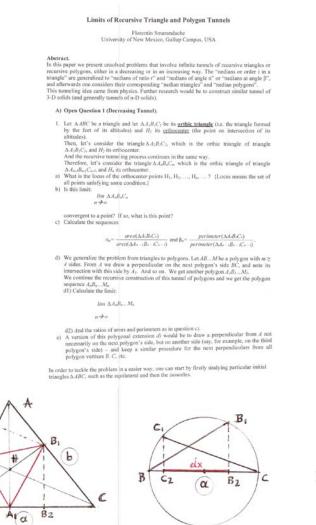
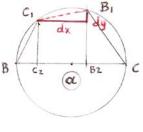
### ENERGY LAWS, FOLLOW MOULDS OF EUCLIDEAN GEOMETRY. AND THE SIX, TRIPLE - CONCURRENCY POINTS, LINE.

A geometrical attempt was developed for approaching the Open question 1 [The Orthic triangle] concerning the the locus of centerpoints H1...n and the point of convergency. A further Analysis in Euclidean geometry follows. Markos Georgallides : Tel-00357-99 634628 Civil Engineer(NATUA) : Fax-00357-24 653551 15, N.Mylona St, 6010, Larnaca Cyprus Expeled from Famagusta town occupied by The Barbaric Turks. Email < georgallides.marcos@cytanet.com.cy >

The present article `Energy Laws, follow moulds of Euclidean Geometry', demonstrates the correlation of < Changeable Areas in a closed or Isolated Figure (Any triangle or Square in a circle) to a Totally constant Area > to the < Constant Total Energy in a closed or Isolated System > The article, Six, [Triple - Points], Line, shows correspondences of lengths and angles, of Projective and other Geometries, under Euclidean First dimensional Unit, which is one, Duality, Triple and Multiple. P.12, P19.



F.1(2)



F.1(3)

THE ORTHOCENTER (H) OF A TRIANGLE (ABC)

F.1(1)

C

B

15 / 1 / 2012

Let  $\triangle$  ABC be any triangle with vertices A, B, C and let  $\triangle$  A1B1C1 be its orthic triangle.

AA1, BB1, CC1 are the altitudes of the vertices and points A1, B1, C1 the feet of them. Altitudes AA1  $\perp$  BC, BB1  $\perp$  AC, CC1  $\perp$  AB and triangles AA1 B, AA1 C, BB1A, BB1C CC1A, CC1B are all right angled. It is also holding B1B<sup>-</sup>1  $\perp$  AB

 $E_{ABC} = E = Area of triangle ABC and let be$  $<math>E_A = E_{AB1C1} = Area of triangle AB1C1$ ,  $E_B = E_{BC1A1} = Area of triangle BC1A1$ ,  $E_C = E_{CA1B1} = Area of triangle AC1B1$ .

For shortness, we use the known ratios on any right angle triangle ABC at C : The ratio of opposite side BC = a to the hypotenuse AB = c is called , sine of angle A,  $(\sin A = a/c)$  and the ratio of the adjacent side AC = b to the hypotenuse AB is called cosine of angle A  $(\cos A = a/c)$ . It is known,

 $E_{A} = E_{AB1C1} = \frac{1}{2} \cdot AC1 \cdot B1B \cdot 1 = \frac{1}{2} \cdot AC1 \cdot [AB1 \cdot sinA] = \frac{1}{2} \cdot AC1 \cdot AB1 \cdot sinA \dots (1)$  $E_{ABC} = \frac{1}{2} \cdot AB \cdot CC1 = \frac{1}{2} \cdot AB.AC. \sin A \dots (2)$ 

By division :  $E_A / E_{ABC} = [AC_1 \cdot AB_1 \cdot sinA] / [AB \cdot AC \cdot sinA] = [AC_1 \cdot AB_1 \cdot AB_1 \cdot AC]$ 

and for  $AC1 = AC. \cos A = [b. \cos A]$ ,  $AB1 = AB. \cos A = [c. \cos A]$  and also

Using rotational similarity then :

| (3a) | $[\mathbf{b} \cdot \cos \mathbf{A} \cdot \mathbf{c} \cdot \cos \mathbf{A}] / [\mathbf{b} \cdot \mathbf{c}] = \cos^2 \mathbf{A}$ | $\mathbf{E} \mathbf{A} / \mathbf{E} \mathbf{ABC} =$ |
|------|---|---|
| (3b) | $[\mathbf{c}.\cos A \cdot \mathbf{a}.\cos A] / [\mathbf{c} \cdot \mathbf{a}] = \cos^2 \mathbf{B}$                               | $\mathbf{E} \mathbf{B} / \mathbf{E} \mathbf{ABC} =$ |
| (3c) | $[\mathbf{a} . \cos \mathbf{A} \cdot \mathbf{b} . \cos \mathbf{A}] / [\mathbf{a} \cdot \mathbf{b}] = \cos^2 \mathbf{C}$         | $\mathbf{E} \mathbf{c} / \mathbf{E} \mathbf{ABC} =$ |

The area of the three triangles is,

 $E_A = E_{ABC} \cdot \cos^2 A = E_{\cdot} \cos^2 A$   $E_B = E_{ABC} \cdot \cos^2 B = E_{\cdot} \cos^2 B$  $E_C = E_{ABC} \cdot \cos^2 C = E_{\cdot} \cos^2 C$  by summation :

 $E_{A}+E_{B}+E_{C} = E.cos^{2}A + E.cos^{2}B + E.cos^{2}C = E.[cos^{2}A + cos^{2}B + cos^{2}C]$ , so

Area of triangle A1B1C1 is 
$$E_1 = E - [E_A + E_B + E_C] = E \cdot [1 - \cos^2 A - \cos^2 B - \cos^2 C]$$
 or

$$E_1 = E \cdot [1 - \cos^2 A - \cos^2 B - \cos^2 C] = E \cdot [1 - (AB1/c)^2 - (BC1/a)^2 - (CA1/b)^2] \dots (4)$$

Replacing the results of (6.abc) in (4), then using,

 $\begin{aligned} 4.a^{2}b^{2}c^{2}.[1 - \cos^{2}A - \cos^{2}B - \cos^{2}C] &= 4.a^{2}b^{2}c^{2} - [a6 + a^{2}b^{4} + a^{2}c^{4} - 2.a^{4}b^{2} - 2.a^{4}c^{2} + 2.a^{2}.b^{2}.c^{2}] \\ -[b6 - 2.a^{2}b^{4} + b^{2}c^{4} - 2.b^{4}c^{2} + a^{4}b^{2} + 2.a^{2}.b^{2}.c^{2}] - [c6 - 2.a^{2}c^{4} + b^{4}c^{2} - 2.b^{2}c^{4} + a^{4}c^{2} + 2.a^{2}.b^{2}.c^{2}] \\ = a^{4}.b^{2} + a^{4}.c^{2} + a^{2}.b^{4} + a^{2}.c^{4} + b^{4}.c^{2} + b^{2}.c^{4} - 2.a^{2}.b^{2}.c^{2} - a6 - b6 - c6. \end{aligned}$ 

then the ratio of area E1 of the Orthic triangle to the area E of the triangle ABC is :

Verification :

For equilateral triangle 
$$a = b = c \rightarrow E1 / E = (6.a6 - 2.a6 - 3.a6)/4.a6 = a6/4.a6 = 1/4$$
  
For isosceles triangle  $a , b = c \rightarrow E1 / E = [2.a^4.b^2 + 2.a^2.b^4 - 2.a^2.b^4 - a6]/4.a^2.b^4$   
 $= [2.a^4.b^2 - a6]/4.a^2.b^4 = [2.a^2.b^2 - a^4]/4.b^4 = a^2.(2.b^2 - a^2)/4.b^4$ 

Extensions to Pythagoras's theorem :

Using the general conversions of Pythagoras's theorem is easy to measure altitude la=AA1 , lb=BB1 , lc=CC1

In the right angled triangle  $ABA1 \rightarrow AA1^2 = AB^2 - BA1^2 = AB^2 - (BC - A1C)^2$  $AA1^2 = AB^2 - (BC^2 + A1C^2 - 2.BC A1C) = AB^2 - BC^2 - A1C^2 + 2.BC A1C$ In the right angled triangle  $AA1C \rightarrow AA1^2 = AC^2 - A1C^2$ and by subtraction,  $0 = AB^2 - BC^2 - A1C^2 + 2.BC \cdot A1C - AC^2 + A1C^2 = AB^2 - BC^2 - AC^2 + 2.BC \cdot A1C$ or 2.BC.A1C = AC<sup>2</sup> + BC<sup>2</sup> - AB<sup>2</sup>, so  $\rightarrow$  A1C = [AC<sup>2</sup> + BC<sup>2</sup> - AB<sup>2</sup>] /2.BC = [a<sup>2</sup> + b<sup>2</sup> - c<sup>2</sup>] / 2a  $A_1C = [a^2 + b^2 - c^2]/2.a$  ..... (6ac) also A1B = a - A1C = a -  $[a^2+b^2+c^2]/2.a = [2a^2-b^2-a^2+c^2]/2.a = [a^2+c^2-b^2]/2a$  $A_1B = [a^2 + c^2 - b^2] / 2.a$  ..... (6ab) exists also  $AA1^2 = AC^2 - CA1^2 = (AC + CA1) \cdot (AC - CA1)$ and by substitution (6ac) 4.  $a^{2}(AA_{1})^{2} = [a^{2}+b^{2}+2.ab - c^{2}] [c^{2}-b^{2}-a^{2}+2.ab] = 2.a^{2}b^{2}+2.a^{2}c^{2}+2.b^{2}c^{2}$  $- [a^4 + b^4 + c^4]$ or

4. 
$$a^{2}(AA_{1})^{2} = 4. a^{2}(la)^{2} = 2.a^{2}b^{2}+2. a^{2}c^{2}+2.b^{2}c^{2} - [a^{4}+b^{4}+c^{4}] .... (7a)$$
  
In right angled triangle BB1C → BB1<sup>2</sup> = BC<sup>2</sup> - B1C<sup>2</sup>.  
In right angled triangle BB1A → BB1<sup>2</sup> = BC<sup>2</sup> - (AC - B1C)<sup>2</sup> = BA<sup>2</sup> - AC<sup>2</sup> - B1C<sup>2</sup> + 2.AC,B1C  
and by subtraction , and  
0 = BC<sup>2</sup> - B1C<sup>2</sup> - BA<sup>2</sup> + AC<sup>2</sup> + B1C<sup>2</sup> - 2.AC,B1C  
Hen calculating B1C,B1A  
B1C=[-AB<sup>2</sup> + AC<sup>2</sup> + BC<sup>2</sup>] / 2.AC = [a<sup>2</sup>+b<sup>2</sup>-c<sup>2</sup>] / 2.b ....... (6bc)  
B1A = b - [a<sup>2</sup>+b<sup>2</sup>-c<sup>2</sup>] / 2.b =[2.b<sup>2</sup>-b<sup>2</sup>-a<sup>2</sup> + c<sup>2</sup>] / 2.b = [c<sup>2</sup>+b<sup>2</sup>-a<sup>2</sup>] / 2.b ....... (6ba)  
B1A = b - [a<sup>2</sup>+b<sup>2</sup>-c<sup>2</sup>] / 2.b =[2.b<sup>2</sup>-b<sup>2</sup>-a<sup>2</sup> + c<sup>2</sup>] / 2.b = [c<sup>2</sup>+b<sup>2</sup>-a<sup>2</sup>] / 2.b ........ (6ba)  
B1A = b - [a<sup>2</sup>+b<sup>2</sup>-c<sup>2</sup>] / 2.b =[2.b<sup>2</sup>-b<sup>2</sup>-a<sup>2</sup> + c<sup>2</sup>] / 2.b = [c<sup>2</sup>+b<sup>2</sup>-a<sup>2</sup>] / 2.b ........ (6ba)  
B1A<sup>2</sup> = BC<sup>2</sup> - B1C<sup>2</sup> = (BC + B1C) . (BC - B1C) = (a + B1C).(a - B1C) by substitution (6bc)  
4. b<sup>2</sup>(BB1)<sup>2</sup> = [a<sup>2</sup>+b<sup>2</sup>+2.ab - c<sup>2</sup>].[c<sup>2</sup>-b<sup>2</sup>-a<sup>2</sup> + 2.ab] = 2.a<sup>2</sup>b<sup>2</sup>+2.a<sup>2</sup>c<sup>2</sup>+2.b<sup>2</sup>c<sup>2</sup> - [a<sup>4</sup>+b<sup>4</sup>+c<sup>4</sup>] .... (7b)  
in the same way exists ,  
C1B = [CB<sup>2</sup> + AB<sup>2</sup> - AC<sup>2</sup>] / 2.AC = [a<sup>2</sup>+c<sup>2</sup>-b<sup>2</sup>] / 2.c ........ (6ca)  
also  
4. c<sup>2</sup>(CC1)<sup>2</sup> = 4. c<sup>2</sup>(lc)<sup>2</sup> = 2.a<sup>2</sup>b<sup>2</sup>+2.a<sup>2</sup>c<sup>2</sup>+2.b<sup>2</sup>c<sup>2</sup> - [a<sup>4</sup>+b<sup>4</sup>+c<sup>4</sup>] .... (7c)  
Ia = AA1 =  $\frac{\sqrt{[(a+b)^{2} - c^{2}].[c^{2} - (a - b)^{2}]}}{2.b}$  and altitudes la, lb, lc are  
Ia = AA1 =  $\frac{\sqrt{[(a+b)^{2} - c^{2}].[c^{2} - (a - b)^{2}]}}{2.b}$  Ic = CC1 =  $\frac{\sqrt{[(a+b)^{2} - c^{2}].[c^{2} - (a - b)^{2}]}}{2.c}$   
Verification :  
For a = b then C1A = C1B → C1A = [c<sup>2</sup>/2c] = c/2 → C1B = [c<sup>2</sup>/2c] = c/2  
For a = c then B1A = B1C → B1A = [b<sup>2</sup>/2b] = b/2 → B1C = [b<sup>2</sup>/2b] = b/2  
For b = c then A1B = A1C → A1B = [a<sup>2</sup>/2a] = a/2 → A1C = [a<sup>2</sup>/2a] = a/2

Since angle  $< BC1C = BB1C = 90^{\circ}$  then :

Using Pythagoras's theorem in F.1(2)  $\rightarrow BB1^2 = BB2.BC \rightarrow BB2 = BB1^2/BC$ 

 $2.a^2.b^2 + 2.a^2.c^2 + 2.b^2.c^2 - (a^4 + b^4 + c^4)$ **BB2** = [ BB1<sup>2</sup>] / BC = -----4.b<sup>2</sup>.a

$$\begin{aligned} & 2.a^{2}c^{2} - 2.a^{2}.b^{2} - 2.b^{2}.c^{2} + (a^{4}+b^{4}+c^{4}) \\ BC2 = [BC1^{2}] / BC = \frac{4.c^{2}.a}{4.c^{2}.a} \\ For dx = [BB2 - BC2] then : \\ & 4.a^{2}c^{2}. dx = 2.a^{2}b^{2}c^{2} + 2.a^{2}c^{4} + 2.b^{2}c^{4} - c^{2}b^{4} - c^{2}b^{4} - c^{4}b^{2} - b^{2}c^{4} + 2.a^{2}b^{4} + 2.a^{2}b^{4} + 2.a^{2}b^{4} + 2.a^{2}c^{4} + 2.b^{2}c^{2} + 2.a^{2}c^{4} + 2.b^{2}c^{2} + 2.a^{2}c^{4} + 2.b^{2}c^{2} + 2.a^{2}c^{4} + 2.b^{2}c^{2} + 2.a^{2}c^{2} + 2.b^{2}c^{2} - (a^{4}+b^{4}+c^{4})] / 4.b^{2} \\ & - [a^{2}+b^{2}-c^{2}]. [2.a^{2}b^{2} + 2.a^{2}c^{2} + 2.b^{2}c^{2} - (a^{4}+b^{4}+c^{4})] / 16a^{2}b^{4} = \\ [2.a^{2}b^{2} + 2.a^{2}c^{2} + 2.b^{2}c^{2} - (a^{4}+b^{4}+c^{4})] [2.a^{2}b^{2} - a^{2}c^{2} + 2.b^{2}c^{2} - (a^{4}+b^{4}+c^{4})] / 16a^{2}b^{4} = \\ [2.a^{2}b^{2} + 2.a^{2}c^{2} + 2.b^{2}c^{2} - (a^{4}+b^{4}+c^{4})] [c^{2} + 2.a^{2}b^{2} - a^{2}b^{2} + c^{2} ] / 16a^{2}b^{4} = \\ [2.a^{2}b^{2} + 2.a^{2}c^{2} + 2.b^{2}c^{2} - (a^{4}+b^{4}+c^{4})] [c^{2} + 2.a^{2}b^{2} - a^{2}b^{2} + c^{2} ] / 16a^{2}b^{4} = \\ [2.a^{2}b^{2} - a^{2}c^{2} + 2.b^{2}c^{2} - a^{4}b^{2} - a^{4}b^{2} - a^{4}c^{2} + b^{2}c^{4} + c^{2}b^{4} - b^{6} - c6 \quad or \\ dx = [BB2 - BC2] = [2.a^{2}b^{4} + 2.a^{2}b^{2} - a^{4}b^{2} - a^{4}c^{2} + b^{2}c^{4} + c^{2}b^{4} - b^{6} - c6 ] / 4.ab^{2}c^{2} ...(a) \\ Verification : \\ For b = c \rightarrow BAi = BC2 + [BB2 - BC2] / 2 = a/2 \\ dx = BB2 - BC2 = (4.a^{2}b^{4} - 2.a^{4}b^{2}) / 4.ab^{4} = (4.a^{2}b^{2} - 2.a^{3}) / 4.b^{2} = (2.ab^{2} - a^{3}) / 2.b^{2} \\ BAi = (a^{3}) / 4.b^{2} + (2.a^{2}b^{2} - 2.a^{2}b^{2}) / 4.ab^{4} = a/2 \\ Ax = BB2 - BC2 = (4.a^{2}b^{4} - 2.a^{4}b^{2}) / 4.ab^{4} = (4.a^{2}b^{2} - 2.a^{3}) / 4.b^{2} = (2.ab^{2} - a^{3}) / 2.b^{2} \\ From similar triangles CAA1, C B1B2 \rightarrow [B1B2 / AA1] = CB1/b and (B1B2)^{2} = [CB1^{2}.AA1^{2}] / b^{2} \\ Or \\ B1B2^{2} = (a^{2} + b^{2} - c^{2})^{2} . [(a+b)^{2} - c^{2}] . [c^{2} - (a+b)^{2}] / 16.a^{2}b^{4} \\ ........... \\ and so \\ B1B2^{2} = (a^{2} + b^{2} - c^{2}) . \sqrt{[c^{2} - (a+b)^{2} - 1.[c^{2} - (a-b)^{2}] / 4.b^{2} \\ ......... \\ Ac^{2} = (a^{2}$$

$$C1C2 = \frac{a^2}{4.ab^2} \sqrt{(b^2 - a^2 - b^2 - 2.ab) \cdot (a^2 + b^2 - 2.ab - b^2)} = \frac{a}{4.b^2} \sqrt{-(a^2 + 2.ab) \cdot (a^2 - 2.ab)}$$

$$[AA1]^{2} = b^{2} - a^{2} / 4 = (4.b^{2} - a^{2}) / 4 \longrightarrow AA1 = |\sqrt{4.b^{2} - a^{2}}| / 4$$

Let [B1B2-C1C2] = dy, then dy = [CB1, AA1]/b - [BC1, AA1]/c = [AA1].[c.CB1-b.BC1]/bc

c.CB1- b.BC1 = 
$$c.(a^2+b^2-c^2)/2.b - b.(a^2+c^2-b^2/2c = [a^2c^2-a^2b^2+b^4+c^4]/2.bc$$
 and

$$dy = [B1B2 - C1C2] = \frac{\sqrt{[c^2 - (a+b)^2] \cdot [(a-b)^2 - c^2]}}{4 \cdot a \cdot b^2 c^2} [a^2 c^2 - a^2 b^2 + b^4 + c^4] \quad \text{or}$$

$$dy = [B1B2 - C1C2] = \frac{\sqrt{[(a+b)^2 - c^2] \cdot [c^2 - (a-b)^2]}}{4 \cdot a \cdot b^2 c^2} [a^2 c^2 - a^2 b^2 + b^4 - c^4] \dots (b)$$

B1C1 is measured by using Pythagoras's theorem in triangle (B1B1, dy, dx) and then by squaring equation (a) and (b),

 $\begin{aligned} & dx^2 \cdot [4.a \ b^2 c^2]^2 = [4.a^4 b^8 + 4.a^4 c^8 + a^8 b^4 + \ a^8 c^4 + b^4 c^8 + \ b^8 c^4 + b12 + c12 - 4.a6.b6 - 4a6b^4 c^2 \\ & + 4.a^2 b6.c^4 + 4.a^2 b^8 c^2 - 4.a^2 b10 - 4.a^2 b^4 c6 + 8.a^4 b^4 c^4 - 4.a6b^2 c^4 - 4.a6.c6 + 4.a^2 b^2 c^8 + 4.a^2 b^4 c6 \\ & - 4.a^2 b6.c^4 - 4.a^2 c10 + 2a^8 b^2 c^2 - 2.a^4 b^4 c^4 - 2.a^4 b6c^2 + 2.a^4 b^8 + 2.a^4 b^2 c6 - 2.a^4 b^2 c6 - 2.a^4 b^4 c^4 + 2.a^4 b6c^2 + 2.a^4 c^8 + 2.b6.c6 - 2.b^8 c^4 - 2.b^2 c10 - 2.b10 c^2 - 2.b^4 c^8 + 2.b6.c6 \end{bmatrix} = \end{aligned}$ 

 $[ 4.a^{2}b^{2}c^{8} - 4.a^{2}b10 - 4.a^{2}c10 + 4.a^{2}b^{8}c^{2} + 6. a^{4}b^{8} + 6.a^{4}c^{8} + 4.a^{4}b^{4}c^{4} - 4.a6.b^{2}c^{4} - 4.a6.b^{4}c^{2} - 4.a6.b6 - 4.a6.c6 + 2a^{8}b^{2}c^{2} + a^{8}b^{4} + a^{8}c^{4} - 2.b^{2}c10 + 4.b6.c6 - b^{8}c^{4} - 2.b10c^{2} + b12 + c12 ]$ 

 $\begin{array}{l} 2.a6.c6 + 2.a6.b^4c^2 + 2.a^2b^8c^2 + 2.a^2c10 & -4.a6b^2c^4 + 4.a^4 \ b^4c^4 - 4.a^4c^8 & -4.a^4b6c^2 + 4.a^4b^2c6 \\ -4.a^2b^4c6 + 2.a6.c6 & -4.a6.b^4c^2 + 2.a^2b^2c^8 & +4.a^2b10 + 2.a6.b^2c^4 + 4.a^4 \ b^4c^4 - 4.a^4b^8 + 4.a^4b6c^2 \\ -4.a^4b^2c6 & -4.a^2b6.c^4 - 4.a6.c6 & -4.a^2b^2c^8 & +2.b10c^2 & + c^4 + 4.a^2b^4c6 & -4.a^4 \ b^4c^4 + 2.a^4b6c^2 \\ +2.a^4b^2c6 \ c6 & + 2.a^2b6.c^4 - 4.a^2b^8c^2 & +2.b^2c10 & -a^8c^4 & -a^8b^4 & -a^4b^8 & -a^4c^8 + 2.a^8b^2c^2 \\ -2.a6.b^4c^2 + \ 4.a6.c6 & + 2.a6.b6 & - 2.a6.b^2c^4 + 2.a^4 \ b^4c^4 + \ 2.a^8c^4 & -b^4c^8 & -a^4b^8 & - 2.a^2b6.c^4 \\ 2.a^4b6c^2 & -2.a^2b^8c^2 + 2.a^2b^4c6 & +2.b^2c10 & -a^4 \ b^4c^4 - b12 & -b^8c^4 + 2.b^4c^8 & -a^4c^8 + 2.a^4b^2c6 \\ -2.a^2b^4c6 & +2.a^2c10 + 2.a^2b6.c^4 & -2.a^2b^2c^8 & -a^4 \ b^4c^4 - c12 \ . \end{array}$ 

and segment B1C1 is :

$$(dx^2+dy^2) \cdot [4.ab^2c^2]^2 = [4.a^4b^2c^2] \cdot [a^4+b^4+c^4-2.a^2c^2-2.a^2b^2+2.b^2c^2]$$
 and

 $(dx^2+dy^2) = [B1C1]^2 = [4.a^4b^2c^2] \cdot [b^2+c^2 - a^2]^2$  $[4.ab^2c^2]^2$ 

21 [12 2 2]

 $P_{0} = BICI + AICI + AIBI = \frac{[a^{2}b^{2} + a^{2}c^{2} - a^{4} + a^{2}b^{2} + b^{2}c^{2} - b^{4} + a^{2}c^{2} + b^{2}c^{2} - c^{4}]}{2.abc} = \frac{2.abc}{2.abc}$   $P_{0} = \frac{[2.a^{2}b^{2} + 2.a^{2}c^{2} + 2.b^{2}c^{2} - a^{4} - b^{4} - c^{4}]}{2.abc} = \frac{4.b^{2}c^{2} - [a^{2} - b^{2} - c^{2}]^{2}}{2.abc} = \frac{2.abc}{2.abc}$   $P_{0} = \frac{[2.bc + a^{2} - b^{2} - c^{2}] \cdot [2.bc - a^{2} + b + c^{2}]}{2.abc} = \frac{[a^{2} - (b - c)^{2}] \cdot [(b + c)^{2} - a^{2}]}{2.abc} \text{ or } \frac{2.abc}{2.abc}$   $P_{0} = \frac{[a + b - c] \cdot [a - b + c] \cdot [a + b + c] \cdot [b + c - a]}{2.abc} = \frac{[a + b + c] \cdot [-a + b + c] \cdot [a - b + c] \cdot [a + b + c] \cdot [b + c - a]}{2.abc} \dots (10)$ Remarks :

a) Perimeter Po becomes zero when . [-a+b+c] = 0, [a-b+c] = 0, [a+b-c] = 0 or when a = b+c, b = a+c, c = a+b and

This is the property of any point A on line BC where then Segment BC = a is equal to the parts AB = c and AC = b. The same for points B and C respectively. [6] Since perimeter is minimized by the orthic triangle then this triangle is the only one among all inscribed triangles in the triangle ABC. This property is very useful later on.

- **b**) Since Perimeter Po of the orthic triangle is minimized at the three lengths a, b, c then is also at the three vertices A, B, C of the original triangle ABC.
- c) The ratio  $(R_p)$  of the perimeter of the orthic triangle A1B1C1 to the triangle ABC is :

 $R_{p} = \frac{P_{0}}{P} = \frac{[a+b-c].[a-b+c].[b+c-a].[a+b+c]}{2.abc} = \frac{[-a+b+c].[a-b+c].[a+b-c]}{2.abc}$ 

For a = b = c then  $\rightarrow$  (Po/P) = (a.a.a)/2.a.a. = 1/2 which is holding. Let

The ratio  $R_p$  of the perimeters is depended only on the **n-1** sides of orthic triangles :

 $Rp = \frac{P_n}{P_{n-1}} = \frac{a_n + b_n + c_n}{a_{n-1} + b_{n-1} + c_{n-1}} = \frac{[-a_{n-1} + b_{n-1} + c_{n-1}] \cdot [a_{n-1} - b_{n-1} + c_{n-1}] \cdot [a_{n-1} + b_{n-1} - c_{n-1}]}{2 \cdot a_{n-1} \cdot b_{n-1} \cdot c_{n-1}}$ 

**d**) The ratio Ra of the area of triangle  $\Delta A_n B_n C_n$  to the  $\Delta A_{n-1} B_{n-1} C_{n-1}$  is :

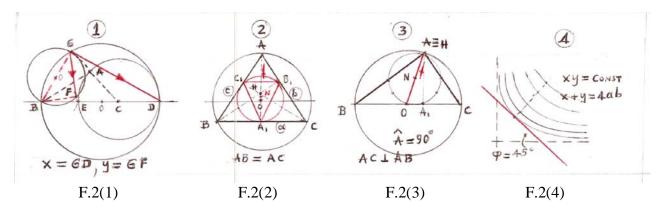
The ratio Ra of the areas is also depended only on the n-1 sides of orthic triangles :

e.a. It is well known that the nine point circle is the circumcircle of the orthic triangle and has circumradius RAIBIC1 which is one half of the radius  $R = R_{ABC}$  of the circumcircle of triangle  $\Delta ABC$ .

From F.4, using Pythagoras theorem on triangle with hypotenuse equal to the diameter of the circle, then we have the law of sines as :

AB AC BC AC BC AB ----= = -----= = 2. RABC and  $\rightarrow R = -----= = -----= = -----=$ and R is sinC sinB sinA 2.sinC 2.sinA 2.sinB BC a.c[2.b] = abca.c abc R = ----- = ----- = ----- = ----- = ----- = ----- = ----- $2.\sqrt{[(a+b)^2-c^2].[c^2-(a-b)^2]}$   $\sqrt{[(a+b)^2-c^2].[c^2-(a-b)^2]}$  and 2.sinA 2. BB1 abc 2.  $\sqrt{[(a+b)^2-c^2].[c^2-(a-b)^2]}$ 

For  $(a+b)^2 - c^2 = 0$  or  $c^2 - (a-b)^2 = 0$  then R AIBICI =  $\infty$ , and it is a + b = c and a - b = ca = b + c i.e. triangle ABC has the three vertices (the points) A, B, C on lines c and a respectively, a property of points on the two lines. [6]



**e.b.** The denominator of circum radius is of two variables  $x = [(a+b)^2-c^2]$  and  $y = [c^2-(a-b)^2]$  which have a fixed sum of lengths equal to **4.ab** and their product is to be made as large as possible. The product of the given variables,  $x = [(a+b)^2-c^2]$ ,  $y = [c^2-(a-b)^2]$  becomes maximum (this is proven) when x = y = 2.ab and exists on a family of hyperbolas curves where xy is constant for each of these curves . F.2(4)

All factors in denominator are conjugate and this is why orthogonal hyperbolas on any triangle are conjugate hyperbolas and follow Axial symmetry to their asymptotes.

The tangent on hyperbolas at point x = 2.ab formulates 45 ° angle to x, y plane system.

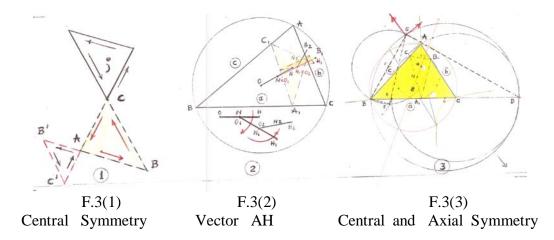
Since Complex numbers spring from Euclidean geometry [11] then the same result follows from complex numbers also . It is holding ,

**x.y** =  $\rho\rho$  [ cos ( $\phi+\phi$  ) + i.sin ( $\phi+\phi$  )] where  $\rho$ ,  $\rho$  are the modulus and  $\phi$ ,  $\phi$  the angles between the positive direction of the x- axis and x, y direction.

Product x.y becomes maximum when the derivative of the second part is zero as,

 $-\sin(\varphi+\varphi') + i \cdot \cos(\varphi+\varphi') = 0 \quad \rightarrow \quad \sin(\varphi+\varphi') = i \cdot \cos(\varphi+\varphi') \quad \text{or}$  $\sin(\varphi+\varphi')$  $-\cdots = \tan(\varphi+\varphi') = +i \text{ or } \rightarrow \quad \tan^{2}(\varphi+\varphi') = -1 \quad \text{i.e.}$  $\cos(\varphi+\varphi')$ 

the slope of the tangent line (which is equal to the derivative) at point x = y = 2.ab is -1 and this happens for  $(\phi + \phi') = 135^{\circ}$  or  $45^{\circ}$ .



e.c. Let's consider the length AH and the directions rotated through point A. F.1(1) The right angles triangles HAB<sub>1</sub>, BB<sub>1</sub>C are similar because all angles are equal respectively (angle AHB<sub>1</sub> = B<sub>1</sub>BC because BB<sub>1</sub> $\perp$ AB<sub>1</sub> and BC $\perp$ AH), so

 $\begin{array}{cccc} AH & AB_{1} & & BC \cdot AB_{1} & & a \cdot [c^{2} + b^{2} - a^{2}] & 2.b & & a \cdot [c^{2} + b^{2} - a^{2}] \\ BC & BB_{1} & & BB_{1} & & 2b \cdot \sqrt{[(a+b)^{2}-c^{2}] \cdot [c^{2}-(a-b)^{2}]} & & \sqrt{[(a+b)^{2}-c^{2}] \cdot [c^{2}-(a-b)^{2}]} \end{array}$ 

In any triangle ABC is holding ---- F.1(1)

 $\begin{array}{ll} a^{2} = b^{2} + c^{2} - 2.bc.\cos A & \rightarrow 2.bc.\cos A = b^{2} + c^{2} - a^{2} & \rightarrow & \cos A = \left[ \begin{array}{c} b^{2} + c^{2} - a^{2} \right] / 2.bc \\ b^{2} = c^{2} + a^{2} - 2.ac.\cos B & \rightarrow 2.ac.\cos B = c^{2} + a^{2} - b^{2} & \rightarrow & \cos B = \left[ \begin{array}{c} c^{2} + a^{2} - b^{2} \right] / 2.ca \\ c^{2} = a^{2} + b^{2} - 2.ab.\cos C & \rightarrow 2.ab.\cos C = a^{2} + b^{2} - c^{2} & \rightarrow & \cos C = \left[ \begin{array}{c} a^{2} + b^{2} - c^{2} \right] / 2.ab \end{array} \right]$ 

$$\mathbf{AH} = \frac{a.[c^{2}+b^{2}-a^{2}].[\sqrt{[(a+b)^{2}-c^{2}].[c^{2}-(a-b)^{2}]}}{[(a+b)^{2}-c^{2}].[c^{2}-(a-b)^{2}]} = \frac{a.[c^{2}+b^{2}-a^{2}].\sqrt{[x,y]}}{x.y} = \frac{2.abc.\sqrt{x}.y}{(cos A)}$$

$$\frac{x.y}{where} = \frac{x.y}{x=(a+b)^{2}-c^{2}}, \quad y=c^{2}-(a-b)^{2}$$

 $AH = \begin{vmatrix} 2.abc.\sqrt{x}.y & | & 2.abc \\ |-----|.\cos A & = & |-----|.\cos A & = & Vector AH & .....(13) \\ x.y & \sqrt{x}.y & \sqrt{x}.y \end{vmatrix}$ 

From F2(1) BC = a , AC = b , AB = c , CD = CE = CA = b , BD = BC+CD = a + b , BA = BG = c , BE = BF = BC - EC = a - b .

With point O as center draw circle with BD = a+b as diameter and with point B as center draw circle (B, BA = BG) intersecting circle (O, OB) at point G. Using Pythagoras theorem in triangles BDG, BFG then  $GD^2 = BD^2 - BG^2 = [(a+b)^2 - c^2] = \mathbf{x}$ and  $GF^2 = GB^2 - BF^2 = c^2 - BE^2 = c^2 - (a-b)^2 = \mathbf{y}$  and it is holding  $x+y = a^2+b^2+2.a \ b - c^2+c^2-a^2-b^2+2.a \ b = 4.a.b = GD + GF = constant$  $x \cdot y = [(a+b)^2 - c^2] \cdot [c^2 - (a-b)^2] = GD \cdot GF = constant$ 

# Since Ortocenter H changes Position, following orthic triangles $A_1B_1C_1$ , then Sector AHn is altering magnitude and direction, so AHn is a mathematical vector.

**f.** In F.2(1) GD  $\perp$  GB , GF  $\perp$  BF , therefore angle DGF = GBF so the sum of the pairs of two vectors [GD,GE], [BG, BE] is constant. Since addition of the two bounded magnitudes follows parallelogram rule , then their sum is the diagonal of the parallelogram . In F2(2-4) the product of the pairs of the two vectors [GD,GE], [BG, BE] is constant in the direction perpendicular to diameter DE, so rectangular hyperbolas on the x, y system are 45 ° at the point x = y = 2.ab.

g. In F.3(2) orthic triangle A<sub>1</sub>B<sub>1</sub>C<sub>1</sub> of triangle ABC is circumscribed in Nine-point circle with center point N, *the middle of OH*, while point O is ABC's circumcenter.
Since point N is the center of A<sub>1</sub>B<sub>1</sub>C<sub>1</sub>'s circumcenter, therefore Euler line OH is rotated through the middle point N of OH to all nested orthic triangles A<sub>n</sub>B<sub>n</sub>C<sub>n</sub> as is shown in F.3(2), or are as

Sector (ONH), (N = O<sub>1</sub> N<sub>1</sub> H<sub>1</sub>), (N<sub>1</sub> = O<sub>2</sub> N<sub>2</sub> H<sub>2</sub>)  $\rightarrow$  (N<sub>n-1</sub> = O<sub>n</sub> N n H<sub>n</sub>)  $\rightarrow$  (N<sub>∞</sub> = O<sub>∞</sub> N<sub>∞</sub> H<sub>∞</sub>)

From vertices A,B,C and orthocenter H of triangle ABC passes rectangular circum-hyperbolas with point N as the center of the Nine-point circle. In Kiepert hyperbola, its center is the midpoint of Fermat points. In Jerabek rectangular hyperbola, its center is the intersection of Euler lines of the three triangles, of the four in triangle ABC. (the fourth is the orthic triangle).

**h.** In F.2(1) GD  $\perp$  GB and GF  $\perp$  BF therefore angle DGF = GBF or DGF + GBF = 360° [6] ie. angles DGF, GBF are conjugate. It is known that in an equilateral hyperbola, conjugate diameters make equal angles with the asymptotes, and because angle DGF = GBF then the sum of the two pairs of the two vectors (GD,GE), (BG,BE) is constant for all AH of orthic triangles.

To be vector  $\mathbf{AH}$  a relative extreme (minimum or zero), numerator of equation (13) must be zero in a fix direction to triangle ABC. Since a, b, c are constants, vector AH is getting extreme to the opposite direction by Central Symmetry through point A.

Verification :

C1. For a = b = c then  $\cos A = [2 a^2 - a^2] / 2.a^2 = a^2 / 2a^2 = 1/2$  therefore  $\rightarrow A = 60^{\circ}$   $x = (a+b)^2 - c^2 = 4a^2 - a^2 = 3.a^2$ ,  $y = c^2 - (a-b)^2 = a^2$  x + y = 4.  $a^2$  and  $x.y = 3.a^4$   $AH = [2.a^3. a^2 \sqrt{3}] / [3.a^4.2] = a \sqrt{3} / 3 = [a \sqrt{3}/2] \cdot (2/3) \rightarrow a | / = a \sqrt{2} \setminus a = a \sqrt{3}$  i.e. *Orthocenter Hn limits to*  $\rightarrow$  *circumcenter*  $O \rightarrow (2/3)$ . AA1

**C2.** For b = c then  $\cos A = [2b^2 - a^2]/2$ .  $b^2 = [b.\sqrt{2} + a] [b\sqrt{2} - a]/2$ .  $b^2$  ..... (13.a)

1. For  $\cos A = 0$  then  $b\sqrt{2} - a = 0$  and this for  $A = 90^{\circ}$  and AH = 0 i.e. *Orthocenter Hn limits to Vertice*  $A \rightarrow AHn \rightarrow A$ 

Since also cos A becomes zero with  $b\sqrt{2} = -a$  (The Central symmetry to a) then Orthocenter Hn limits always to  $\rightarrow$  Vertice A or AHn  $\rightarrow$  A

- 2. For  $\cos A = 1/2$  then  $A = 60^{\circ}$ ,  $x = 2.ab + a^2$ ,  $y = 2.ab b^2$  and b = a  $AH = [2.ab^2.\sqrt{x.y}].(1/2) / xy = [a.b^2 / \sqrt{x.y}] = (ab^2) / a\sqrt{3} = a/\sqrt{3} = a\sqrt{3}/3 = AO$  i.e. Orthocenter Hn limits to circumcenter O of triangle ABC or AHn  $\rightarrow O$ .
- 3. For  $\cos A = \sqrt{2}/2$  then  $A = 45^{\circ}$ ,  $x = 2.ab + a^2$ ,  $y = 2.ab b^2$  and  $4.la^2 = 4.b^2 a^2$ AH =  $[2.ab^2\sqrt{x}.y].(\sqrt{2}/2)/xy = [2.ab^2\sqrt{2}/\sqrt{x}.y] = [2.ab^2.\sqrt{2}]/\sqrt{(4.la^2)} = \frac{b^2}{(la.\sqrt{2})}$  i.e.

Orthocenter Hn limits to An on altitude la, or  $AHn \rightarrow b^2/(la.\sqrt{2})$ , and for  $\cos A = la^2/b^2$ AHn = la i.e Orthocenter Hn limits to A1, or AHn = la = AA1 = Altitude AA1.

4. For 
$$\cos A = 1$$
 then  $A = 0^{\circ}$ ,  $x = a^2 + b^2 + 2.ab - b^2 = a. (a+2.b)$   
 $y = b^2 - a^2 + 2.ab - b^2 = a. (2.b - a)$  and

AH =  $[2.ab^2] / [a.\sqrt{4.b^2 - a^2}] = [2.b^2] / [\sqrt{4.b^2 - a^2}]$  and for A = 0° then AH =  $[2.b^2] / 2.b = b$  i.e. Orthocenter Hn limits to vertices B or C (the two vertices coincide). or Orthocenter Hn limits to B, C or AHn  $\rightarrow$  B = C

5. For  $\cos A = -1$  then  $A = 180^{\circ}$ , x = a. (a+2.b) = a. (2.b-a) and a = 2.b

AH =  $[2.b^2](-1) / [\sqrt{4.b^2 - (2.b)^2}] = [-2.b^2] / [\infty] = 0$  i.e point A coincides with the foot A1 or AA1 = 0, Orthocenter Hn limits to B, C or AHn  $\rightarrow$  B = C

**C3.** The first Numerator term of equation (13) and in F.2(3) is  $, c^2 + b^2 - a^2 ,$  and this *in order* to be on a right angle triangle ABC with angle  $< A = 90^{\circ}$ , must be zero, or  $a^2 = b^2 + c^2$ . The second term is  $x = (a+b)^2 - c^2 \neq 0$ ,  $a^2+b^2+2.ab - c^2 = b^2+c^2+b^2+2.ab - c^2 = 2$ .  $[ab+b^2] \neq 0$  or  $a+b \neq 0 = \text{constant} \rightarrow (b/a) < 0$  i.e.  $H \rightarrow A$ , and for  $y = c^2 - (a-b)^2 \neq 0$ ,  $c^2 - a^2 - b^2 + 2.ab = c^2 - b^2 - c^2 - b^2 + 2.ab = 2$ .  $[ab-b^2] \neq 0$  or  $a-b \neq 0 = \text{constant}$ , and (b/a) > 0 i.e.  $H \rightarrow A$ .

Geometrically, since  $B_1C_1$  of orthic triangle  $A_1B_1C_1$  coincides with point A, so the center N of the nine-point circle on ABC is always on OA. Since point N is  $A_1B_1C_1$ 's circum-center and represents the new O<sub>1</sub> then the new N<sub>1</sub> of  $A_1B_1C_1$ 's is the center point on NA or NH<sub>1</sub> = NA / 2 Therefore point N is on OA direction at (AO/2), (AO/4), (AO/8), ..., (AO/2<sup>a</sup>) points , i.e.

In any right-angle triangle ABC where angle  $\langle A = 90^{\circ}$ , the locus of the orthocenter points  $H_1 \dots H_n$  of the orthic triangles  $A_n B_n C_n$ , is on line OA, and for  $n = \infty$  then convergent to point A (vertice A) of the triangle ABC.

so, In an equilateral triangle ABC where a = b = c, Orthocenter H is fixed at Centroid K which coincides with Circum center O, and the Nine-point center N. In an Isosceles triangle ABC where a, b = c, Orthocenter H moves on altitude AA1 (this is the locus of the orthocenter points  $H_1 \dots H_n$ ) and for angle  $A = 90^\circ$  then convergent to the point A of the triangle.

Remark : In any triangle ABC rectangular hyperbolas follow Axial symmetry to their Asymptotes , in contradiction to orthocenter H , which follows Central Symmetry and Rotation through point A , the vertice opposite to the greatest side of the triangle . This Springs out of the logic of Spaces , Anti-Spaces , Sub-Spaces of any first dimentional Unit ds > 0. [11], therefore vector AHn is limiting to the Orthocenters H<sub>1</sub>....H<sub>n</sub> of orthic triangles in triangle ABC. (Equation 13). Conics through the vertices of triangle ABC that are not passing through Orthocenter H are not rectangular hyperbolas. A further geometrical analysis follows.

# **Extremum Principle or Extrema :**

All Principles are holding on any Point A.

For two points A, B not coinciding, exists Principle of Inequality which consists another quality. Any two Points exist in their Position under one Principle, *Equality and Stability in Virtual displacement which presupposes Work in a Restrain System*). [11]

This Equilibrium presupposes homogenous Space and Symmetrical Anti-Space.

For two points A, B which coincide, exists *Principle of Superposition* which is a Steady State containing Extrema for each point separately.

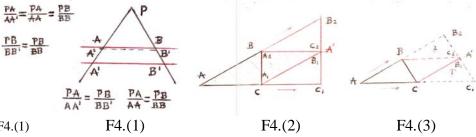
*Extrema*, for a *point* A is the Point, for a *straight line* the infinite points on line, either these coincide or not or these are in infinite, and for *a Plane* the infinite lines and points with all combinations and Symmetrical ones, *i.e. all Properties of Euclidean geometry*, *compactly exist in Extrema Points*, *Lines*, *Planes*, *circles*.

Since Extrema is holding on Points, lines, Surfaces etc, therefore all their compact Properties (Principles of Equality, Arithmetic and Scalar, Geometric and Vectors, Proportionality, Qualitative, Quantities, Inequality, Perspectivity etc), exist in a common context. Since a quantity is either a vector or a scalar and by their distinct definitions are,

**Scalars**, are quantities that are fully described by a magnitude (or numerical value) alone, **Vectors**, are quantities that are fully described by both magnitude and a direction, therefore

In Superposition magnitude AB is equal to zero and direction , any direction ,  $\neq 0$  i.e.

Any Segment AB between two points A, B consist a Vector described by the magnitude AB and directions  $\tilde{A}B$ ,  $B\tilde{A}$  and in case of Superposition  $\tilde{A}A$ ,  $A\tilde{A}$ . i.e. Properties of Vectors, Proportionality, Symmetry, etc exists either on edges A, B or on segment AB as follows :



**A**. Thales Theorem . F4.(1)

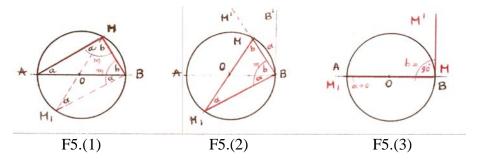
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According to Thales F4.(1), if two intersecting lines PA, PB are intercepted by a pair of Parallels AB // A'B', then ratios PA/AA', PB/BB', PA/PA', PB/PB' of lines, or ratios in similar triangles PAB, PA'B' are equal or  $\lambda = [PA / AA'] = [PB / BB']$ . In case line A'B' coincides with AB, then AA' = AA, BB' = BB, i.e. exist **Extrema** and then  $\lambda = [PA / AA] = [PB / BB]$ , (Principle of Superposition).

**B.** Rational Figured Numbers of Figures F4.(2-3).

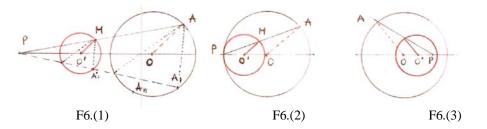
The definition of "Heron" that gnomon is as that which, when added to anything , a number or figure, makes the whole similar to that to which it is added. (Proportional Principle). It has been proven that the triangle with sides twice the length of the initial , preserves the same angles of the triangle. [6] i.e. exists **Extrema** for Segment BC at  $B_1C_1$ .

C. A given Point M and any circle with AB as diameter . [6].



It has been proved [6] that angle  $AMB = 90^{\circ}$  for all points of the circle. This when point M is on B where then exists **Extrema** at point B for angle AMB . (Segments MA, MB) i.e. Angle  $AMB = AMO + OMB = AMM_1 + M_1MB = ABA + ABB = 0 + 90^{\circ} = 90^{\circ} \dots F5.(3)$ 

**D.** A given Point **P** and any circle (O, OA). [6]



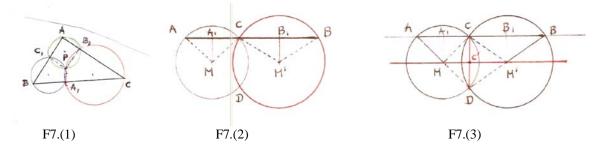
It has been proved that the locus of midpoints M of any Segments PA, is a circle with center O' at the middle of PO and radius O' M = OA / 2. (F6)

Extending the above for point M to be any point on PA such that PM / PA = a constant ratio equal to  $\lambda$ , then the locus of point M is a circle with center O' on line PO,  $PO' = \lambda .PO$ , and radius O'  $M = \lambda . OA$ . Extrema exists for points on the circle.

Remarks :

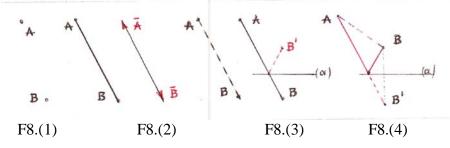
1. In case  $PO' = \lambda$ . PO and  $O'M = \lambda$ . PO and this is holding for every point on circle, so also for 2, 3,... n points i.e. any Segment AA1, triangle AA1A2, Polygon AA1...An,... circle, is represented as a Similar Figure (*Segment*, *triangle*, *Polygon* or *circle*).

2. In case  $PO' = \lambda . PO$  and  $PM_1 = PA . \lambda_1$ , then for every point A on the circle (O, OA), in or out the circle, exist a point M1 such that line AM1 passes through point P. i.e. every segment AA1 Triangle AAA2, Polygon AA1.....An, or circle, is represented as segment MM1M2, Polygon MM1..... Mn or a closed circle [Perspective or Homological shape ]. F6.(1)



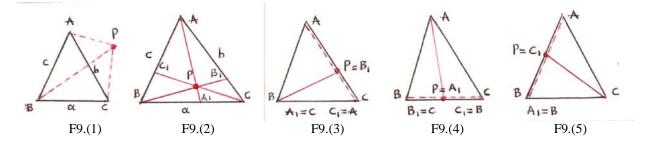
Any point M, not coinciding with points A, B consists a Plane (the Plane MAB) and from point M passes only one Parallel to AB. This parallel and the symmetrical to AB is the **Extrema** because all altitudes are equal and of minimum distance. When point M lies on line AB then parallel is on AB and all properties of point P are carried on AB and all of M on line AB. F7.(2-3)

F. Symmetry (Central, Axial) is Extrema F.8



Since any two points A,B consist the first dimentional Unit (magnitude AB and direction  $\tilde{A}B$ ,  $B\tilde{A}$ ) F8.(1-2) equilibrium at the middle point of A, B, *Central Symmetry*. Since the middle point belongs to a Plane with infinite lines passing through and in case of altering central to axial symmetry, then equilibrium also at *axial Symmetry* F8.(3), so Symmetrical Points are in **Extrema**. *Nature* follows this property of points of Euclidean geometry (*common context*) as Fermat's Principle for Reflection and Refraction . F8.(4).

G. A point P and a triangle ABC. (F9)



If a point P is in Plane ABC and lines AP, BP, CP intersect sides BC, AC, AB, of the triangle ABC at points A1,B1,C1 respectively F9. (1–2), then the product of ratios  $\lambda$  is,  $\lambda = (AB1/B1C) \cdot (CA1/A1B) \cdot (BC1/C1A) = 1$ , and the opposite. Proof :

Since Extrema of Vectors exist on edge Points A, B, C, and lines AC, BC, AB then for,

a. Point P on line AC , F9.(3)  $\rightarrow$  A1 = C , B1 = P , C1 = A and for  $\lambda = (AB1 / B1C).(CA1 / A1B).(BC1 / C1A) \rightarrow \lambda 1 = (PA / PC).(CC / BC).(AB / AA)$ 

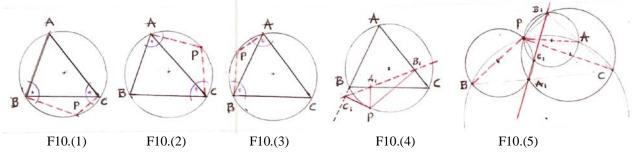
b. Point P on line BC , F9.(4)  $\rightarrow$  A1 = P , B1 = C , C1 = B and for  $\lambda = (AB1 / B1C).(CA1 / A1B).(BC1 / C1A) \rightarrow \lambda_2 = (AC / CC).(PC / PB).(BB / AB)$ 

c. Point P on line BA, F9.(5)  $\rightarrow A1 = B$ , B1 = A, C1 = P and for  $\lambda = (AB1 / B1C).(CA1 / A1B).(BC1 / C1A) \rightarrow \lambda_3 = (AA / AC).(BC / BB).(PB / PA)$  and for

 $\lambda_1 \cdot \lambda_2 \cdot \lambda_3 = [PA.CC.AB.AC.PC.BB.AA.BC.PB] : [PC.BC.AA \cdot CC.PB.AB \cdot AC.BB.PA] = 1$ 

i.e. Menelaus *Theorem*, and for Obtuse triangle  $\lambda_1 \cdot \lambda_2 \cdot \lambda_3 = -1 \rightarrow$  Ceva's Theorem

H. A point P a triangle ABC and the circumcircle.



**a.** Let be A1,B1,C1 the feet of the perpendiculars (altitudes are the Extrema) from any point P to the side lines BC, AC, AB of the triangle ABC, F10.(4) Since Properties of Vectors exist on lines AA1, BB1,CC1 then for **Extrema Points**,

 $F10.(1) \rightarrow Point A1$  on points B, C of line BC respectively, formulates perpendicular lines BP, CP which are intersected at point P. Since Sum of opposite angles PBA+PCA = 180° therefore the quadrilateral PBAC is cyclic on circumcircle of triangle ABC and also the feet of the perpendiculars of point P on sides of triangle ABC are points B, C.

 $F10.(2) \rightarrow Point B1$  on points A, C of line AC respectively, formulates perpendicular lines AP, CP which are intersected at point P. Since Sum of opposite angles PAB+PCB = 180° therefore the quadrilateral PABC is cyclic on circumcircle of triangle ABC and also the feet of the perpendiculars of point P on sides of triangle ABC are points A, C.

 $F10.(3) \rightarrow Point C1$  on points A, B of line AB respectively, formulates perpendicular lines AP, BP which are intersected at point P. Since Sum of opposite angles PAC+PBC =  $180^{\circ}$  therefore the quadrilateral PACB is cyclic on circumcircle of triangle ABC and also the feet of the perpendiculars of point P on sides of triangle ABC are points A, B.

So **Extrema** for the three sides of the triangle is point P which is on the circumcircle of the triangle and the feet A1,B1,C1 of the perpendiculars of point P on sides of triangle ABC are respectively on sides BC, CA, AB i.e. on a line. [F10.4] *Simsons line.* Since altitudes PA1, PB1, PC1 are also perpendiculars on the sides BC,AC,AB and segments PA,PB,PC are diameters of the circles,then points A1,B1,C1 are collinear.[F10.5]. *Saimon Theorem* 

**b.** Let be A1,B1,C1 any three points on sides of a triangle ABC (these points are considered **Extrema** because they maybe on vertices A, B, C or to  $\infty$ ). F7.(1). If point P is the common point of the two circumcircles of triangles AB1C1, BC1A1, (a vertex and two adjacent sides) then circumcircle of the third triangle CA1B1 passes through the same point P. Proof :

Since points A, B1, P, C1 are cyclic then the sum of opposite angles  $BAC + B1PC1 = 180^{\circ}$ . Since points B, C1, P, A1 are cyclic then the sum of opposite angles  $ABC + C1PA1 = 180^{\circ}$ . and by Summation  $BAC + ABC + (B1PC1 + C1PA1) = 360^{\circ}$  .....(1) Since  $BAC + ABC + ACB = 180^{\circ}$  then  $BAC + ABC = 180^{\circ} - ACB$  and by substitution to (1)  $(180^{\circ} - ACB) + 360 - A1PB1 = 360^{\circ}$  or , the sum of angles  $ACB + A1PB1 = 180^{\circ}$ , therefore points C, B1, P, C1 are cyclic i.e. Any three points  $A_1, B_1, C_1$  on sides of triangle ABC, forming three circles determined by a Vertex and the two Adjacent sides, meet at a point P. (Miguel's Theorem)

- **c.** In case angle PA1B = 90° then also PA1C = 90°. Since angle PA1C + PB1C = 180° then also PB1C = 90° (*angles PA1B*, *PC1B*, *PB1C* are extreme of point P).
- **d.** ABC is any triangle and A1,B1,C1 any three points on sides opposite to vertices A,B,C Show that Perimeter C1B1+B1A1+A1C1 is minimized at Orthic triangle A1B1C1 of ABC.

Since point P gets Extrema on circumcircle of triangle ABC, so sides A1B1,B1C1,C1A1 are **Extrema** at circumcircle determined by a vertex and the two adjacent sides .Since adjacent sides are determined by sides AA1, BB1, CC1 then maximum exists on these sides . Proof :

In triangle AA1B, AA1C the sum of sides p1 p1 = (AA1+A1B+AB) + (AA1+AC+A1C) = 2.(AA1) + AB+AC+BC = 2.(AA1) + a+b+c

In triangle BB1A, BB1C the sum of sides p2 p2 = (BB1+B1A+AB) + (BB1+BC+B1C) = 2.(BB1) + AB+AC+BC = 2.(BB1) + a+b+c

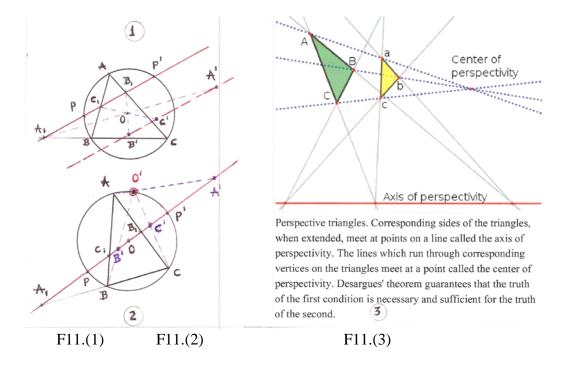
In triangle CC1A, CC1B the sum of sides p3 p3 = (CC1+C1A+AB) + (CC1+AC+C1C) = 2.(CC1) + AB+AC+BC = 2.(CC1) + a+b+c

The sum of sides  $\mathbf{p} = p1 + p2 + p3 = 2$ . [AA1+BB1+CC1] + 3.[a+b+c] and since a+b+c is constant then  $\mathbf{p}$  becomes minimum when AA1+BB1+CC1 or when these are the altitudes of the triangle ABC, where then are the vertices of orthic triangle . *i.e.* 

# The Perimeter C1B1 + B1A1 + A1C1 of orthic triangle A1B1C1 is the minimum of all triangles in ABC.

I. Perspectivity :

In Projective geometry, (*Desargues' theorem*), two triangles are in perspective *axially*, if and only if they are in perspective *centrally*. Show that, Projective geometry is an **Extrema** in Euclidean geometry.



F7(1)

Two points P, P' on circumcircle of triangle ABC, form **Extrema** on line PP'. Symmetrical axis for the two points is the mid-perpendicular of PP' which passes through the centre O of the circle, *therefore*, Properties of axis PP' are transferred on the Symmetrical axis in rapport with the center O (central symmetry), *i.e.* the *three points of intersection* A1, B1, C1 are Symmetrically placed as A', B', C' on this Parallel axis. F11.(1)

a. In case points P, P' are on **any diameter** of the circumcircle F11.(2), then line PP' coincides with the parallel axis, the points A', B', C' are Symmetric in rapport with center O, and the Perspective lines AA', BB', CC' are concurrent in a point O' situated on the circle. When a pair of lines of the two triangles (ABC, abc) are parallel F11.(3), where the point of intersection recedes to infinity, axis PP' passes through the circumcenters of the two triangles, (Maxima) and is not needed " to complete " the Euclidean plane to a projective plane \_\_i.e.

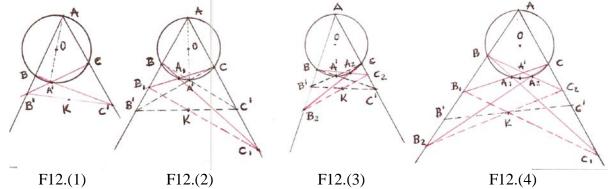
Perspective lines of two Symmetric triangles in a circle, on the diameters and through the vertices of corresponding triangles, are concurrent in a point on the circle.

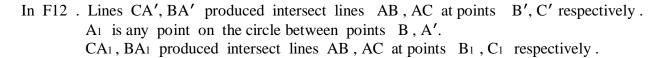
b. When all pairs of lines of two triangles are parallel, equal triangles, then points of intersection recede to infinity, and axis PP` passes through the circumcenters of the two triangles (Extrema).

c. When second triangle is a point P then axis PP' passes through the circumcenter of triangle.

Now is shown that *Perspectivity* exists between a triangle ABC, a line PP' and any point P where then exists Extrema, i.e. *Perspectivity in a Plane is transferred on line and from line to Point This is a compact logic in Euclidean geometry which holds in Extrema Points*.

J. A point A1 and triangle ABC in a circle of diameter AA'.





Show that lines B1C1 are concurrent at the circumcenter K of triangles CC'B', BB'C'.

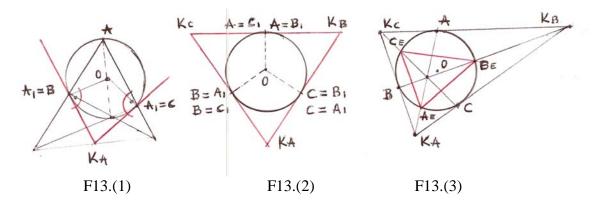
#### Proof :

Angle C'CA'= C' CB' = 90° therefore circumcenter of triangle CC'B' is point K, the middle point of B'C' Angle B'BA'= B'BC' = 90° therefore circumcenter of triangle BB'C' is point K, the middle point of B'C' Considering angle < C'CA'= 90° as constant then all circles passing through points C, A', C' have their center on KC.

Considering angle B'BA'=  $90^{\circ}$  as constant then all circles passing through points B, A', B' have their center on KB.

Considering both angles  $< C'CA' = B'BA' = 90^{\circ}$  then lines BA', CA' produced meet lines AB', AC' at points B', C' such that line B'C' passes through point K (*common to KC*, KB) Extrema for points A<sub>1</sub>, A<sub>2</sub> are points C, B and in case of points B, C coincide with point A *i.e. line KA is Extrema line for lines BA*, CA.

On the contrary, In any angle < BAC of triangle ABC exists a constant point KA such that all lines passing through this point intersect sides AB, AC at points C<sub>1</sub>, B<sub>1</sub> so that internal lines CB<sub>1</sub>, BC<sub>1</sub> concurrence on the circumcircle of triangle ABC and in case this point is A, then concurrence on line AK<sub>A</sub>. F12.(4), F13.



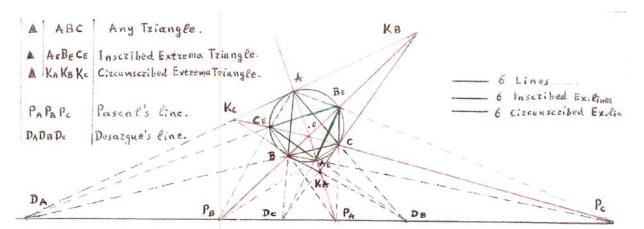
**a**) When point A<sub>1</sub> is on point B (Superposition of points A<sub>1</sub>, B) then line BA<sub>1</sub> is the tangent at point B, where then angle  $< OBK_A = 90^\circ$ . When point A<sub>1</sub> is on point C (Superposition of points A<sub>1</sub>, C) then line CA<sub>1</sub> is the tangent at point C, where then angle  $< OCK_A = 90^\circ$ . F13.(1) Following the above for the three angles BAC, ABC, ACB F13.(2) then,

KAB, KAC are tangents at points B and C and angle  $< OBK_A = OCK_A = 90^{\circ}$ . KBC, KBA are tangents at points C and A and angle  $< OCK_B = OAK_B = 90^{\circ}$ . KCA, KCB are tangents at points A and B and angle  $< OAK_C = OBK_C = 90^{\circ}$ .

Since at points A, B, C of the circumcircle exists only one tangent then, The sum of angles  $OCK_A + OCK_B = 180^\circ$  therefore points KA, C, KB are on line KAKB. The sum of angles  $OAK_B + OAK_C = 180^\circ$  therefore points KB, A, KC are on line KBKC. The sum of angles  $OBK_C + OBK_A = 180^\circ$  therefore points KC, B, KA are on line KAKC. i.e.

#### Circle (O, OA = OB = OC) is inscribed in triangle KAKBKc and circumscribed on triangle ABC.

b) Theorem : On any triangle ABC and the circumcircle exists one inscribed triangle AEBECE and another one circumscribed Extrema triangle KAKBKC such that the Six points of intersection of the six pairs of triple lines are collinear  $\rightarrow$  (3+3). 3 = 18



F.14. The Six, Triple Points, Line  $\rightarrow$  The Six, Triple Concurrency Points, Line Proof:

F13. (1 - 2 - 3), F14

Let AE, BE, CE are the points of intersection of circumcircle and lines AKA, BKB, CKc respectively. Since circle (O,OA) is incircle of triangle KAKBKc therefore lines AKA, BKB, CKc concurrence.

- 1. When points A1, A coincide, then internal lines CB1, BC1 coincide with sides CA, BA, so line KAA is constant. Since point AE is on *Extrema line AKA* then lines CEB, BEC concurrent on line AKA. The same for tangent lines KAKB, KAKC of angle < KBKAKC.
- 2. When points A1, B coincide, then internal lines CA1, AC1 coincide with sides CB, AB, so line K<sub>B</sub>B is constant. Since point BE is on *Extrema line BK*<sub>A</sub> then lines AEC, CEA concurrent on line BK<sub>B</sub>. The same for tangent lines K<sub>B</sub>K<sub>C</sub>, K<sub>B</sub>K<sub>A</sub> of angle < K<sub>C</sub>K<sub>B</sub>K<sub>A</sub>.
- 3. When points A1, C coincide, then internal lines AB1, BA1 coincide with sides AC, BC, so line KcC is constant. Since point CE is on *Extrema line CKc* then lines BEA, AEB concurrent on line CKc. The same for tangent lines KcKA, KcKB of angle < KAKcKB, *i.e.*

Since Perspective lines, on Extrema triangles AEBECE, KAKBKC concurrent, and since also Vertices A, B, C of triangle ABC lie on sides of triangle KAKBKC, therefore all corresponding lines of the three triangles when extended concurrent, and so the three triangles ABC, AEBECE, KAKBKC are Perspective between them.

In triangles ABC, AEBECE all corresponding Perspective lines concurrent on AKA, BKB, CKc lines, and concurrency points  $P_A$ , PB, Pc collinear. The pairs of Perspective lines [AAE, CBE, BCE], [BBE, CAE, ACE], [CCE, ABE, ABE] concurrent in points  $P_A$ , PB, Pc respectively and lie on a line.

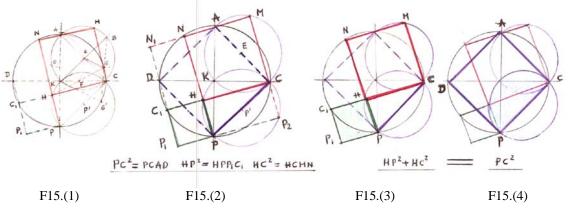
In triangles ABC, KAKBKC vertices A, B, C lie on triangle's KAKBKC sides, therefore all corresponding Perspective lines concurrent in points DA, DB, DC respectively (sides of triangle KAKBKC are tangents on circumcircle). The pairs of Perspective lines [KBA, CB, CEBE], [KAB, AC, AECE], [KBC, BA, BEAE], concurrent in points DA, DB, DC respectively.

In triangles AEBECE, KAKBKC, and ABC corresponding Perspective lines concurrent in the same points DA, DB, DC because triangles` KAKBKC sides are tangent on circumcircle, so **Extrema** lines KBKC, KCKA, KAKB for both sets of sides lines [BC, BECE, KBKC], [AC, AECE, KAKC] [AB, AEBE, KAKB] concurrent in points of the same line.

This compact logic of the points [A, B, C], [AE, BE, CE], [KA, KB, KC] when is applied on the three lines KAKB, KAKC, KBKC, THEN THE SIX pairs of the corresponding lines which extended are concurrent at points PA, PB, PC for the triple pairs of lines [AAE, BCE, CBE] [BBE, CAE, ACE], [CCE, ABE, BAE] and at points DA, DB, DC for the other Triple pairs of lines [CB, KBA, BECE], [AC, KAB, CEAE], [BA, KBC, AEBE], lie on a straight line.

Remarks :

- 1. Since Inscribed Extrema Triangle [AE,BE,CE] defines, axis AAE,BBE,CCE of Projective geometry and Circumscribed Extrema Triangle [KA,KB,KC], axis KBKC, KAKC, KAKB of Perspective geometry therefore, Projective and Perspective geometry are Extrema in Euclidean geometry i.e. an Extension of the two fundamental branches of geometry.
- c). Pythagoras's Theorem and the Mould (*Machine*) of changeable Squares . 25/2/2012



It has been proved [5], F15.(1) that any two equal and Perpendicular first dimentional Units CA, CP and the hypotenuse AP, formulate the two equal circles with diameters CA, CP and the circumscribed circle (K,KA) of triangle CAP, ( $Machine CA \perp CP = CA$ ), which forms on the three circles, { for any point **H** on circle (P',P'C) }, the rectangle HNMC which is Square, (HNMC = HC<sup>2</sup>) and the Square HPP1C1 = HP<sup>2</sup>.

Show that :  $PC^2 = HP^2 + HC^2$  or  $\rightarrow$  Rectangle CADP = HCMN + HPP1C1

## Proof :

Complete Rectangles PNMP<sub>2</sub>, PHCP<sub>2</sub> on the circle (P', P' P) and HNN<sub>1</sub>C<sub>1</sub>, PNN<sub>1</sub>P<sub>1</sub> on the circle (K, KC = KD) and the squares HPP<sub>1</sub>C<sub>1</sub>, HNMC in the three circles . F15.(2) Rightangled triangles CMA, CP<sub>2</sub>P, DP<sub>1</sub>P, DN<sub>1</sub>A, are equal between them because these have equal their two sides, (CA = CP = DP = DA *and* CM = PP<sub>2</sub> = DP<sub>1</sub> = AN<sub>1</sub>), therefore other sides  $AM = CP_2 = PP_1 = DN_1$ , and areas of triangles CAM, CPP<sub>2</sub>, DPP<sub>1</sub>, DAN<sub>1</sub> are also equal.

- 1. Since HC = HN then Rectangles  $HCP_2P$ ,  $HNN_1C_1$  are equal, and both equal to 2. CHP.
- 2. In square MP<sub>2</sub>P<sub>1</sub>N<sub>1</sub>  $\rightarrow$  Square CADP = Square MP<sub>2</sub>P<sub>1</sub>N<sub>1</sub> 4. Triangles CHP.
- 3. In square MP<sub>2</sub>P<sub>1</sub>N<sub>1</sub>  $\rightarrow$  Square HCMN + Square HPP<sub>1</sub>C<sub>1</sub> = Square MP<sub>2</sub>P<sub>1</sub>N<sub>1</sub> [2. Rectangles PHCP<sub>2</sub> = 4. Triangles CHP] = Square MP<sub>2</sub>P<sub>1</sub>N<sub>1</sub> – 4. Triangles CHP ... i.e.

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Square CADP = Square HCMN + Square HPP<sub>1</sub>C<sub>1</sub> or \rightarrow PC<sup>2</sup> = HC<sup>2</sup> + HP<sup>2</sup>
which is Pythagoras's theorem.
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Remarks :

- **a.** In machine  $CA \perp CP$ , CA = CP of the two equal circles (E, EA), (P', P'C) and the circumcircle (K, KA) of the triangle ACP, are drawn two Changeable Squares HNMC, HPP1C1, which Sum is equal to the inscribed one CADP, or  $PC^2 = HC^2 + HP^2$ .
- **b.Extrema** exists at edge points **P**, **C** where then point **H** coincides with points P and C, and  $PC^2 = PP^2 + PC^2 = PC^2$  and  $PC^2 = PC^2 + CC^2 = PC^2$ , and when coincides with K, then the Sum of the two Changeable Squares HNMC, HPP1C1 is  $KC^2+KP^2 = 2.\Delta$  (KCA)+2. $\Delta$  (KCP) = 2. $\Delta$ (KCA+KCP) = CADP = PC<sup>2</sup>.
- **c**. The Position of the three Points only, defines Quantities (sides CP, HP, HC), and Qualities (triangle PCH, Squares PDAC, HPP1C1, HCMN and any classification of numbers is included).

**d**. It has been proved [5] that the two equal and perpendicular Units CA, CP, (in plane ACP) construct the Isosceles rightangled triangle ACP and the three circles on the sides as diameters. From any point **H** on the first circle are conscructed Squares HNMC, HPP1C1 with vertices on the three circles. This Plane Geometrical Formation is a , **mooving Machine**, and is called < **Plane Formation of Constructing Squares** >. *The same analogues exist in Space and is called*, < **Space Formation of Constructing Cubes**, and for Cubes  $HO^3 = HP^3 + HC^3 + HJ^3$ .

The Plane System of triangle ACP with the three circles on the sides as diameters consists *the* Steady Formulation, and squares HNMC, HPP1C1, is the moving Changeable Formulation of this twin Supplementary System, (The Sum of Areas of the two Changeable Squares is constant and equal to that of Hypotenuse). i.e. The Total Area is conserved on the Changable System.

**e.** Pythagoras theorem defines the relation between the three sides of the rightangled triangle HCP which is an equality of Squares . The Sum of the Quantities, *Moving Squares HNMC*, *HPP1C1*, is constant and equal to that of PCAD, which is the Conservation of Areas in motion .i.e.

In Mechanics, the fundamental laws of Conservation of Energy is not Energy's Property, but of Geometry's (Since the Total Area, quantity, Conserves on the Changeable System).

The Position of Points only, defines Properties and Laws of Universe (Quantities and Qualities). Conservation laws are the most fundamental principle of Mechanics. The Conserved Quantities (Energy, Momentum, Angular Momentum etc.) follow the Pythagoras theorem, applied on the moving machine [CA $\perp$ CP, CA = CP]. The parallel transformations are,

Kinetic Energy (KE) + Potential Energy (PE) = Total Energy. Changeable Square HNMC + Changeable Square HPP $_1C_1$  = Total Area of Square CADP.

f. In applying the method on the three dimension Space (*Four points = Three equal and perpendicular First dimensional Units* OA, OB, OC construct an Isosceles Orthogonal System with four Spheres, three on the Units and the fourth on the Resultant as diameters), exists a Changeable Space Formation such that the Sum of the Volumes of Spheres to be equal to that of the Resultant, meaning that, conservation of Volumes exists on the three Perpendicular Units. Energy (*Motion*) follows this Euclidean Mould, because this Proposition (*Principle*) belongs to geometry's, and not to Energy's which is only motion.

*Open Problem* ? Which logic exists on this moving machine such that the area of the changeable Square *or changeable Cube*, to be equal to that of the circle, *or Cube* ?

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by Marcos Georgallides .