ENERGY LAWS , FOLLOW MOULDS OF EUCLIDEAN GEOMETRY . AND THE SIX , TRIPLE - CONCURRENCY POINTS , LINE .

the point of convergency . A further The Barbaric Turks. *Analysis in Euclidean geometry follows .* Email < georgallides.marcos@cytanet.com.cy >

A geometrical attempt was developed Markos Georgallides : Tel-00357-99 634628 *for approaching the Open question 1* Civil Engineer(NATUA) : Fax-00357-24 653551 [*The Orthic triangle*] *concerning the* 15 , N .Mylona St , 6010 , Larnaca Cyprus *the locus of centerpoints* H1*...n and* Expeled from Famagusta town occupied by

The present article ` **Energy Laws , follow moulds of Euclidean Geometry***′ , demonstrates the correlation of < Changeable Areas in a closed or Isolated Figure* (*Any triangle or Square in a circle*) *to a Totally constant Area > to the < Constant Total Energy in a closed or Isolated System* **>** *The article ,* **Six , [Triple - Points] , Line** *, shows correspondences of lengths and angles ,* **of Projective and other Geometries** *,* **under Euclidean First dimensional Unit** *, which is one , Duality , Triple and Multiple .* P.12 , P19 .

THE ORTHOCENTER (H) OF A TRIANGLE (ABC) 15/1/2012

 \overline{p}

 $A\sqrt{a}$

 \dot{B}

c

Let Δ ABC be any triangle with vertices A , B , C and let **Δ A1B1C1** be its orthic triangle .

AA1, BB1, CC1 are the altitudes of the vertices and points A1, B1, C1 the feet of them. Altitudes AA1 \perp BC, BB1 \perp AC, CC1 \perp AB and triangles AA1 B, AA1 C, BB1A, BB1C CC₁A, CC₁B are all right angled . It is also holding B₁B^{\sim}1^{\perp}AB

 E ABC = E = Area of triangle ABC and let be $E A = E AB1C1 = Area of triangle AB1C1$, $E_B = E_{BC1A1}$ = Area of triangle BC1A1, $EC = E$ CA1B1 = Area of triangle AC1B1.

For shortness , we use the known ratios on any right angle triangle ABC at C : The ratio of opposite side $BC = a$ to the hypotenuse $AB = c$ is called, sine of angle A, $(\sin A = a/c)$ and the ratio of the adjacent side $AC = b$ to the hypotenuse AB is called cosine of angle A ($\cos A = a/c$). It is known,

 $E_A = E_{AB1C1} = \frac{1}{2}$. AC₁. B₁B^{\leq} 1 = ½. AC₁. AB₁. sinA] = ½. AC₁. AB₁. sinA (1) E ABC = ½ . AB . CC1 = ½ . AB.AC. sin A .………………….. (2)

By division : $E_A/E_{ABC} = [AC_1, AB_1, \sin A]/[AB, AC, \sin A] = [AC_1, AB_1]/[AB, AC]$

and for $AC1 = AC \cdot cosA = [b \cdot cosA]$, $AB1 = AB \cdot cosA = [c \cdot cosA]$ and also

Using rotational similarity then :

The area of the three triangles is.

 $E_A = E_{ABC}$ **cos² A** = E_{COS} ² A $E_B = E_{ABC}$ **cos² B** = E_{COS} ² B $E C = E ABC$ **C** $cos^2 C = E cos^2 C$ by summation :

 $E_A + E_B + E_C = E\cdot\cos^2 A + E\cdot\cos^2 B + E\cdot\cos^2 C = E\cdot [\cos^2 A + \cos^2 B + \cos^2 C]$, so

Area of triangle A1B1C1 is
$$
E_1 = E - [E_A + E_B + E_C] = E . [1 - \cos^2 A - \cos^2 B - \cos^2 C]
$$
 or

$$
E_1 = E. [1 - \cos^2 A - \cos^2 B - \cos^2 C] = E. [1 - (AB1/c)^2 - (BC1/a)^2 - (CA1/b)^2] \dots (4)
$$

Replacing the results of (6.abc) in (4) , then using ,

 $|AB1|^2$ $|b^2+c^2-a^2|^2$ $a^4+b^4+c^4-2$. $a^2-b^2-2a^2+c^2+2b^2+c^2$ |--- | = ------------ = --------------------------------------- $\begin{array}{ccc} | & c & | \end{array}$ 4. $b^2.c^2$ 4. $b^2.c^2$ $|BC1|^2$ $|a^2+c^2-b^2|^2$ $a^4+b^4+c^4-2$. $a^2-b^2+2a^2-c^2-2b^2-c^2$ |--- | = ------------ = --------------------------------------- $\begin{array}{|c|c|c|c|c|}\n\hline\n & a & 4. a^2.c^2 & 4. a^2.c^2\n\end{array}$

| CA1|² | a²+b²- c²| ² a + b +c + 2. a².b² -2.a².c² - 2.b².c² |--- | = ------------ = --------------------------------------- | b | 4. a².b² 4. a².b²

and rewrite equation (4) as :

 $4.a²b²c².$ [1 - cos²A - cos²B - cos²C] = $4.a²b²c²$ -[a6+a²b⁴ + a²c⁴- 2.a⁴b²- 2.a⁴c²+2.a².b².c²] $-$ [b6 $-2.a^2b^4+b^2c^4-2.b^4c^2+a^4b^2+2.a^2.b^2.c^2$] $-$ [c6 $-2.a^2c^4+b^4c^2-2.b^2c^4+a^4c^2+2.a^2.b^2.c^2$] $=$ a⁴.b² + a⁴.c² + a².b⁴ + a².c⁴ + b⁴.c² + b².c⁴ - 2.a².b².c² - a6 - b6 -c6.

then the ratio of area **E1** of the Orthic triangle to the area **E** of the triangle ABC is :

E₁
$$
a^4 \cdot b^2 + a^4 \cdot c^2 + a^2 \cdot b^4 + a^2 \cdot c^4 + b^4 \cdot c^2 + b^2 \cdot c^4 - 2 \cdot a^2 \cdot b^2 \cdot c^2 - a^6 - b^6 \cdot c^6
$$

\n... = 4a²·b²·c²
\nE₁ 4a²·b²·c² - a²[b²+c² - a²]² - b²[a²+c² - b²]² - c²[a²+b² - c²]²
\n... = 4a²·b²·c² - a²[b²+c² - a²]² - b²[a²+c² - b²]² - c²[a²+b² - c²]²
\n... (5)
\nE

Verification :

For equilateral triangle
$$
a = b = c \rightarrow \textbf{E1} / \textbf{E} = (6. a6 - 2. a6 - 3. a6)/4. a6 = a6/4. a6 = 1/4
$$

For isosceles triangle $a, b = c \rightarrow \textbf{E1} / \textbf{E} = [2. a^4. b^2 + 2. a^2. b^4 - 2. a^2. b^4 - a6]/4. a^2. b^4$

$$
= [2. a^4. b^2 - a6]/4. a^2. b^4 = [2. a^2. b^2 - a^4]/4. b^4 = a^2.(2. b^2 - a^2)/4. b^4
$$

Extensions to Pythagoras`s theorem :

Using the general conversions of Pythagoras`s theorem is easy to measure altitude $la = AA1$, $lb = BB1$, $lc = CC1$

In the right angled triangle $ABA1 \rightarrow AA1^2 = AB^2 - BA1^2 = AB^2 - (BC - A1C)^2$ AA₁² = AB² - (BC² + A₁C² - 2.BC .A₁C) = AB² - BC² - A₁C² + 2.BC .A₁C In the right angled triangle $AA1C \rightarrow AA1^2 = AC^2 - A1C^2$ and by subtraction, $0 = AB^2 - BC^2 - A1C^2 + 2.BC$. A1C $- AC^2 + A1C^2 = AB^2 - BC^2 - AC^2 + 2.BC$. A1C or 2.BC.A1C = AC² + BC²- AB², so \rightarrow A1C = [AC²+ BC²- AB²] /2.BC = [a² + b²-c²]/2a $A1C = [a^2 + b^2 - c^2]/2$.a (6ac) also $A1B = a - A1C$ = a - $[a^2 + b^2 + c^2] / 2.a = [2a^2 - b^2 - a^2 + c^2] / 2.a = [a^2 + c^2 - b^2] / 2a$ $A1B = [a^2 + c^2 - b^2] / 2.a$ …… (6ab) exists also $AA1² = AC² - CA1² = (AC + CA1)$. $(AC - CA1)$ and by substitution (6ac) 4. $a^2(AA1)^2 = [a^2 + b^2 + 2 \cdot ab - c^2] \cdot [c^2 - b^2 - a^2 + 2 \cdot ab] = 2 \cdot a^2b^2 + 2 \cdot a^2c^2 + 2 \cdot b^2 c^2$ $-[a^4 + b^4 + c^4]$ or

4. a²(AA1)² = 4. a²(la)2 = 2.a²b²+2. a²c²+2. b²c² - [a⁴+b⁴+c⁴], ..., (7a)
\nIn right angled triangle BB1G → BB1² = BC² - B1C².
\nIn right angled triangle BB1A → BB1² = BA²-(AC-BC)² = BA²-AC²-BC²+2.AC.B1C
\nand by subtraction, and then calculating B1C,B1A
\n
$$
D = BC²-B1C²-BA²+AC²+BC²]/2.AC = [a²+b²-c²]/2. b = [c²+b²-a²]/2. b -.... (6be)
\nB1A=b- [a²+b²-c²]/2. b=[2b²-b²-a²+c²]/2. b = [c²+b²-a²]/2. b -.... (6be)
\n
$$
B1B1² = BC²-B1C² = (BC+BC). (BC-B1C) = (a+BC)(a-BC) by substitution (6bc)
\n4. b²(BB1)² = [a²+b²+2.ab - c²]. [c²-b²-a²+2.ab] = 2.a²b²+2. a²c²+2. b²c² - [a⁴+b⁴+c⁴] ... (7b)
\nin the same way exists,
\n
$$
C1B = [CB²+AB²-BC²]/2.AC = [
$$
$$
$$

Since angle $\langle BClC = BB1C = 90^\circ \text{ then :}$

Using Pythagoras's theorem in F.1(2) \rightarrow BB1² = B B2. BC \rightarrow BB2 = BB1²/BC

 $2.a².b² + 2.a².c² + 2.b².c² - (a⁴ + b⁴ + c⁴)$ **BB2** = [BB1²] / BC = -- $4.b^2.a$

 $2.a².c² - 2.a².b² - 2.b².c² + (a⁴+b⁴+c⁴)$ $BC2 = [BC1^2] / BC =$ $4.c².a$ For $dx = [BB2 - BC2]$ then: 4. ab^2c^2 . $dx = 2.a^2b^2c^2 + 2.a^2c^4 + 2.b^2c^4 - c^2a^4 - c^2b^4 - c6-b6-a^4b^2-b^2c^4 + 2.a^2b^4 + 2.b^4c^2 - 2.a^2b^2c^2$ and 4. a.b².c². $\int dx = (\text{BB2 - BC2}) = 2.a^2b^4 + 2.a^2c^4 + b^2c^4 + c^2b^4 - a^4b^2 - a^4c^2 - b^6 - c^6$ In the right angle triangle BB1B2 exists also , $(BB2)^2 = BB1^2 - B1B2^2 = [2.a^2b^2 + 2.a^2c^2 + 2.b^2c^2 - (a^4 + b^4 + c^4)] / 4.b^2$ - $[a^2 + b^2 - c^2]$. $[2 \cdot a^2 b^2 + 2 \cdot a^2 c^2 + 2 \cdot b^2 c^2 - (a^4 + b^4 + c^4)] / 16 a^2 b^4 =$ $[2.a^2b^2 + 2.a^2c^2 + 2.b^2c^2 - (a^4 + b^4 + c^4)][4.a^2b^2 - a^2-b^2 + c^2]/16a^2b^4 =$ $[2.a^2b^2 + 2.a^2c^2 + 2.b^2c^2 - (a^4 + b^4 + c^4)] [c^2 + 2.a^2b^2 - (a+b)^2]/16a^2b^4$ and the previous equation is : 4. a.b².c². dx = 2.a²b⁴ + 2.a²c⁴ - a⁴b²- a⁴c² + b²c⁴ + c²b⁴ - b6 - c6 or $dx = [BB2 - BC2] = [2a^2b^4 + 2a^2c^4 - a^4b^2 - a^4c^2 + b^2c^4 + c^2b^4 - b^6 - c^6]/4ab^2c^2$..(a) Verification : For $b = c \rightarrow BA = BC2 + [BB2 - BC2]/2 = a/2$ **dx** = BB2 - BC2 = $(4.a²b⁴ - 2.a⁴b²) / 4(ab⁴ = (4.ab² - 2.a³) / 4.b² = (2.ab² - a³) / 2.b²$ $BC2 = (a^4 + b^4 + b^4 + 2a^2b^2 - 2a^2b^2 - 2b^2b^2)$ /4.ab² = $(a^4 + 2b^4 - 2b^4)$ / 4.ab² = a³ / 4.b² BA1 = (a^{3}) / 4.b² + ($2.ab^{2} - a^{3}$) / 4.b² = 2.ab² / 4.b² = a /2 **dx** = BB2 - BC2 = $(4.a^2b^4 - 2.a^4b^2)/4.ab^4 = (4.ab^2 - 2.a^3)/4.b^2 = (2.ab^2 - a^3)/2.b^2$ From similar triangles CAA1, C B1B2 \rightarrow [B1B2/AA1] = CB1/b and (B1B2)²= [CB1².AA1²]/b² or B1B2² = $(a^2 + b^2 - c^2)$ ² . $[2 \cdot a^2 b^2 + 2 \cdot a^2 c^2 + 2 \cdot b^2 c^2 - (a^4 + b^4 + c^4)]$ / 4.b⁴ .4a² and **B1B2² = (a²+b²-c²)². [(a+b)² - c²] . [c²- (a-b)²] / 16. a**²**b** ……………. From similar triangles BAA1, $BC1C2 \rightarrow [C1C2/AA1] = BC1/c$ and $(C1C2)^2 = [BC1^2.AA1^2]/c^2$ $C_1C_2^2 = (a^2 + c^2 - b^2)^2$. $[(a+b)^2 - c^2]$. $[c^2 - (a-b)^2]$ / 16. b^2c^4 and so and s __________________________ **B1B2 = (a²+b²-c²) . √ [c² - (a+b)²] . [(a-b)² - c²] / 4. ab**²……………. (8) __________________________ **C1C2 = (a²+c² -b²) . √ [c² - (a+b)²] . [(a-b)² - c²] / 4. bc²** ….……….. (8.a) Verification : For $b = c \rightarrow B1B2 = C1C2$ $a²$ $a²$ $a²$ $a²$ $a²$ B1B2 = ------- $\sqrt{(b^2-a^2-b^2-2.ab)} \cdot (a^2+b^2-2.ab-b^2) =$ ------ $\sqrt{(a^2+2.ab)} \cdot (a^2-2.ab)$ 4.ab² 4.b²

5

$$
C1C2 = \dots \qquad \sqrt{(b^2 - a^2 - b^2 - 2 \cdot ab) \cdot (a^2 + b^2 - 2 \cdot ab - b^2)} = \dots \qquad \sqrt{-(a^2 + 2 \cdot ab) \cdot (a^2 - 2 \cdot ab)}
$$

4.ab²
4.ab²
[AA1]² = b² - a² /4 = (4.b² - a²) /4 → AA1 = $|\sqrt{4 \cdot b^2 - a^2}|/4$

Let $[B1B2-C1C2] = dy$, then $dy = [CB1. AA1]/b - [BC1. AA1]/c = [AA1].$ [c.CB1- b.BC1] / bc

c.CB1- b.BC1 = c.(a²+b²-c²)/2.b – b.(a²+c²-b²/2c **=** [a²c²- a²b²+b+ c] / 2.bc and

$$
dy = [B1B2 - C1C2] = \frac{\sqrt{[c^2 - (a+b)^2] \cdot [(a-b)^2 - c^2]}}{4 \cdot a b^2 c^2}
$$

$$
[a^2c^2 - a^2b^2 + b^4 + c^4] \qquad \text{or}
$$

$$
4 \cdot a b^2c^2
$$

$$
dy = [B1B2 - C1C2] = \frac{\sqrt{[(a+b)^2 - c^2] \cdot [c^2 - (a-b)^2]}}{4 \cdot a b^2 c^2}
$$

$$
[a^2c^2 - a^2b^2 + b^4 - c^4] \dots (b)
$$

B₁C₁ is measured by using Pythagoras's theorem in triangle (B₁B₁, dy, dx) and then by squaring equation (a) and (b) ,

 dx^2 . [4.a b²c²] ² = [4.a⁴b⁸+ 4.a⁴c⁸ +a⁸b⁴ + a⁸c⁴ + b⁴c⁸ + b⁸c⁴ + b12 +c12 -4.a6.b6 -4a6b⁴c² $+4. a²b6. c⁴ +4. a²b⁸c² -4. a²b10 - 4. a²b⁴c6 + 8. a⁴b⁴c⁴ - 4. a6b²c⁴ - 4. a6. c6 +4. a²b²c⁸ +4. a²b⁴c6$ $-4. a²b6. c⁴ -4. a²c10 + 2a⁸b²c² -2. a⁴b⁴c⁴ -2. a⁴b6c²+2. a⁴b⁸+2. a⁴b²c6 - 2. a⁴b²c6 - 2. a⁴b⁴c⁴ +$ $2 \cdot a^4 b^6 c^2 + 2 \cdot a^4 c^8 + 2 \cdot b^6 c^6 - 2 \cdot b^8 c^4 - 2 \cdot b^2 c^1 0 - 2 \cdot b^1 0 c^2 - 2 \cdot b^4 c^8 + 2 \cdot b^6 c^6$

 $[4. a²b²c⁸ - 4. a²b10 - 4. a²c10 + 4. a²b⁸c² + 6. a⁴b⁸ + 6. a⁴c⁸ + 4. a⁴b⁴c⁴ - 4. a6. b²c⁴ - 4. a6. b⁴c²$ $-4.36.66 - 4.36.66 + 2a^{8}b^{2}c^{2} + a^{8}b^{4} + a^{8}c^{4} - 2.b^{2}c^{1}0 + 4.b6.66 - b^{8}c^{4} - 2.b10c^{2} + b12 + c121$

$$
dy^{2} \t{.} [4.a b^{2}c^{2}]^{2} = [(a+b)^{2} - c^{2}] \t{.} [c^{2} - (a-b)^{2}] \t{.} [a^{2}c^{2} - a^{2}b^{2} + b^{4} - c^{4}]^{2} = [a^{2} + b^{2} + 2.ab - c^{2}] \t{.} [c^{2} - a^{2} - b^{2} + 2.ab] \t{.} [a^{2}c^{2} - a^{2}b^{2} + b^{4} - c^{4}]^{2} = [a^{2}c^{2} - a^{2}b^{2} + 2.a^{3}b + b^{2}c^{2} - b^{4} + 2.ab^{3} + 4.abc^{2} - c^{4} + a^{2}c^{2} - a^{2}b^{2} - 2.a^{3}b + b^{2}c^{2} - 2.ab^{3} - 2.abc^{2} + 4.a^{2}b^{2}] \t{.} [a^{2}c^{2} - a^{2}b^{2} + b^{4} - c^{4}]^{2} = [2.a^{2}c^{2} + 2.a^{2}b^{2} + 2.b^{2}c^{2} - a^{4} - b^{4} - c^{4}] \t{.} [a^{4}c^{4} + a^{4}b^{4} + b^{8} + c^{8} - 2.a^{4}b^{2}c^{2} + 2.a^{2}b^{4}c^{2} - 2.a^{2}c^{6} - 2.a^{2}b^{6} + 2.a^{2}b^{2}c^{4} - 2.b^{4}c^{4}] =
$$

 $2. a6. c6 + 2. a6. b⁴c² + 2. a²b⁸c² + 2. a²c10 - 4. a6b²c⁴ + 4. a⁴b⁴c⁴ - 4. a⁴c⁸ - 4. a⁴b6c² + 4. a⁴b²c6$ $-4. a²b⁴c6 + 2. a6. c6 - 4. a6. b⁴c² + 2. a²b²c⁸ + 4. a²b10+2. a6. b²c⁴ + 4. a⁴b⁴c⁴ - 4. a⁴b⁸ + 4. a⁴b6c²$ $-4. a⁴b²c6 - 4. a²b6.c⁴ - 4. a6.c6 - 4. a²b²c⁸ +2. b10c² + c⁴ + 4. a²b⁴c6 - 4. a⁴b⁴c⁴ + 2. a⁴b6c²$ $+2a^{4}b^{2}c6 c6 + 2a^{2}b6c^{4} - 4a^{2}b^{8}c^{2} + 2b^{2}c10 - a^{8}c^{4} - a^{8}b^{4} - a^{4}b^{8} - a^{4}c^{8} + 2a^{8}b^{2}c^{2}$ $-2. a6.b⁴c² + 4. a6.c6 + 2. a6.b6 - 2. a6.b²c⁴ + 2. a⁴b⁴c⁴ + 2. a⁸c⁴ - b⁴c⁸ - a⁴b⁸ - 2. a²b6.c⁴$ $2.a⁴b6c² - 2.a²b⁸c² + 2.a²b⁴c6 + 2.b²c10 - a⁴b⁴c⁴ - b12 - b⁸c⁴ + 2.b⁴c⁸ - a⁴c⁸ + 2.a⁴b²c6$ $-2.a^2b^4c^6 + 2.a^2c^10 + 2.a^2b^6c^4 - 2.a^2b^2c^8 - a^4b^4c^4 - c12$.

and segment B1C1 is :

$$
(dx2+dy2) \cdot [4.ab2c2] 2 = [4.a4b2c2]. [a4+b4+c4 -2.a2c2-2.a2b2 +2.b2c2]
$$
 and

 $[4.a⁴b²c²]$. $[b²+c² - a²]$ ² (dx²+dy²) = [B1C1] ² = ----------------------------------- $[4.ab^2c^2]$ ²

$$
2. a^{2}bc. [b^{2}+c^{2}-a^{2}] = a
$$

\n
$$
4. ab^{2}c^{2} = 2.bc
$$

\n
$$
a = B1C1 = \frac{a}{1000} \text{ s} + c^{2} - a^{2} = \frac{a}{100} \text{ s} + c^{2} - a^{2} = \frac{a}{100} \text{ s} + c^{2} - a^{2} = \frac{a}{100} \text{ s} + c^{2} = \frac{a}{100} \text{ s
$$

 $[a^2b^2 + a^2c^2 - a^4 + a^2b^2 + b^2c^2 - b^4 + a^2c^2 + b^2c^2 - c^4]$ Po = B1C1 +A1C1 + A1B1 = -- = 2.abc $[2.a^2b^2+2.a^2c^2+2.b^2c^2-a^4-b^4-c^4]$ $4.b^2c^2 - [a^2-b^2-c^2]^2$ Po = --- = ----------------------------------- = 2.abc 2.abc $[2(bc+a^2-b^2-c^2]$.[2.bc - a^2+b+c^2] $[a^2-(b-c)^2]$.[(b+c)²-a²] Po = --- = --- or 2.abc 2.abc [a+b – c] . [a- b+c] . [a+b+c] . [b+c -a] **[a+b+c] .[-a+b+c].[a-b+c].[a+b– c] Po** = -- = **--** … (10) 2.abc **2.abc** Remarks :

a) Perimeter Po becomes zero when $[-a+b+c]=0$, $[a-b+c]=0$, $[a+b-c]=0$ or when $a = b+c$, $b = a+c$, $c = a+b$ and This is the property of any point A on line BC *where then* Segment BC = a is equal to the parts $AB = c$ and $AC = b$. The same for points B and C respectively [6] Since perimeter is minimized by the orthic triangle then this triangle is the only one among all inscribed triangles in the triangle ABC. This property is very useful later on.

- **b**) Since Perimeter Po of the orthic triangle is minimized at the three lengths a, b, c then is also at the three vertices A , B , C of the original triangle ABC .
- **c**) The ratio (R_p) of the perimeter of the orthic triangle A1B1C1 to the triangle ABC is:

 Po [a+b – c].[a- b+c].[b+c – a].[a+b+c] **[-a+b+c] . [a-b+c] . [a+b– c]** Rp **= ------ = ---** = --- … (11) **P** 2.abc . [a+b+c] **2.abc**

For $a = b = c$ then $\rightarrow (P_0 / P) = (a.a.a) / 2.a.a.a = 1/2$ which is holding. Let

 $P_0 = a+b+c$ is the perimeter of triangle \triangle ABC $P_1 = a_1 + b_1 + c_1$ is the perimeter of orthic triangle Δ A₁ B₁ C₁ $P_n = a_n + b_n + c_n$ is the perimeter of **n**-th orthic triangle

The ratio Rp of the perimeters is depended only on the **n-1** sides of orthic triangles :

 P_n an + **b**_n + **c**_n **i** $[-\mathbf{a}_{n-1} + \mathbf{b}_{n-1} + \mathbf{c}_{n-1}]$. $[\mathbf{a}_{n-1} - \mathbf{b}_{n-1} + \mathbf{c}_{n-1}]$. $[\mathbf{a}_{n-1} + \mathbf{b}_{n-1} - \mathbf{c}_{n-1}]$ Rp = ---- = ---------------------- = --- P_{n-1} an $-1 + b_{n-1} + c_{n-1}$.
2. a_{n-1} **b**_{n-1} **c**_n-1

d) The ratio Ra of the area of triangle Δ An B_n C_n to the Δ An-1 B_{n-1} C_{n-1} is :

En-1 4.a n-1².b n-1² c n-1² - a n-1² b n-1²+c n-1²-a n-1² | 2 - b n-1² | a n-1²+c n-1²-b n-1² | 2 -c n-1² | a n-1²+b n-1²-c n-1² | Ra = --- =-- En . $4.\mathbf{a} \cdot \mathbf{n}^{-1}$, $\mathbf{b} \cdot \mathbf{n}^{-1}$, $\mathbf{c} \cdot \mathbf{n}^{-1}$ \ldots (11a)

The ratio Ra of the areas is also depended only on the **n-1** sides of orthic triangles :

e.a . It is well known that the nine point circle is the circumcircle of the orthic triangle and has circumradius RA1B1C1 which is one half of the radius $R = R$ ABC of the circumcircle of triangle Δ ABC .

 From F.4 , using Pythagoras theorem on triangle with hypotenuse equal to the diameter of the circle , then we have the law of sines as :

AB AC BC AB AC BC ------ = ------- = ------- = 2. RABC and → R = --------- = --------- = ---------- and R is sinC sinB sinA 2.sinC 2.sinB 2.sinA BC a.c $a.c [2.b] = abc$ abc R = -------- = --------- = ------_____________________ **=** /==================== 2.sinA 2. BB₁ 2. $\sqrt{[(a+b)^2-c^2]}$. $[c^2-(a-b)^2]$ $\sqrt{[(a+b)^2-c^2]}$. $[c^2-(a-b)^2]$ and **abc** R A1B1C1 $=$ /============================ the circumradius of orthic triangle (12) 2. $\sqrt{\left[(a+b)^2 - c^2 \right] \cdot \left[c^2 - (a-b)^2 \right]}$

For $(a+b)^2 - c^2 = 0$ or $c^2 - (a - b)^2 = 0$ then R AIBICI $=\infty$, and it is $a + b = c$ and $a - b = c$ $a = b + c$ i.e. triangle ABC has the three vertices (the points) A, B, C on lines **c** and **a** respectively , a property of points on the two lines . [6]

e.b. The denominator of circum radius is of two variables $x = [(a+b)^2-c^2]$ and $y=[c^2-(a-b)^2]$ which have a fixed sum of lengths equal to **4.ab** and their product is to be made as large as possible. The product of the given variables, $x = [(a+b)^2-c^2]$, $y = [c^2-(a-b)^2]$ becomes maximum (this is proven) when $x = y = 2$.*ab* and exists on a family of hyperbolas curves where xy is constant for each of these curves $F.2(4)$

All factors in denominator are conjugate and this is why orthogonal hyperbolas on any triangle are conjugate hyperbolas and follow Axial symmetry to their asymptotes .

The tangent on hyperbolas at point $x = 2$ ab formulates 45 ° angle to x, y plane system.

Since Complex numbers spring from Euclidean geometry [11] then the same result follows from complex numbers also . It is holding ,

x.y = $\rho \rho'$. $\left[\cos (\varphi + \varphi') + i \sin (\varphi + \varphi') \right]$ where ρ , ρ' are the modulus and φ , φ' the angles between the positive direction of the x- axis and x , y direction .

Product **x.y** becomes maximum when the derivative of the second part is zero as,

 $-\sin(\varphi+\varphi') + i \cdot \cos(\varphi+\varphi') = 0 \qquad \rightarrow \quad \sin(\varphi+\varphi') = i \cdot \cos(\varphi+\varphi') \qquad \text{or}$ sin $(\varphi + \varphi^{\prime})$ $=$ tan ($\varphi + \varphi$) = + i or \rightarrow tan $2(\varphi + \varphi)$ = -1 i.e. cos $(\varphi + \varphi^{\prime})$

 the slope of the tangent line (which is equal to the derivative) at point $x = y = 2$.*ab* is **-1** and this happens for $(\varphi + \varphi^*) = 135$ ° or 45°.

e.c. Let`s consider the length AH and the directions rotated through point A . F.1(1) The right angles triangles HAB₁, BB₁C are similar because all angles are equal respectively (angle $AHB_1 = B_1BC$ because $BB_1 \perp AB_1$ and $BC \perp AH$), so

AH AB₁ BC . AB₁ a . $[c^2 + b^2 - a^2]$ 2.b a . $[c^2 + b^2 - a^2]$ $-$ = ------ or AH = ----------- = BC BB₁ BB₁ $2b.\sqrt{(a+b)^2-c^2}$. $[c^2-(a-b)^2]$ $\sqrt{(a+b)^2-c^2}$. $[c^2-(a-b)^2]$ In any triangle ABC is holding $---$ F.1(1)

 $a^2 = b^2 + c^2 - 2$.bc.cos A \rightarrow 2.bc.cos A = $b^2 + c^2 - a^2$ \rightarrow cos A = $[b^2 + c^2 - a^2]/2$.bc
 $b^2 = c^2 + a^2 - 2$.ac.cos B \rightarrow 2.ac.cos B = $c^2 + a^2 - b^2$ \rightarrow cos B = $[c^2 + a^2 - b^2]/2$.ca $b^2 = c^2 + a^2 - 2 \cdot ac \cdot \cos B \rightarrow 2 \cdot ac \cdot \cos B = c^2 + a^2 - b^2$ $c^{2} = a^{2}+b^{2} - 2$.ab.cos C $\rightarrow 2$.ab.cos C = $a^{2}+b^{2} - c^{2}$ \rightarrow cos C = $[a^{2}+b^{2} - c^{2}] / 2$.ab so

$$
AH = \frac{a.[c^2 + b^2 - a^2.[\sqrt{[(a+b)^2 - c^2]}.[c^2 - (a-b)^2]}{[(a+b)^2 - c^2]}.[c^2 - (a-b)^2]} = \frac{a.[c^2 + b^2 - a^2].\sqrt{[x,y]} \quad 2.abc.\sqrt{x,y}}{x.y}
$$
\nwhere $x = (a+b)^2 - c^2$, $y = c^2 - (a-b)^2$

 | **2.abc.√x.y | 2.abc AH = |-----------------| . cos A** = **|------------| . cos A** = **Vector AH** …………(13) **x.y √x.y**

From F2(1) $BC = a$, $AC = b$, $AB = c$, $CD = CE = CA = b$, $BD = BC + CD = a + b$, $BA = BG = c$, $BE = BF = BC - EC = a - b$.

With point O as center draw circle with $BD = a+b$ as diameter and with point B as center draw circle $(B, BA = BG)$ intersecting circle (O, OB) at point G. Using Pythagoras theorem in triangles BDG, BFG then $GD^2 = BD^2 - BG^2 = [(a+b)^2 - c^2] = x$ and $GF^2 = GB^2 - BF^2 = c^2 - BE^2 = c^2 - (a-b)^2 = y$ and it is holding $x+y = a^2+b^2+2$.a b $-c^2+c^2-a^2-b^2+2$.a b = 4.a.b = GD + GF = constant $x \cdot y = [(a+b)^2 - c^2] \cdot [c^2 - (a-b)^2] = GD \cdot GF = constant$

Since Ortocenter **H** *changes Position , following orthic triangles* **A1B1C1** *, then Sector* **AHn** *is altering magnitude and direction , so* **AHn** *is a mathematical vector .*

f. In F.2(1) GD \perp GB, GF \perp BF, therefore angle DGF = GBF so the sum of the pairs of two vectors [GD ,GE] , [BG , BE] is constant . Since addition of the two bounded magnitudes follows parallelogram rule , then their sum is the diagonal of the parallelogram . In $F2(2-4)$ the product of the pairs of the two vectors $[GD, GE]$, $[BG, BE]$ is constant in the direction perpendicular to diameter DE , so rectangular hyperbolas on the x, y system are 45 ° at the point $x = y = 2$.ab.

g. In F.3(2) orthic triangle A1B1C1 of triangle ABC is circumscribed in Nine-point circle with center point N, *the middle of OH*, while point O is ABC`s circumcenter. Since point N is the center of $A_1B_1C_1$'s circumcenter, therefore Euler line OH is rotated through

the middle point N of OH to all nested orthic triangles $A_nB_nC_n$ as is shown in F.3(2), or are as

Sector (ONH) , $(N = O_1 N_1 H_1)$, $(N_1 = O_2 N_2 H_2) \rightarrow (N_{n-1} = O_n N_n H_n) \rightarrow (N_{\infty} = O_{\infty} N_{\infty} H_{\infty})$

From vertices A,B,C and orthocenter H of triangle ABC passes rectangular circum-hyperbolas with point N as the center of the Nine-point circle. In Kiepert hyperbola, its center is the midpoint of Fermat points . In Jerabek rectangular hyperbola , its center is the intersection of Euler lines of the three triangles, of the four in triangle ABC. (the fourth is the orthic triangle).

h. In F.2(1) GD \perp GB and GF \perp BF therefore angle DGF = GBF or DGF + GBF = 360° [6] ie. angles DGF , GBF are conjugate . It is known that in an equilateral hyperbola , conjugate diameters make equal angles with the asymptotes, and because angle $\text{DGF} = \text{GBF}$ then the sum of the two pairs of the two vectors (GD,GE), (BG,BE) is constant for all AH of orthic triangles.

To be vector **AH** a relative extreme (minimum or zero) , numerator of equation (13) must be zero in a fix direction to triangle ABC . Since a , b , c are constants , vector AH is getting extreme to the opposite direction by Central Symmetry through point A .

Verification :

C1. For $a = b = c$ then $cosA = [2a^2 - a^2]/2.a^2 = a^2/2a^2 = 1/2$ therefore $\rightarrow A = 60^\circ$ $x = (a+b)^2 - c^2 = 4a^2 - a^2 = 3 \cdot a^2$, $y = c^2 - (a-b)^2 = a^2$ x + y = 4. a² and x.y = 3.a __a AH = $\begin{bmatrix} 2 \cdot a^3 \cdot a^2 \sqrt{3} \end{bmatrix}$ / $\begin{bmatrix} 3 \cdot a^4 \cdot 2 \end{bmatrix} = a \cdot \sqrt{3}/3 = \begin{bmatrix} a \sqrt{3}/2 \end{bmatrix}$. $\begin{bmatrix} (2/3) \rightarrow a \end{bmatrix}$ / $\begin{bmatrix} a \neq \sqrt{2} \end{bmatrix}$ a = $a \sqrt{3}$ i.e. *Orthocenter Hn limits to* \rightarrow *circumcenter* $0 \rightarrow (2/3)$ *. AA1*

C2. For $b = c$ then cosA = $[2b^2 - a^2]/2$. $b^2 = [b \sqrt{2} + a][b \sqrt{2} - a]/2b^2$ ……. (13.a)

1. For $\cos A = 0$ then $b\sqrt{2} - a = 0$ and this for $A = 90^\circ$ and $AH = 0$ i.e. *<i>Orthocenter Hn limits to Vertice* $A \rightarrow AHn \rightarrow A$

Since also cos A becomes zero with $b\sqrt{2} = -a$ (The Central symmetry to a) then *Orthocenter Hn limits always to* \rightarrow *Vertice A or AHn* \rightarrow A

- 2. For $\cos A = 1/2$ then $A = 60^{\circ}$, $x = 2(ab + a^2)$, $y = 2(ab b^2)$ and $b = a$ AH = $[2.ab^2 \text{·} \sqrt{x} \text{·} y] \cdot (1/2) / xy = [a \cdot b^2 / \sqrt{x} \text{·} y] = (ab^2) / a\sqrt{3} = a\sqrt{3}/3 = 40$ i.e. *Orthocenter Hn limits to circumcenter* O *of triangle ABC or AHn* \rightarrow O.
- 3. For cos A = $\sqrt{2}/2$ then A = 45°, x = 2.ab + a², y = 2.ab b² and 4.la² = 4.b² a² AH =[2.ab² \sqrt{x} ,y].($\sqrt{2}/2$) / xy =[2.ab² $\sqrt{2}/\sqrt{x}$,y] =[2.ab². $\sqrt{2}$] / $\sqrt{(4.1a^2)} = b^2/(a.\sqrt{2})$ i.e.

Orthocenter Hn limits to An on altitude la, or AHn \rightarrow b^2 /(la. $\sqrt{2}$), and for cosA = la²/b² AHn = α i.e *Orthocenter Hn limits to A1*, *or* AHn = α = AA₁ = Altitude AA₁.

4. For
$$
\cos A = 1
$$
 then $A = 0^{\circ}$, $x = a^2 + b^2 + 2 \cdot ab - b^2 = a \cdot (a + 2 \cdot b)$
 $y = b^2 - a^2 + 2 \cdot ab - b^2 = a \cdot (2 \cdot b - a)$ and

AH = $[2.ab^2] / [a.\sqrt{4.b^2 - a^2}] = [2.b^2] / [\sqrt{4.b^2 - a^2}]$ and for $A = 0^\circ$ then AH = $[2.b^2] / 2.b = b$ i.e. Orthocenter Hn limits to vertices B or C (the two vertices coincide) or *Orthocenter Hn limits to B, C or* AHn \rightarrow B = C

5. For $\cos A = -1$ then $A = 180^\circ$, $x = a. (a+2.b)$ $y = a. (2.b-a)$ and $a = 2.b$

AH = $[2.b^2](-1) / [\sqrt{4.b^2-(2.b)^2}] = [-2.b^2] / [\infty] = 0$ i.e point A coincides with the foot A₁ or A_{A1} = 0, *Orthocenter Hn limits to B*, *C* or AHn \rightarrow B = C

C3. The first Numerator term of equation (13) and in F.2(3) is $, c^2 + b^2 - a^2$, and this *in order to be* on a right angle triangle ABC with angle $\langle A = 90^\circ \rangle$, must be zero, or $a^2 = b^2 + c^2$. The second term is $x = (a+b)^2 - c^2 \ne 0$, $a^2+b^2+2ab - c^2 = b^2+c^2+b^2+2ab - c^2 = 0$ 2. $[a\mathbf{b} + \mathbf{b}^2] \neq 0$ or $a + \mathbf{b} \neq 0$ = constant $\rightarrow (\mathbf{b}/a) < 0$ i.e. $\mathbf{H} \rightarrow \mathbf{A}$, and for $y = c^2 -(a-b)^2 \neq 0$, $c^2 - a^2 - b^2 + 2ab = c^2 - b^2 - c^2 - b^2 + 2ab = 2$. $[ab - b^2] \neq 0$ or $a - b \neq 0$ = constant, and (b/a) > 0 i.e. $H \rightarrow A$.

Geometrically, since B_1C_1 of orthic triangle $A_1B_1C_1$ coincides with point A, so the center N of the nine-point circle on ABC is always on OA . Since point N is $A₁B₁C₁$ s circum-center and represents the new O₁ then the new N₁ of A₁B₁C₁'s is the center point on NA or NH₁ = NA / 2 Therefore point N is on OA direction at $(AO/2)$, $(AO/4)$, $(AO/8)$, $(AO/2^a)$ points, i.e.

In any right-angle triangle ABC where angle $\langle A = 90$, the *locus of the orthocenter points* H_1 *……..Hn* of the orthic triangles $A_n B_n C_n$, is on line OA, and for $n = \infty$ then *convergent to point A (vertice A) of the triangle ABC .*

so , In an equilateral triangle ABC where a = b = c , Orthocenter H is fixed at Centroid K which coincides with Circum center O , and the Nine-point center N . In an Isosceles triangle ABC where a , b = c , Orthocenter H moves on altitude AA1 (this is the locus of the orthocenter points $H_1,...,H_n$ *) and for angle* $A = 90^\circ$ *then convergent to the point A of the triangle .*

Remark : In any triangle ABC rectangular hyperbolas follow Axial symmetry to their Asymptotes , in contradiction to orthocenter H , which follows Central Symmetry and Rotation through point A , the vertice opposite to the greatest side of the triangle . This Springs out of the logic of Spaces , Anti-Spaces , Sub-Spaces of any first dimentional Unit $ds > 0$. [11], therefore vector AHn is limiting to the Orthocenters H₁..., H_n of orthic triangles in triangle ABC . (Equation 13) . Conics through the vertices of triangle ABC that are not passing through Orthocenter H are not rectangular hyperbolas . A further geometrical analysis follows .

Extremum Principle or Extrema : 20 / 1 / 2012

All Principles are holding on any Point A .

For two points A , B not coinciding , exists Principle of Inequality which consists another quality . Any two Points exist in their Position under one Principle , *Equality and Stability in Virtual displacement which presupposes Work in a Restrain System*) . [11]

This Equilibrium presupposes homogenous Space and Symmetrical Anti-Space .

For two points A , B which coincide , exists *Principle of Superposition* which is a Steady State containing Extrema for each point separately .

Extrema , for a *point A* is the Point , for a *straight line* the infinite points on line , either these coincide or not or these are in infinite , and for *a Plane* the infinite lines and points with all combinations and Symmetrical ones *, i.e. all Properties of Euclidean geometry , compactly exist in Extrema Points , Lines , Planes , circles .*

Since Extrema is holding on Points , lines , Surfaces etc , therefore all their compact Properties (Principles of Equality , Arithmetic and Scalar , Geometric and Vectors , Proportionality , Qualitative , Quantities , Inequality , Perspectivity etc) , exist in a common context . Since a quantity is either a vector or a scalar and by their distinct definitions are ,

Scalars, are quantities that are fully described by a magnitude (or numerical value) alone, **Vectors ,** are quantities that are fully described by both magnitude and a direction , therefore

In Superposition magnitude AB is equal to zero and direction , *any direction* , $\neq 0$ i.e.

Any Segment AB between two points A , B consist a Vector described by the magnitude AB and directions ÃB , BÃ and in case of Superposition ÃA , AÃ . i.e. Properties of Vectors , Proportionality , Symmetry , etc exists either on edges A , B or on segment AB as follows :

According to Thales F4.(1) , if two intersecting lines PA , PB are intercepted by a pair of Parallels AB // A'B', then ratios PA/AA', PB/ BB', PA/PA', PB/ PB' of lines, or ratios in similar triangles PAB, PA'B' are equal or $\lambda = \int P A / A A' = \int P B / B B'$. In case line A' B' coincides with AB, then $AA' = AA$, $BB' = BB$, i.e. exist **Extrema** and then $\lambda = [PA/AA] = [PB/BB]$, (Principle of Superposition).

B. Rational Figured Numbers of Figures F4.(2 - 3) .

The definition of "Heron" that gnomon is as that which, when added to anything, a number or figure , makes the whole similar to that to which it is added . (Proportional Principle) . It has been proven that the triangle with sides twice the length of the initial , preserves the same angles of the triangle . [6] i.e. exists **Extrema** for Segment BC at B1C1 .

C. A given Point **M** and any circle with AB as diameter . [6] .

It has been proved [6] that angle $AMB = 90^{\circ}$ for all points of the circle. This when point M is on B where then exists **Extrema** at point B for angle AMB . (Segments MA , MB) i.e. Angle $AMB = AMO + OMB = AMM_1 + M_1MB = ABA + ABB = 0 + 90^{\circ} = 90^{\circ}$ F5.(3)

D. A given Point **P** and any circle $(0, 0A)$. [6]

It has been proved that the locus of midpoints M of any Segments PA , is a circle with center O' at the middle of PO and radius O' $M = OA / 2$. (F6)

Extending the above for point M to be any point on PA such that $PM / PA = a constant ratio$ equal to λ , then the locus of point M is a circle with center O' on line PO, PO' = λ . PO, and radius $O'M = \lambda$. OA. **Extrema** exists for points on the circle.

Remarks :

1. In case $PO' = \lambda$. PO and $O'M = \lambda$. PO and this is holding for every point on circle, so also for 2, 3,.. n points i.e. any Segment AA1, triangle AA1A2, Polygon AA1...An,... circle, is represented as a Similar Figure (*Segment , triangle , Polygon or circle*) .

2. In case $PO' = \lambda$. PO and $PM_1 = PA$. λ_1 , then for every point A on the circle (O, OA), in or out the circle , exist a point M1 such that line AM1 passes through point P . i.e. every segment AA1 Triangle AAA2 , Polygon AA1……An , or circle , is represented as segment MM1M2 , Polygon MM1 Mn or a closed circle [Perspective or Homological shape]. F6.(1)

Any point M , not coinciding with points A , B consists a Plane (the Plane MAB) and from point M passes only one Parallel to AB .This parallel and the symmetrical to AB is the **Extrema** because all altitudes are equal and of minimum distance . When point M lies on line AB then parallel is on AB and all properties of point P are carried on AB and all of M on line AB . F7.(2-3)

F. Symmetry (Central , Axial) is Extrema F.8

Since any two points A,B consist the first dimentional Unit (magnitude AB and direction ÃB ,B Ã) F8.(1-2) equilibrium at the middle point of A , B , *Central Symmetry* . Since the middle point belongs to a Plane with infinite lines passing through and in case of altering central to axial symmetry ,then equilibrium also at *axial Symmetry* F8.(3), so Symmetrical Points are in **Extrema.** *Nature* follows this property of points of Euclidean geometry (*common context*) as Fermat`s Principle for Reflection and Refraction . F8.(4) .

G. A point P and a triangle ABC . (F9)

If a point P is in Plane ABC and lines AP , BP , CP intersect sides BC , AC , AB , of the triangle ABC at points A1, B1, C1 respectively F9. $(1-2)$, then the product of ratios λ is, $\lambda = (AB1/B1C)$. (CA1/A1B). (BC1/C1A) = 1, and the opposite . Proof :

Since **Extrema of Vectors** exist on edge Points A ,B ,C , and lines AC , BC , AB then for ,

a. Point P on line AC, $F9(3) \rightarrow A1 = C$, $B1 = P$, $C1 = A$ and for $\lambda = (AB1 \mid B1C) \cdot (CA1 \mid A1B) \cdot (BC1 \mid C1A) \rightarrow \lambda_1 = (PA \mid PC) \cdot (CC \mid BC) \cdot (AB \mid AA)$

b. Point P on line BC, $F9(4) \rightarrow A1 = P$, $B1 = C$, $C1 = B$ and for $\lambda = (AB1 \mid B1C) \cdot (CA1 \mid A1B) \cdot (BC1 \mid C1A) \rightarrow \lambda_2 = (AC \mid CC) \cdot (PC \mid PB) \cdot (BB \mid AB)$ c. Point P on line BA, $F9(5) \rightarrow A1 = B$, $B1 = A$, $C1 = P$ and for $\lambda = (AB1 \mid B1C) \cdot (CA1 \mid A1B) \cdot (BC1 \mid CA) \rightarrow \lambda_3 = (AA \mid AC) \cdot (BC \mid BB) \cdot (PB \mid PA)$ and for

 λ 1. λ 2. λ 3 = [PA.CC.AB.AC.PC.BB.AA.BC.PB] : [PC.BC.AA .CC.PB.AB .AC.BB.PA] = 1

i.e. Menelaus *Theorem*, and for Obtuse triangle $\lambda_1 \cdot \lambda_2 \cdot \lambda_3 = -1 \rightarrow$ Ceva's Theorem

H. A point P a triangle ABC and the circumcircle .

a. Let be A1 ,B1 ,C1 the feet of the perpendiculars (altitudes are the Extrema) from any point P to the side lines BC , AC , AB of the triangle ABC , F10.(4) Since Properties of Vectors exist on lines AA1 , BB1 ,CC1 then for **Extrema Points** ,

F10.(1) \rightarrow Point A1 on points B, C of line BC respectively, formulates perpendicular lines BP ,CP which are intersected at point P. Since Sum of opposite angles $PBA+PCA = 180^{\circ}$ therefore the quadrilateral PBAC is cyclic on circumcircle of triangle ABC and also the feet of the perpendiculars of point P on sides of triangle ABC are points B , C .

F10.(2) \rightarrow Point B1 on points A, C of line AC respectively, formulates perpendicular lines AP, CP which are intersected at point P. Since Sum of opposite angles $PAB+PCB = 180^\circ$ therefore the quadrilateral PABC is cyclic on circumcircle of triangle ABC and also the feet of the perpendiculars of point P on sides of triangle ABC are points A , C .

F10.(3) \rightarrow Point C1 on points A, B of line AB respectively, formulates perpendicular lines AP, BP which are intersected at point P. Since Sum of opposite angles $PAC+PBC = 180^\circ$ therefore the quadrilateral PACB is cyclic on circumcircle of triangle ABC and also the feet of the perpendiculars of point P on sides of triangle ABC are points A , B .

So **Extrema** for the three sides of the triangle is point P which is on the circumcircle of the triangle and the feet A1 ,B1 ,C1 of the perpendiculars of point P on sides of triangle ABC are respectively on sides BC , CA , AB i.e. on a line **. [** F10.4] *Simsons line.* Since altitudes PA1 , PB1 , PC1 are also perpendiculars on the sides BC,AC,AB and segments PA,PB,PC are diameters of the circles,then points A1,B1,C1 are collinear.[F10.5] . *Saimon Theorem*

b. Let be A1, B1, C1 any three points on sides of a triangle ABC (these points are considered **Extrema** because they maybe on vertices A, B, C or to ∞). F7.(1). If point P is the common point of the two circumcircles of triangles AB1C1, BC1A1, (a vertex and two adjacent sides) then circumcircle of the third triangle CA1B1 passes through the same point P . Proof :

Since points A, B1, P, C1 are cyclic then the sum of opposite angles $BAC + B1PC1 = 180^\circ$. Since points B, C1, P, A1 are cyclic then the sum of opposite angles $ABC + C1PA1 = 180^\circ$. and by Summation $BAC + ABC + (B1PC1 + C1PA1) = 360$ ° ………… (1) Since BAC+ABC+ACB = 180 \degree then BAC+ABC = 180 \degree - ACB and by substitution to (1) $(180^\circ - ACB) + 360 - A1PB1 = 360^\circ$ or , the sum of angles $ACB + A1PB1 = 180^\circ$, therefore points C, B₁, P, C₁ are cyclic i.e.

Any three points A1 , B1 , C1 on sides of triangle ABC , forming three circles determined by a Vertex and the two Adjacent sides , meet at a point P . (Miguel`s Theorem)

- **c.** In case angle PA1B = 90° then also PA1C = 90° . Since angle PA1C + PB1C = 180° then also PB1C = 90° (*angles PA1B , PC1B , PB1C are extreme of point P*) .
- **d.** ABC is any triangle and A1 ,B1 ,C1 any three points on sides opposite to vertices A ,B, C Show that Perimeter C1B1 +B1A1+A1C1 is minimized at Orthic triangle A1B1C1 of ABC.

 $F7(1)$ Since point P gets Extrema on circumcircle of triangle ABC , so sides A1B1 ,B1C1 ,C1A1 are **Extrema** at circumcircle determined by a vertex and the two adjacent sides .Since adjacent sides are determined by sides AA1 , BB1 , CC1 then maximum exists on these sides . Proof :

In triangle AA1B , AA1C the sum of sides p1 $p1 = (AA1 + A1B + AB) + (AA1 + AC + A1C) = 2(AA1) + AB + AC + BC = 2(AA1) + a+b+c$

In triangle BB1A , BB1C the sum of sides p2 $p2 = (BB1 + B1A + AB) + (BB1 + BC + B1C) = 2.(BB1) + AB + AC + BC = 2.(BB1) + a+b+c$

In triangle CC1A , CC1B the sum of sides p3 $p3 = (CC1 + C1A + AB) + (CC1 + AC + C1C) = 2(CC1) + AB + AC + BC = 2(CC1) + a+b+c$

The sum of sides $p = p1 + p2 + p3 = 2$. [AA1+BB1+CC1] + 3. [a+b+c] and since a+b+c is constant then **p** becomes minimum when AA1+BB1+CC1 or when these are the altitudes of the triangle ABC , where then are the vertices of orthic triangle . *i.e.*

The Perimeter C1B1 + B1A1 + A1C1 of orthic triangle A1B1C1 is the minimum of all triangles in ABC .

I. Perspectivity :

In Projective geometry , (*Desargues` theorem*) , two triangles are in perspective *axially ,* if and only if they are in perspective *centrally .* Show that , Projective geometry is an **Extrema** in Euclidean geometry .

Two points P , P′ on circumcircle of triangle ABC , form **Extrema** on line PP′ . Symmetrical axis for the two points is the mid-perpendicular of PP′ which passes through the centre O of the circle *, therefore* , Properties of axis PP′ are transferred on the Symmetrical axis in rapport with the center O (central symmetry) *, i.e.* the *three points of intersection A1 ,B1 ,C1 are Symmetrically placed as A′ , B′ , C′ on this Parallel axis .* F11.(1)

a. In case points P , P′ are on **any diameter** of the circumcircle F11.(2) , then line PP′ coincides with the parallel axis, the points A', B', C' are Symmetric in rapport with center O, and *the Perspective lines AA′ , BB′ , CC′ are concurrent in a point O′ situated on the circle . When a pair of lines of the two triangles (ABC , abc) are parallel F11.(3) , where the point of intersection recedes to infinity , axis PP′ passes through the circumcenters of the two triangles ,* (*Maxima*) *and is not needed " to complete " the Euclidean plane to a projective plane .i.e.*

 Perspective lines of two Symmetric triangles in a circle , on the diameters and through the vertices of corresponding triangles , are concurrent in a point on the circle .

b. *When all pairs of lines of two triangles are parallel ,* equal triangles *, then points of intersection recede to infinity , and axis PP` passes through the circumcenters of the two triangles* (*Extrema*).

c. *When second triangle is a point P then axis PP′ passes through the circumcenter of triangle .*

Now is shown that *Perspectivity* exists between a triangle ABC , a line PP′ and any point P where then exists Extrema , i.e. *Perspectivity in a Plane is transferred on line and from line to Point This is a compact logic in Euclidean geometry which holds in Extrema Points .*

J. A point A1 and triangle ABC in a circle of diameter AA′ .

In F12. Lines CA', BA' produced intersect lines AB, AC at points B', C' respectively. A1 is any point on the circle between points B , A′. $CA₁$, $BA₁$ produced intersect lines AB , AC at points $B₁$, $C₁$ respectively.

Show that lines B₁C₁ are concurrent at the circumcenter K of triangles CC'B', BB'C'.

Proof :

Angle $C'CA' = C'CB' = 90^\circ$ therefore circumcenter of triangle $CC'B'$ is point K, the middle point of B'C' Angle $B'BA' = B'BC' = 90^\circ$ therefore circumcenter of triangle BB'C' is point K, the middle point of B'C' Considering angle $\langle C'CA' = 90^\circ$ as constant then all circles passing through points C, A', C' have their center on KC .

Considering angle B'BA'= 90° as constant then all circles passing through points B, A', B' have their center on KB .

Considering both angles \langle C'CA'= B'BA'= 90° then lines BA', CA' produced meet lines AB′, AC′ at points B′, C′ such that line B′C′ passes through point K (*common to KC , KB*) Extrema for points A_1 , A_2 are points C , B and in case of points B , C coincide with point A *i.e. line KA is Extrema line for lines BA , CA .*

On the contrary , In any angle < BAC of triangle ABC exists a constant point KA such that all lines passing through this point intersect sides AB , AC at points C1 , B1 so that internal lines CB1 , BC1 concurrence on the circumcircle of triangle ABC and in case this point is A , then concurrence on line AKA . F12 . (4) , F13 .

a) When point A₁ is on point B (Superposition of points A₁, B) then line BA₁ is the tangent at point B, where then angle $\langle OBKA = 90^\circ$. When point A₁ is on point C (Superposition of points A₁, C) then line CA₁ is the tangent at point C, where then angle \langle OCK_A = 90°. F13.(1) Following the above for the three angles BAC, ABC, ACB F13.(2) then,

KA B, KAC are tangents at points B and C and angle \lt OBKA = OCKA = 90 $^{\circ}$. KB C, KBA are tangents at points C and A and angle $\lt OCKB = OAKB = 90^\circ$. Kc A, KcB are tangents at points A and B and angle $\lt OAKc = OBKc = 90^\circ$.

Since at points A, B, C of the circumcircle exists only one tangent then, The sum of angles $OCKA + OCKB = 180^\circ$ therefore points Ka, C, Kb are on line KAKB. The sum of angles $OAKB + OAKC = 180^{\circ}$ therefore points KB, A, Kc are on line KBKc. The sum of angles $OBKc + OBKA = 180^{\circ}$ therefore points Kc , B, KA are on line KAKc . i.e.

Circle (O , OA = OB = OC) is inscribed in triangle KAKBKC and circumscribed on triangle ABC .

b) Theorem : On any triangle **ABC** *and the circumcircle exists one inscribed triangle* **AEBECE** *and another one circumscribed Extrema* **triangle KAKBKC** *such that the Six points of intersection of the six pairs of <i>triple lines* are collinear \rightarrow (3+3) \cdot 3 = 18

F.14. *The Six, Triple Points, Line* \rightarrow *The Six, Triple Concurrency Points, Line Proof* :

 $F13. (1 - 2 - 3)$, $F14$

Let AE, BE, CE are the points of intersection of circumcircle and lines AKA, BKB, CKc respectively. Since circle (O ,OA) is incircle of triangle KAKBKc therefore lines AKA ,BKB ,CKc concurrence.

- 1. When points A1 , A coincide , then internal lines CB1 , BC1 coincide with sides CA , BA , so line KAA is constant . Since point AE is on *Extrema line AKA* then lines CEB ,BEC concurrent on line AKA . The same for tangent lines $KAKB$, $KAKC$ of angle $\lt KBKAKC$.
- 2. When points A1 , B coincide , then internal lines CA1 , AC1 coincide with sides CB , AB , so line KBB is constant . Since point BE is on *Extrema line BKA* then lines AEC ,CEA concurrent on line BKB . The same for tangent lines KBK_c , KBK_A of angle $\lt KcK_BKA$.
- 3. When points A1 , C coincide , then internal lines AB1 , BA1 coincide with sides AC , BC , so line KCC is constant . Since point CE is on *Extrema line CKC* then lines BEA ,AEB concurrent on line CKc. The same for tangent lines KcK_A , KcK_B of angle $\lt KAKcK_B$, *i.e.*

Since Perspective lines , on Extrema triangles **AEBECE , KAKBKC** *concurrent , and since also Vertices A , B , C of triangle ABC lie on sides of triangle* **KAKBKC ,** *therefore all corresponding lines of the three triangles when extended concurrent , and so the three triangles* **ABC ,****AEBECE , KAKBKC** *are Perspective between them .*

In triangles ABC, AEBECE all corresponding Perspective lines concurrent on AKA, BKB, CKC lines, and concurrency points P_A, P_B, P_C collinear. The pairs of Perspective lines [AAE, CBE, BCE], [BBE, CAE, ACE], [CCE, ABE, ABE] concurrent in points PA, PB, Pc respectively and lie on a line .

In triangles ABC , KAKBKC vertices A ,B ,C lie on triangle`s KAKBKC sides , therefore all corresponding Perspective lines concurrent in points DA ,DB ,DC respectively (sides of triangle KAKBKC are tangents on circumcircle). The pairs of Perspective lines $[KBA, CB, CEBe]$, [KAB, AC, AECE], [KBC, BA, BEAE], concurrent in points DA, DB, Dc respectively.

In triangles AEBECE , KAKBKC , and ABC corresponding Perspective lines concurrent in the same points DA , DB , DC because triangles` KAKBKC sides are tangent on circumcircle , so **Extrema** lines KBKC , KCKA , KAKB for both sets of sides lines [BC , BECE , KBKC] , [AC, AECE ,KAKC] [AB, AEBE, KAKB] concurrent in points of the same line . i.e.

This compact logic of the points **[A , B , C] , [AE , BE , CE] , [KA , KB , KC]** *when is applied on the three lines* **KAKB , KAKC , KBKC** *, THEN THE SIX pairs of the corresponding lines which extended are concurrent at points* P_A , P_B , P_C *for the triple pairs of lines* $[AA_E, BC_E, CB_E]$ **[BBE ,CAE ,ACE] , [CCE ,ABE ,BAE]** *and at points* **DA , DB , DC** *for the other Triple pairs of lines* **[CB , KBA , BECE] , [AC , KAB , CEAE] , [BA , KBC , AEBE]** *, lie on a straight line .*

Remarks :

- 1. Since Inscribed Extrema Triangle [AE,BE,CE] defines , axis AAE ,BBE ,CCE of Projective geometry and Circumscribed Extrema Triangle [KA, KB, Kc], axis KB Kc, KA Kc, KA KB of Perspective geometry therefore , Projective and Perspective geometry are Extrema in Euclidean geometry i.e. an Extension of the two fundamental branches of geometry .
- **c) .** Pythagoras`s Theoremand the Mould (*Machine*) of changeable Squares . 25 / 2 / 2012

It has been proved [5] , F15.(1) that any two equal and Perpendicular first dimentional Units CA ,CP and the hypotenuse AP, formulate the two equal circles with diameters CA, CP and the circumscribed circle (K, KA) of triangle CAP, (*Machine* CA \perp CP = CA), which forms on the three circles, { *for any point H on circle* $(P', P'C)$ }, the rectangle **HNMC** which is Square, $(\text{HNMC} = \text{HC}^2)$ and the Square $\text{HPP1C1} = \text{HP}^2$.

Show that : $PC^2 = HP^2 + HC^2$ or \rightarrow Rectangle CADP = HCMN + HPP1C1

Proof :

Complete Rectangles PNMP₂, PHCP₂ on the circle (P' , $P'P$) and HNN₁C₁, PNN₁P₁ on the circle $(K, KC = KD)$ and the squares HPP₁C₁, HNMC in the three circles . F15.(2) Rightangled triangles CMA , CP2P , DP1P, DN1A , are equal between them because these have equal their two sides , $(CA = CP = DP = DA$ *and* $CM = PP2 = DP1 = AN1$), therefore other sides $AM = CP_2 = PP_1 = DN_1$, and areas of triangles CAM, CPP₂, DPP₁, DAN₁ are also equal.

- 1. Since $HC = HN$ then Rectangles HCP_2P , HNN_1C_1 are equal, and both equal to 2. CHP.
- 2. In square $MP_2P_1N_1 \rightarrow$ Square CADP = Square $MP_2P_1N_1 4$. Triangles CHP.
- 3. In square $MP_2P_1N_1 \rightarrow Square HCMN + Square HPP_1C_1 = Square MP_2P_1N_1 -$ [2. Rectangles PHCP₂ = 4. Triangles CHP] = Square $MP_2P_1N_1 - 4$. Triangles CHP ... i.e.

Remarks :

- **a**. In machine $CA \perp CP$, $CA = CP$ of the two equal circles (E, EA), (P', P'C) and the circumcircle (K, KA) of the triangle ACP, are drawn two Changeable Squares HNMC, HPP1C1, which Sum is equal to the inscribed one CADP, or $PC^2 = HC^2 + HP^2$.
- **b**.**Extrema** exists at edge points **P , C** where then point **H** coincides with points P and C , and $PC^2 = PP^2 + PC^2 = PC^2$ and $PC^2 = PC^2 + CC^2 = PC^2$, and when coincides with K, then the Sum of the two Changeable Squares HNMC, HPP1C1 is $KC^2+KP^2 = 2.\Delta$ (KCA)+2. Δ (KCP) = $2.\mathcal{A}(KCA+KCP) = CADP = PC²$.
- **c**.The Position of the three Points only , defines Quantities (sides CP , HP , HC) , and Qualities (triangle PCH , Squares PDAC , HPP1C1 , HCMN and any classification of numbers is included).

d. It has been proved [5] that the two equal and perpendicular Units CA, CP, (in plane ACP) construct the Isosceles rightangled triangle ACP and the three circles on the sides as diameters . From any point **H** on the first circle are conscructed Squares HNMC, HPP₁C₁ with vertices on the three circles . This Plane Geometrical Formation is a , **mooving Machine** , and is called < **Plane Formation of Constructing Squares** >. *The same analogues exist in Space and is called,* \leq **Space Formation of Constructing Cubes**, and for Cubes $HO^3 = HP^3 + HC^3 + HI^3$.

The Plane System of triangle ACP with the three circles on the sides as diameters consists *the Steady Formulation ,* and squares HNMC , HPP1C1 , *is the moving Changeable Formulation of this twin Supplementary System ,* (*The Sum of Areas of the two Changeable Squares is constant and equal to that of Hypotenuse*) . i.e. *The Total Area is conserved on the Changable System* .

e. Pythagoras theorem defines the relation between the three sides of the rightangled triangle HCP which is an equality of Squares. The Sum of the Quantities, *Moving Squares HNMC*, *HPP_{1C1}*, is constant and equal to that of PCAD , which is the Conservation of Areas in motion .i.e.

 In Mechanics , the fundamental laws of Conservation of Energy is not Energy`s Property , but of Geometry`s (Since the Total Area , quantity , Conserves on the Changeable System). The Position of Points only , defines Properties and Laws of Universe (Quantities and Qualities). Conservation laws are the most fundamental principle of Mechanics . The Conserved Quantities (Energy , Momentum , Angular Momentum etc.) follow the Pythagoras theorem , applied on the moving machine $[CA \perp CP, CA = CP]$. The parallel transformations are,

Kinetic Energy (KE) + Potential Energy (PE) = Total Energy. Changeable Square HNMC + Changeable Square HPP1C1 = Total Area of Square CADP.

f. In applying the method on the three dimension Space (*Four points* = *Three equal and perpendicular First dimensional Units* OA , OB , OC *construct an Isosceles Orthogonal System with four Spheres , three on the Units and the fourth on the Resultant as diameters*) , exists a Changeable Space Formation such that the Sum of the Volumes of Spheres to be equal to that of the Resultant , meaning that , conservation of Volumes exists on the three Perpendicular Units. Energy (*Motion*) follows this Euclidean Mould , because this Proposition (*Principle*) belongs to geometry`s , *and not to Energy`s which is only motion* .

Open Problem ? Which logic exists on this moving machine such that the area of the changeable Square *or changeable Cube* , to be equal to that of the circle , *or Cube* ?

References :

by Marcos Georgallides .