

# Two Uncertain Things

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# [Build-up](#page-2-0)

- [Sample Space](#page-3-0)
- **•** [Probability Measures](#page-5-0)
- [Belief and Plausibility Measures](#page-10-0)
- 2 [The First Uncertain Thing](#page-23-0)
	- **•** [Assumptions](#page-24-0)
	- [Progress](#page-25-0)

# 3 [Build-up Again](#page-27-0)

- [Conditioning Belief Measures to Update Knowledge](#page-28-0)
- [Meaningful Measure of Uncertainty with Beliefs](#page-29-0)
- [Generalized Hartley's Measure with Beliefs](#page-30-0)
- [Generalized Shannon's Measure with Beliefs](#page-31-0)
- [Aggregate Uncertainty](#page-32-0)
- 4 [The Second Uncertain Thing](#page-34-0)
	- **•** [Assumptions](#page-35-0)
	- [Progress](#page-36-0)

**KORK EXTERNE PROVIDE** 

# 1 [Build-up](#page-2-0)

- [Sample Space](#page-3-0)
- **[Probability Measures](#page-5-0)**
- [Belief and Plausibility Measures](#page-10-0)
- [The First Uncertain Thing](#page-23-0)
	- **•** [Assumptions](#page-24-0)
	- [Progress](#page-25-0)

# [Build-up Again](#page-27-0)

- **[Conditioning Belief Measures to Update Knowledge](#page-28-0)**
- [Meaningful Measure of Uncertainty with Beliefs](#page-29-0)
- [Generalized Hartley's Measure with Beliefs](#page-30-0)
- [Generalized Shannon's Measure with Beliefs](#page-31-0)
- **[Aggregate Uncertainty](#page-32-0)**
- <span id="page-2-0"></span>[The Second Uncertain Thing](#page-34-0)
	- **•** [Assumptions](#page-35-0)
	- [Progress](#page-36-0)



### Sample Space (Frame of Discernment)

- A set of possible worlds/states/elementary outcomes  $W = \{w_1, ..., w_n\}$
- $\bullet$  An agent considers some subset of W possible and this subset qualitatively measures her uncertainty
- The more worlds an agent considers possible, the more uncertain she is, and the less she knows
- When throwing a dice, the sample space would be  $W = \{w_1, w_2, w_3, w_4, w_5, w_6\}$ , w<sub>i</sub> means the dice lands *i*
- <span id="page-3-0"></span>An agent can consider the dice landing on an even number possible, that is the subset  $W = \{w_2, w_4, w_6\}$



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- A method for representing uncertainty
- Given a sample space  $W = \{w_1, ..., w_n\}$ , a probability measure assigns to each world  $w_i$  a number (a probability)
- <span id="page-5-0"></span>This probability describes the likelihood that the world  $w_i$  is the actual world

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#### Algebra

- An algebra over W is a set F of subsets of W that contains W and is closed under union and complementation
- If A and B are in F, then so are  $A \cup B$  and A

 $\bullet$  Given a sample space  $W$ , a probability measure is a function  $\mu$ :  $F \rightarrow [0, 1]$  that satisfies the following two properties:

$$
\bullet~~\mu(W)=1
$$

<span id="page-6-0"></span> $\bullet$  Finite additivity:  $\mu(A \cup B) = \mu(A) + \mu(B)$  if A and B are disjoint sets in F

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- When flipping a coin, the sample space would be  $W = \{w_H, w_T\}$
- An algebra:  $F = \{\{w_H\}, \{w_T\}, \{w_H, w_T\}\}\$
- A probability measure:  $\mu : F \rightarrow [0, 1]$

<span id="page-8-0"></span>• 
$$
\mu({w_H}) = 0.7, \mu({w_T}) = 0.3
$$
  
\n•  $\mu({w_H, w_T}) = \mu({w_H}) + \mu({w_T}) = 1$ 

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- Probability measures are not good at representing uncertainty because of the finite additivity property
- Ignorance is difficult to express an agent has to assign a probability to  $\{w_H\}$
- <span id="page-9-0"></span>An agent may not have the computational power to compute all the probabilities



#### Belief Measure

 $\bullet$  Given a sample space W, a belief measure is a function Bel :  $2^W \rightarrow [0, 1]$  that satisfies the following three properties:

• 
$$
Bel(\emptyset) = 0
$$

$$
\bullet\;\;Bel(W)=1
$$

- **Inclusion-exclusion rule:**  $Bel(A_1 \cup A_2 \cup ... \cup A_n) \geq \sum_j Bel(A_j) - \sum_{j < k} Bel(A_j \cap A_k) +$  $\dots + (-1)^{n+1}$ Bel(A<sub>1</sub> ∩ A<sub>2</sub> ∩ ... ∩ A<sub>n</sub>) (Ω<sub>1</sub>)
- <span id="page-10-0"></span>• In  $(\Omega_1)$ , let  $A_1 = A$  and  $A_2 = \overline{A}$  for  $n = 2$ . Then  $Bel(A \cup \overline{A}) > Bel(A) + Bel(\overline{A}) - Bel(A \cap \overline{A})$  which gives  $Bel(A) + Bel(A) \leq 1$

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- <span id="page-11-0"></span>• In  $(\Omega_1)$ , let  $A_1 = A$  and  $A_2 = \overline{A}$  for  $n = 2$ . Then  $Bel(A \cup \overline{A}) \ge Bel(A) + Bel(\overline{A}) - Bel(A \cap \overline{A})$  which gives  $Bel(A) + Bel(\overline{A}) \leq 1$

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#### Plausibility Measure

- $\bullet$  Given a sample space W, a plausibility measure is a function  $PI: 2^W \rightarrow [0, 1]$  that satisfies the following three properties:
	- $Pl(\emptyset) = 0$

$$
\bullet \ \mathsf{PI}(W) = 1
$$

Inclusion-exclusion rule:  $Pl(A_1 \cap A_2 \cap ... \cap A_n) \leq \sum Pl(A_j) -$ 

$$
\sum_{j < k} P I(A_j \cup A_k) + \ldots + (-1)^{n+1} Bel(A_1 \cup A_2 \cup \ldots \cup A_n) \quad (\Omega_2)
$$

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<span id="page-12-0"></span>• In  $(\Omega_2)$ , let  $A_1 = A$  and  $A_2 = \overline{A}$  for  $n = 2$ . Then  $PI(A \cap \overline{A}) \leq PI(A) + PI(\overline{A}) - PI(A \cup \overline{A})$  which gives  $Pl(A) + Pl(\overline{A}) > 1$ 



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$$
\sum_{j < k} P I(A_j \cup A_k) + \ldots + (-1)^{n+1} Bel(A_1 \cup A_2 \cup \ldots \cup A_n) \quad (\Omega_2)
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<span id="page-13-0"></span>• In  $(\Omega_2)$ , let  $A_1 = A$  and  $A_2 = \overline{A}$  for  $n = 2$ . Then  $PI(A \cap \overline{A}) \leq PI(A) + PI(\overline{A}) - PI(A \cup \overline{A})$  which gives  $Pl(A) + Pl(\overline{A}) > 1$ 



#### Basic Belief Assignment (Mass Function) (Möbius Representation)

 $\bullet$  Given a sample space W, a basic belief assignment is a function  $m: 2^W \rightarrow [0, 1]$  that satisfies the following two properties:

$$
\begin{array}{ll} \bullet & m(\varnothing) = 0 \\ \bullet & \sum\limits_{A \in 2^W} m(A) = 1 \end{array}
$$

- $\bullet$  m(A)  $\geq$  0
- If  $m(A) > 0$  then A is a focal set
- Let  $\mathcal F$  be the set of all focal sets induced by m, then  $\langle \mathcal F, m \rangle$ is a body of evidence

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<span id="page-14-0"></span>• It is clear that a bba resembles a probability distribution



#### Basic Belief Assignment (Mass Function) (Möbius Representation)

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$$
\begin{array}{ll} \bullet & m(\varnothing) = 0 \\ \bullet & \sum\limits_{A \in 2^W} m(A) = 1 \end{array}
$$

- $m(A) > 0$
- If  $m(A) > 0$  then A is a focal set
- Let F be the set of all focal sets induced by m, then  $\langle F, m \rangle$ is a body of evidence

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<span id="page-15-0"></span>• It is clear that a bba resembles a probability distribution function



### Some Formulas

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- Bel(A) is the total belief that the actual world is in the set A which is obtained by adding degrees of evidence for the set itself, as well as for any of its subsets
- $\bullet$  PI(A) is the total belief that the actual world is in the set A, and also the partial evidence for the set that is associated with any set that overlaps with A
- <span id="page-17-0"></span> $\bullet$  m(A) is the degree of belief that the actual world is in the set A, but it does not take into account any additional evidence for the various subsets of A



 $\bullet$   $Q(A)$  is the total belief that can move freely to every point of A

- The interval  $[Bel(A), Pl(A)]$  describes the range of possible values of the likelihood of A
- <span id="page-18-0"></span> $\bullet$  If W is finite, then there is one-to-one correspondence between belief measures and bbas



#### Total Ignorance

- When no evidence is available about the actual world
- Capture it using a vacuous bba  $m_{vac}: 2^W \rightarrow [0, 1]$  where  $m\text{vac}(W) = 1$  and  $m\text{vac}(A) = 0$  for all  $A \in 2^W \backslash W$
- Capture it using a vacuous belief measure  $Bel_{\text{vac}} : 2^W \rightarrow [0, 1]$ where  $Bel_{vac}(W) = 1$  and  $Bel_{vac}(A) = 0$  for all  $A \in 2^W \backslash W$
- <span id="page-19-0"></span>• Capture it using a vacuous plausibility measure  $Pl_{vac}: 2^W \rightarrow [0, 1]$  where  $Pl_{vac}(\emptyset) = 0$  and  $Pl_{vac}(A) = 1$  for all  $A \neq \emptyset$

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- A bag contains 100 balls; 25 are known to be red, 25 are known to be either red or blue, and 50 are known to be either blue or yellow.
- The sample space  $W = \{ red, blue, yellow\}$
- <span id="page-20-0"></span>• The bba  $m: 2^W \rightarrow [0, 1]$  where  $m({red}) = 0.25$ ,  $m({red, blue}) = 0.25, m({blue, yellow}) = 0.5, and$  $m({b|ue}) = m({v|du}) = m({red, yellow}) = m(W) = 0$



- The belief measure  $Bel: 2^W \rightarrow [0, 1]$  where  $Bel({red}) = 0.25, Bel({red, blue}) = 0.5,$  $Bel({$  [blue, yellow  $) = 0.5$ ,  $Bel({\{blue\}}) = Bel({\{yellow\}}) = 0,$  $Bel({red, yellow}) = 0.25$ , and  $Bel(W) = 1$
- <span id="page-21-0"></span>• The plausibility measure  $Pl: 2^W \rightarrow [0, 1]$  where  $Pl({red}) = 0.5, Pl({blue}) = 0.75, Pl({yellow}) = 0.5,$  $PI({red, blue}) = 1, PI({blue, yellow}) = 0.75,$  $PI({red, yellow}) = 1$ , and  $PI(W) = 1$



#### Rule of Combination

- Used to combine evidence obtained from two independent sources
- Assume that the degrees of evidence 1 and 2 are captured using the bbas  $m_1$  and  $m_2$  respectively
- $m_{1,2}(A)=\frac{\sum\limits_{B\cap C=A}m_1(B)m_2(C)}{1-c}$  $\overline{a_{1-c}}$  where  $A\neq\varnothing$ ,  $m_{1,2}(\varnothing)=0$ , and  $c = \sum m_1(B)m_2(C)$  $B \cap C = \emptyset$
- c is the degree of conflict between the two evidence
- The rule is commutative  $m_{1,2} = m_{2,1}$
- The rule is associative  $m_{1,(2,3)} = m_{(1,2),3}$
- <span id="page-22-0"></span>• The neutral element is  $m_{\text{vac}}$ , that is  $m_{1,\text{vac}} = m_{\text{vac}}$ ,  $1 = m_1$

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- [Sample Space](#page-3-0)
- **[Probability Measures](#page-5-0)**
- [Belief and Plausibility Measures](#page-10-0)

# 2 [The First Uncertain Thing](#page-23-0)

- **•** [Assumptions](#page-24-0)
- [Progress](#page-25-0)

# [Build-up Again](#page-27-0)

- **[Conditioning Belief Measures to Update Knowledge](#page-28-0)**
- [Meaningful Measure of Uncertainty with Beliefs](#page-29-0)
- [Generalized Hartley's Measure with Beliefs](#page-30-0)
- [Generalized Shannon's Measure with Beliefs](#page-31-0)
- **[Aggregate Uncertainty](#page-32-0)**
- <span id="page-23-0"></span>[The Second Uncertain Thing](#page-34-0)
	- **•** [Assumptions](#page-35-0)
	- [Progress](#page-36-0)



- A computing system has a number of possible states represented by the space W
- $\bullet$  Over a time period t, the actual state of the system is in the set  $A \in 2^W$
- <span id="page-24-0"></span> $\bullet$  Over the same time period t, an attacker is trying to discover this actual state



- Initially, the attacker has no evidence about the actual state
- $m_{\text{vac}} : 2^W \rightarrow [0, 1]$  where  $m(W) = 1$  and  $m(A) = 0$  for all  $A \in 2^W \backslash W$
- $\bullet$  The attacker obtains evidence from source  $src_1$  that the actual state is in the set  $A \in 2^W$

$$
\bullet \ \ m_1: 2^{\mathcal W} \rightarrow [0,1] \ \text{where} \ \ m(A) = \alpha_1 > 0 \ \text{and} \ \ m(\mathcal W) = 1-\alpha_1
$$

 $\bullet$  ...

- $\bullet$  The attacker obtains the last evidence from source  $src_n$  that the actual state is in the set  $A \in 2^W$
- <span id="page-25-0"></span>•  $m_n: 2^W \to [0, 1]$  where  $m(A) = \alpha_n > 0$  and  $m(W) = 1 - \alpha_n$

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- Assuming that the sources  $src_1, ..., src_n$  are independent
- The attacker will combine to get  $m_1$ ,  $_n(W) = (1 - \alpha_1) \times ... \times (1 - \alpha_n)$  and  $m_1$ ,  $n(A) = 1 - (1 - \alpha_1) \times ... \times (1 - \alpha_n)$
- The Law of Large Numbers says that  $m_1$ ,  $n(A)$  will eventually reach 1
- When this happens, the attacker will have full belief that the actual state is in the set  $A \in 2^W$ , which means that the system is compromised.
- <span id="page-26-0"></span>• Poisoning the values of  $\alpha_1, ..., \alpha_n$  by minimizing them would delay the satisfaction of the Law of Large Numbers, possibly until a next time period  $t^{'}$  by the start of which the system becomes in a different actual state

**KORK EXTERNE PROVIDE** 

- [Sample Space](#page-3-0)
- **[Probability Measures](#page-5-0)**
- [Belief and Plausibility Measures](#page-10-0)
- [The First Uncertain Thing](#page-23-0)
	- **•** [Assumptions](#page-24-0)
	- [Progress](#page-25-0)

# 3 [Build-up Again](#page-27-0)

- **[Conditioning Belief Measures to Update Knowledge](#page-28-0)**
- [Meaningful Measure of Uncertainty with Beliefs](#page-29-0)
- [Generalized Hartley's Measure with Beliefs](#page-30-0)
- [Generalized Shannon's Measure with Beliefs](#page-31-0)
- **[Aggregate Uncertainty](#page-32-0)**
- <span id="page-27-0"></span>[The Second Uncertain Thing](#page-34-0)
	- **•** [Assumptions](#page-35-0)
	- [Progress](#page-36-0)



#### Conditioning Belief Measures to Update Knowledge

- An agent has an evidence that the actual world is in the set  $A \in 2^W$
- Later she obtains another evidence that the actual world is in the set  $B \in 2^W$

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• How can she update her knowledge?

• 
$$
Bel(B||A) = \frac{Bel(B\cup \overline{A}) - Bel(\overline{A})}{1 - Bel(\overline{A})}
$$

<span id="page-28-0"></span>
$$
\bullet \ \textit{PI}(B||A) = \frac{\textit{PI}(B \cap A)}{\textit{PI}(A)}
$$

[Meaningful Measure of Uncertainty with Beliefs](#page-29-0)

#### Meaningful Measure of Uncertainty with Beliefs

A measure  $M$  of the uncertainty of Bel is meaningful if it satisfies the following properties:

- $\bullet$  Probability Consistency: If all focal sets are singletons, M should assume Shannon's entropy:  $\mathcal{M}(Bel) = -\sum Bel(\{x\})log_2Bel(\{x\})$ x∈W
- 2 Set Consistency: If Bel focuses on a single set  $A \subseteq W$ , M should assume Hartley's entropy:  $\mathcal{M}(Bel) = log_2|A|$
- **3** Expansibility: The range of M is  $[0, log_2|W|]$  and M is measured in bits
- $\bullet$  Subadditivity: Let Bel<sub>1</sub>, Bel<sub>2</sub>, and Bel be bbas on  $W_1$ ,  $W_2$ , and  $W_1 \times W_2$ , then  $\mathcal{M}(Bel) \leq \mathcal{M}(Bel_1) + \mathcal{M}(Bel_2)$
- <span id="page-29-0"></span> $\bullet$  Additivity: Let Bel<sub>1</sub>, Bel<sub>2</sub>, and Bel be bbas on  $W_1$ ,  $W_2$ , and  $W_1 \times W_2$ , and assume that Bel<sub>1</sub> and Bel<sub>2</sub> are noninteractive, then  $\mathcal{M}(Bel) = \mathcal{M}(Bel_1) + \mathcal{M}(Bel_2)$



### Generalized Hartley's Measure (U-uncertainty)

- Given a sample space W and a body of evidence  $\langle F, m \rangle$  on this space, the generalized Hartley's measure is given by the formula:  $GH(m) = \sum m(A)log_2|A|$  $\Delta \subset \mathcal{F}$
- It has the Expansibility Property  $GH(m) \in [0, log_2 |W|]$  and is measured in bits
	- lower bound when all focal sets are singletons
	- upper bound in total ignorance
- It has the Subadditivity Property:  $GH(m) \leq GH(m_1) + GH(m_2)$
- <span id="page-30-0"></span>• It has the Additivity Property:  $GH(m) = GH(m_1) + GH(m_2)$

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[Generalized Shannon's Measure with Beliefs](#page-31-0)

### Generalized Shannon's Measure with Beliefs

A number of unsuccessful attempts to generalize Shannon's measure with beliefs.

**1** Measure of Dissonance:  $E(m) = -\sum_{A \in \mathcal{F}} m(A)log_2Pl(A)$ 

• Measure of Confusion: 
$$
C(m) = -\sum_{A \in \mathcal{F}} m(A) \log_2 Bel(A)
$$

$$
\text{Measure of Discord:} \\ D(m) = -\sum_{A \in \mathcal{F}} m(A) \log_2 \left(1 - \sum_{B \in \mathcal{F}} m(B) \frac{|B-A|}{|B|} \right)
$$

A∈F **4** Measure of Strife:  $\sqrt{2}$ 

$$
ST(m) = -\sum_{A \in \mathcal{F}} m(A) \log_2 \left( 1 - \sum_{B \in \mathcal{F}} m(B) \frac{|A - B|}{|A|} \right)
$$

- All of these measures do not have the Subadditivity Property, and are thus meaningless.
- <span id="page-31-0"></span>• This frustrated search was replaced with Aggregate **Uncertainty**



#### Aggregate Uncertainty

• 
$$
AU(Bel) = \max_{\mathcal{P}_{Bel}} \left\{-\sum_{x \in W} p_x \log_2 p_x \right\}
$$

 $\bullet$   $P_{Bel}$  is a set of probability distributions that satisfies:

• 
$$
p_x \in [0, 1]
$$
 for all  $x \in W$  and  $\sum_{x \in W} p_x = 1$ 

• 
$$
Bel(A) \leq \sum_{x \in A} p_x
$$
 for all  $A \subseteq W$ 

<span id="page-32-0"></span> $\bullet$  AU is a meaningful measure of uncertainty with beliefs

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#### Efficient Algorithm

<span id="page-33-0"></span> $\textbf{D}$  Find a nonempty set  $A\subseteq W$  such that  $\frac{Bel(A)}{|A|}$  is maximal 2 For  $x\in A$ , let  $p_{x}=\frac{Bel(A)}{|A|}$  $|A|$  $\bullet$  For each  $B \subseteq W - A$ , let  $Bel(B) = Bel(B \cup A) - Bel(A)$  $\bullet$  Let  $W = W - A$ **•** If  $W \neq \emptyset$  and  $Bel(W) > 0$ , go to 1 **6** If  $W \neq \emptyset$  and  $Bel(W) = 0$ , let  $p_x = 0$  for all  $x \in W$  $\bullet$  Compute  $AU(Bel) = \sum \; p_{\chi} log_2 p_{\chi}$ x∈W

**KORK EXTERNE PROVIDE** 

- [Sample Space](#page-3-0)
- **[Probability Measures](#page-5-0)**
- [Belief and Plausibility Measures](#page-10-0)
- [The First Uncertain Thing](#page-23-0)
	- **•** [Assumptions](#page-24-0)
	- [Progress](#page-25-0)

# [Build-up Again](#page-27-0)

- **[Conditioning Belief Measures to Update Knowledge](#page-28-0)**
- [Meaningful Measure of Uncertainty with Beliefs](#page-29-0)
- [Generalized Hartley's Measure with Beliefs](#page-30-0)
- [Generalized Shannon's Measure with Beliefs](#page-31-0)
- **[Aggregate Uncertainty](#page-32-0)**

# 4 [The Second Uncertain Thing](#page-34-0)

- **•** [Assumptions](#page-35-0)
- <span id="page-34-0"></span>• [Progress](#page-36-0)



- A sample space  $W = \{x_1, x_2, x_3\}$  of three confidential bank balances
- An attacker would like to learn the highest bank balance by monitoring the execution of the following program: int  $i = 1$ : bool  $f = true$ ; while (i  $\leq$  3) { if  $(x[i] > g)$  {  $f = false$ } i++; } cout  $<< f <<$  endl;
- <span id="page-35-0"></span>•  $g \in \{x_1, x_2, x_3\}$  is the attacker's guess and f is a flag that tells whether this guess is correct or not



• 
$$
m: 2^W \rightarrow [0, 1]
$$
 where  $m(\{x_1, x_2\}) = 0.8$  and  $m(\{x_2, x_3\}) = 0.2$ 



\n- $$
p_{x_1} = p_{x_2} = 0.4
$$
\n- $W - A = \{x_1, x_2, x_3\} - \{x_1, x_2\} = \{x_3\}$
\n- $Bel(\{x_3\}) = Bel(\{x_1, x_2, x_3\}) - Bel(\{x_1, x_2\}) = 1 - 0.4 = 0.6$
\n

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<span id="page-36-0"></span>• 
$$
W = W - A = \{x_1, x_2, x_3\} - \{x_1, x_2\} = \{x_3\}
$$



• Since 
$$
W \neq \emptyset
$$
 and  $Bel(W) > 0$ , we repeat the process



**KORK ERKER ADAM ADA** 

$$
\bullet \ \ p_{x_3}=0.6
$$

- $W A = \{x_3\} \{x_3\} = \{\}$  we stop here!
- <span id="page-37-0"></span> $\bullet$  AU(Bel) = -0.4log0.4 - 0.4log0.4 - 0.6log0.6 =  $0.528 + 0.528 + 0.442 = 1.498$  bits



- The attacker has a higher degree of belief that the highest bank balance is in the set  $\{x_1, x_2\} \rightsquigarrow$  she feeds the program with  $x_1$
- Suppose she gets a *true* flag
- The attacker will update her beliefs and get:  $Bel({x_1, x_2}||{x_1}) = 1.0$  and  $Bel({x_2, x_3}||{x_1}) = 0.0$
- <span id="page-38-0"></span>•  $AU(Bel)$  would be 1.5 bits  $\rightsquigarrow$  0.002 increase in uncertainty

**KORKAR KERKER SAGA** 



- The attacker has a higher degree of belief that the highest bank balance is in the set  $\{x_1, x_2\} \rightsquigarrow$  she feeds the program with  $x_1$
- Suppose she gets a *flase* flag
- The attacker will update her beliefs and get:  $Bel({x_1, x_2}||{x_2, x_3}) = 0.8$  and  $Bel({x_2, x_3})||{x_2, x_3}) = 1.0$
- <span id="page-39-0"></span>• Again (!!!)  $AU(Bel)$  would be 1.5 bits  $\rightsquigarrow$  0.002 increase in uncertainty

**KORKAR KERKER SAGA** 

[Build-up](#page-2-0) [The First Uncertain Thing](#page-23-0) [Build-up Again](#page-27-0) [The Second Uncertain Thing](#page-34-0) [Thank You](#page-40-0)

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# <span id="page-40-0"></span>**Thank You!**