the generator impedance Z_g , see Figure (7).

The purpose of this example is to show the power transfer, so to simplify it, we shall consider the 3 phase transmission line matched, hence $Z_{in} = Z_0$. We first obtain the Norton currents vector \mathbf{I}_g (see eq. (62))

$$\mathbf{I}_g = \frac{V_0}{Z_g} \begin{pmatrix} \exp(j4\pi/3) - 1 \\ 1 - \exp(j2\pi/3) \end{pmatrix} = \frac{\sqrt{3}V_0}{Z_g} \begin{pmatrix} \exp(j5\pi/6) \\ \exp(j\pi/6) \end{pmatrix}, \quad (128)$$

and using eq. (123) we obtain the voltage vector at the beginning of the line

$$\mathbf{V}(0) = \frac{\sqrt{3}V_0 Z_0}{Z_0 + Z_g} \mathcal{Q} \begin{pmatrix} \exp(j5\pi/6) \\ \exp(j\pi/6) \end{pmatrix}, \quad (129)$$

Being matched, this voltage vector is the forward moving voltage vector which only changes its phase in propagation. Using eq. (124), we obtain the power

$$P = \frac{3}{Z_0} \left| \frac{V_0 Z_0}{Z_0 + Z_g} \right|^2 (\exp(j5\pi/6) \exp(j\pi/6)) \mathcal{Q} \begin{pmatrix} \exp(j5\pi/6) \\ \exp(j\pi/6) \end{pmatrix}^*, \quad (130)$$

The last matrices multiplication results in 1, and we identify $V_0 Z_0 / (Z_0 + Z_g)$ as the voltage on each phase V_{ph} of the matched load $Z_{ph} = Z_0$, resulting in the usual 3 phase power $3|V_{ph}|^2 / Z_{ph}$.

Of course, this result is valid for the same load we considered above, on *any geometry* of

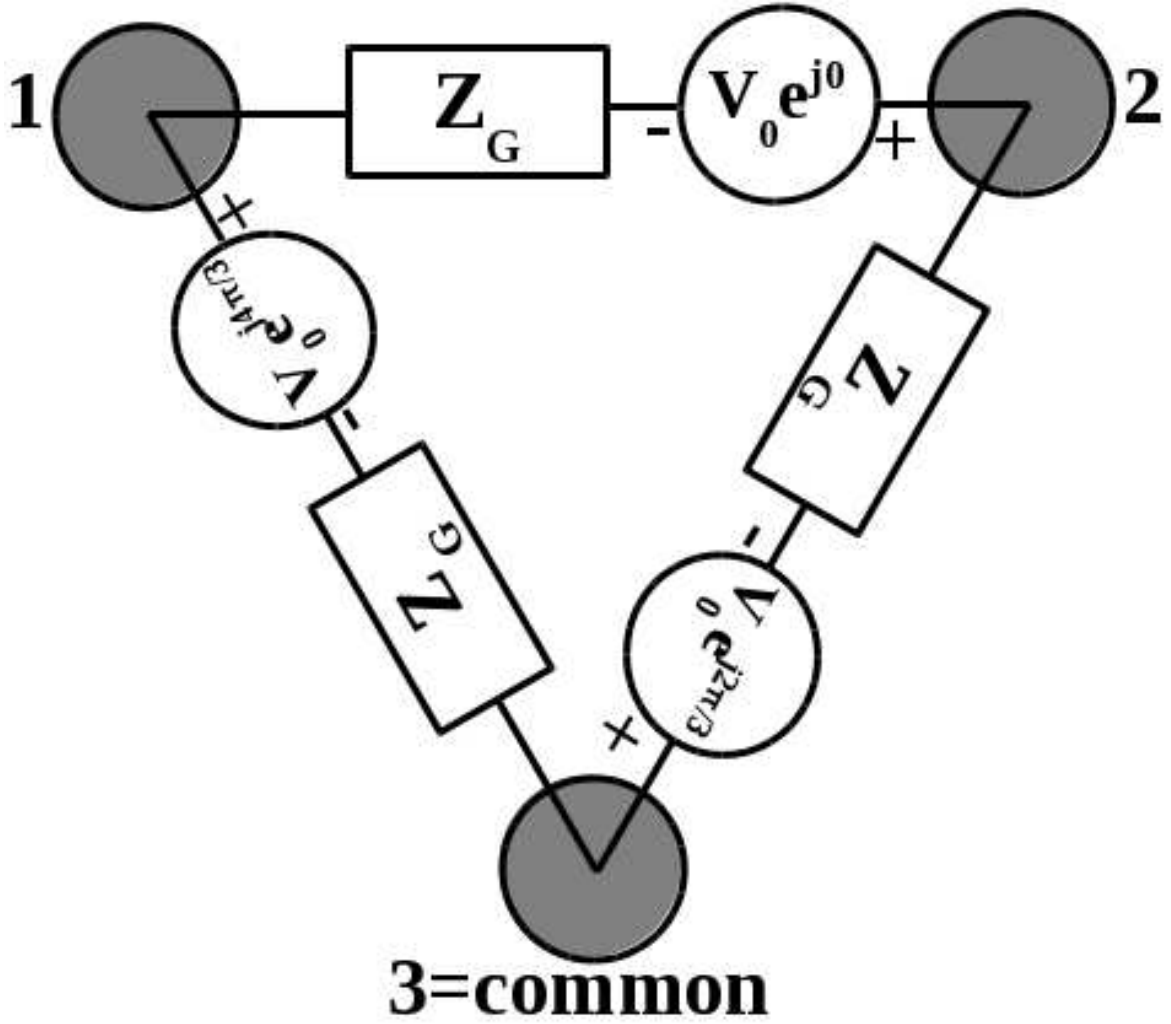


FIG. 7: Three phase generator with internal impedance Z_g feeding the 3 phase symmetric geometry transmission line with characteristic impedance matrix given in eq. (125). The magnitude of the voltage is V_0 RMS.

3 phase transmission line, provided the length is short compared to the wavelength, so that the characteristic impedance does not count when reflecting the load toward the generator.

IX. CONCLUSIONS

We developed here a different derivation for TEM waves guided by many perfect conductors in a homogeneous media, the connection between the multiconductor transmission line, source and load, and formulated the power transfer.

Using this formalism, we calculated the cross talk for a flat cable, and our result compares

well with the datasheet. It is to be mentioned that any multiconductor transmission line which does not have a diagonal representation suffers from cross talk.

The crosstalk is a major problem, due to which one has to reduce the information rate, therefore it deserves a special attention. An additional work on avoiding crosstalk is in preparation.

We generalized the formulation for time harmonic, and showed that in the general case the SWR is not defined, unless special symmetry conditions are satisfied, and for such case, one may express the propagation problem in a scalar form. Using this scalar form, we calculated the power transmitted into a 3 phase transmission line, obtaining the known expression for the power in 3 phase transmission lines.

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